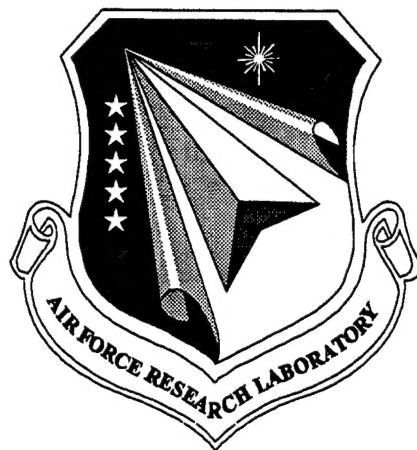


AFRL-VA-WP-TR-1999-3050



**DEVELOPMENT OF THE
AERODYNAMIC/AEROSERVOELASTIC
MODULES IN ASTROS**

**VOLUME 2: ZAERO PROGRAMMER'S
MANUAL (F33615-96-C-3217)**

**P.C. CHEN
D. SARHADDI
D.D. LIU**

**ZONA Technology, Inc.
7430 E. Stetson Drive, Ste 205
Scottsdale, AZ 85251**

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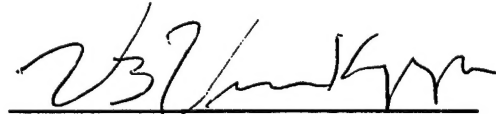
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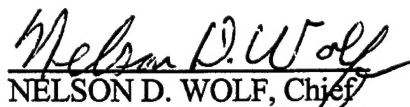
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Aerospace Engineer
Design and Analysis Branch



VIPPERLA B. VENKAYYA
Leader, Multidisciplinary Design
Design & Analysis Branch



NELSON D. WOLF, Chief
Design and Analysis Branch
Structures Division

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7. PERFORMING ORGANIZATION NAME(S) AND ADDRESS(ES) ZONA Technology, Inc. 7434 E. Stetson Drive, Suite 205 Scottsdale, AZ 85251 Tel 602-945-9988 / Fax 602-945-6588		8. PERFORMING ORGANIZATION REPORT NUMBER ZONA 99-11B		
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FOREWORD

This interim report is submitted in fulfillment of CDRL CLIN 0001, Data Item A009, Title: Interface Design Document of a Small Business Technology Transfer (STTR) contract No. Contract No. F33615-96-C-3217 entitled, "Development of the Aerodynamic/Aeroservoelastic Modules in ASTROS," covering the performance period from 24 September 1996 to 24 September 1998. This document provides the programmer's documentation for the ZAERO module in ASTROS*.

This work was performed by ZONA Technology, Inc. and its subcontractors, the University of Oklahoma (Research Institute)/Technion (I.I.T) and Universal Analytics Inc. This work is the second phase of a continuing two-phase STTR contract supported by AFRL/Wright-Patterson. The first phase STTR contract No. F33615-95-C-3219 entitled, "Enhancement of the Aeroservoelastic Capability in ASTROS," was completed in May 1996 and published as WL-TR-96-3119. Started in September 1996, the present second phase STTR contract was conducted by the same team members as in phase I. These contributors are: P.C. Chen (P.I.), D. Sarhaddi and D.D. Liu of ZONA Technology Inc.; Fred Striz of the University of Oklahoma; Moti Karpel of Technion/I.I.T.; and Tony Shimko and Steve Chen of Universal Analytics.

This STTR contract is sponsored by AFRL/Wright-Patterson. Capt. Gerald Andersen is the contract monitor and Dr. V.B. Venkayya is the initiator of the whole STTR effort. During the course of the present phase on the development of ASTROS*, the technical advice and assistance received from Mr. Doug Neill of The MacNeal Schwendler Corporation, Dr. V.B. Venkayya and others from AFRL are gratefully acknowledged.

1.0 INTRODUCTION

There are four major documents that describe the ZONA Aerodynamics Module (ZAERO) Module which has been seamlessly integrated into the Automated STRuctural Optimization System (ASTROS). These are: the ZAERO User's, Programmer's, Application and Theoretical Manuals for ASTROS*. While ZAERO represents the ZONA Aerodynamics Module, ASTROS* is defined as the seamless integration of ZAERO into ASTROS, i.e. $\text{ASTROS}^* = \text{ZAERO} + \text{ASTROS}$. This Programmer's Manual gives the detailed description of the ZAERO software and its interface with the ASTROS system. Newly created database entities in support of the ZAERO module within ASTROS* are described. Newly developed engineering application modules comprising the ZAERO module are presented in detail.

This manual assumes that the user is familiar with the ASTROS system (Version 11.0), its terminology and programming environment. A complete and comprehensive description of the ASTROS environment can be found in the ASTROS User's and Programmer's Manuals (Refs 1,2). In particular, this manual is geared toward system administrators and/or programmers within the ASTROS* environment.

Section 2 presents an overview of the ZAERO software, its aerodynamic capability over that of the previous modules in ASTROS, and the program architecture of ZAERO in relation to ASTROS.

Section 3 presents the computer files delivered under this contract which contain all of the subroutines of the ZAERO module, the modified System Generation (SYSGEN) input for ASTROS*, and the ASTROS* system generation process.

Section 4 presents the ZAERO engineering application modules (altogether nine modules) that make up ZAERO within the ASTROS* environment. Together with the ASTROS* object library, these ZAERO engineering applications modules constitute the entire ASTROS* executable (see ASTROS* system generation flow chart).

Section 5 presents the ZAERO specific relational and matrix database entity descriptions established upon building of the ASTROS* system that are used for communication of data among the ZAERO engineering application modules.

2.0 ZAERO MODULE AND ASTROS*

ASTROS (Automated STRuctural Optimization System) is a finite element based procedure tailored for the preliminary design of aerospace structures. As such, it includes flexibility and generality in multiple discipline integration. For aircraft, missile or spacecraft design, the unique attributes of ASTROS lie in its savings of design effort and time, improvement in flight performance and reduction in structural weight. In principle, ASTROS was aimed at the effective multidisciplinary interactions between aerodynamics, aeroelastics, structures and other modules. Although today a well-acclaimed, proven tool for Multidisciplinary Optimization (MDO) and analysis, ASTROS still requires further improvement in its capabilities in steady/unsteady aerodynamics, aeroelasticity and aeroservoelasticity (e.g. Ref 3).

The ZONA aerodynamic codes contained in the ZAERO module are the software products of ZONA Technology developed throughout the years. These include four major steady/unsteady aerodynamics codes, namely ZONA6, ZONA7, ZTAIC, and ZONA7U, that jointly cover the complete domain of all Mach number ranges. The ZONA aerodynamic system (the ZAERO System) which contains the ZAERO module and two other modules were developed under the support of AFRL/Wright-Patterson AFB for their seamless integration into the ASTROS system to improve and enhance the capability of ASTROS in aerodynamics, aeroelasticity and aeroservoelasticity (ASE). In particular, the ZAERO module improves the aerodynamics capability over the earlier aerodynamics modules in ASTROS in the following aspects (also see Figs 1 and 2):

1. Wing-Body geometry input for realistic aircraft configurations including external stores.
2. Flight regimes that include subsonic, supersonic, transonic and hypersonic Mach numbers.
3. High-order paneling scheme to assure accurate and robust solutions (without stringent paneling requirements).
4. Provides Aerodynamic Influence Coefficient (AIC) matrices for all flow regimes including the generation of transonic AIC.
5. Steady/unsteady aerodynamic options for static and dynamic aeroelastic applications.
6. Unified aerodynamic geometry bulk data input.

The development and seamless integration of the the ZAERO System into ASTROS has created a unique Multidisciplinary Design/Analysis and Optimization (MDO/MAO) tool that is currently unsurpassed in its steady/unsteady aerodynamic and aeroelastic capability. The ZAERO System consists of essentially three modules which include the ZAERO module, the AGM (aerodynamic geometry module) and the 3D-Spline module (see Fig 3).

As can be seen in Fig 1, current capabilities of ASTROS and NASTRAN are limited to subsonic and supersonic Mach numbers and applicable to lifting surfaces only. By contrast, ZAERO is valid throughout the full range of subsonic to hypersonic Mach numbers and is applicable to complex aircraft configurations with external stores.

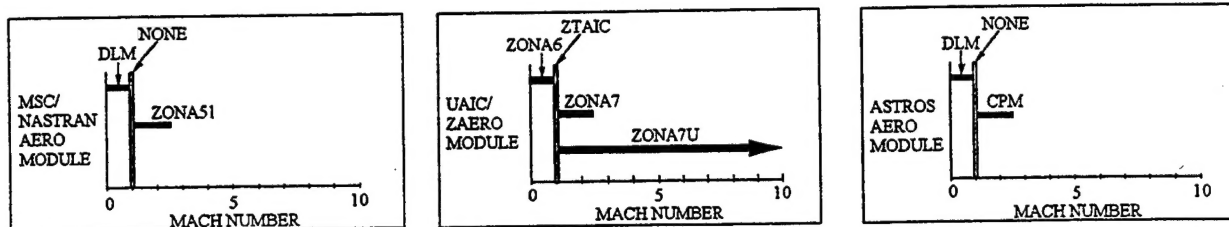


Figure 1. ZAERO and Other Aerodynamic Modules.

Fig 2 shows the capability of each code in the ZAERO Module (marked with †) along with other ZONA Codes.

Capability		ZONA Unsteady/Steady Aerodynamic Codes – ZAERO						
		ZONA51	ZONA51U	ZONA7†	ZONA7U†	ZONA6†	ZTAIC†	ZTAIC6
Geometry	• Lifting Surface (L.S.)	•	•	•	•	•	•	•
	• Thickness Effect		•		•		•	•
	• L.S. + Body = Whole Aircraft			•	•	•		•
Mach Number	• Subsonic					•	•	•
	• Transonic						•	•
	• Supersonic	•	•	•	•			
	• Hypersonic		•		•			

Figure 2. Capability of the ZAERO Module.

The seamlessly integrated ZAERO System in ASTROS is called ASTROS*. Fig 3 illustrates the role of the ZAERO System within ASTROS* and the overall ASTROS* program architecture. The ZAERO System consists of three primary modules with the following functionalities:

- *Unified Aerodynamic Geometry Module (AGM)*
The Unified Aerodynamic Geometry Module processes the ZAERO model aerodynamic geometry input. Two newly created bulk data entries are used to define the aerodynamic geometry, namely **CAERO7** for wing-like components such as wings, tails, pylons, launchers and store fins, and **BODY7** for body-like components such as fuselage, stores and missile bodies.
- *3-D Spline Module*
The 3-D Spline Module provides for the interconnection between the aerodynamic and structural models through the generation of spline matrices. Three spline methods are supported by this module. These are the infinite plate spline (IPS) method (**SPLINE 1**), the beam spline method (**SPLINE 2**) and the thin plate spline (TPS) method (**SPLINE 3**). The TPS

is an addition to the spline capability provided by ASTROS and unlike the IPS method does not require that a spline plane be defined.

- *The ZAERO Module*

The ZAERO Module is made up of the four major aerodynamic codes (ZONA6, ZONA7, ZTAIC, ZONA7U) and generates the Unified Aerodynamic Influence Coefficient (UAIC) matrices, gust force vectors, control surface aerodynamic vectors and steady aerodynamic force vectors of trim parameters.

Database entities generated by AGM, 3-D Spline and ZAERO modules are computed in the ASTROS* preface phase and are not recomputed in the analysis/optimization loop.

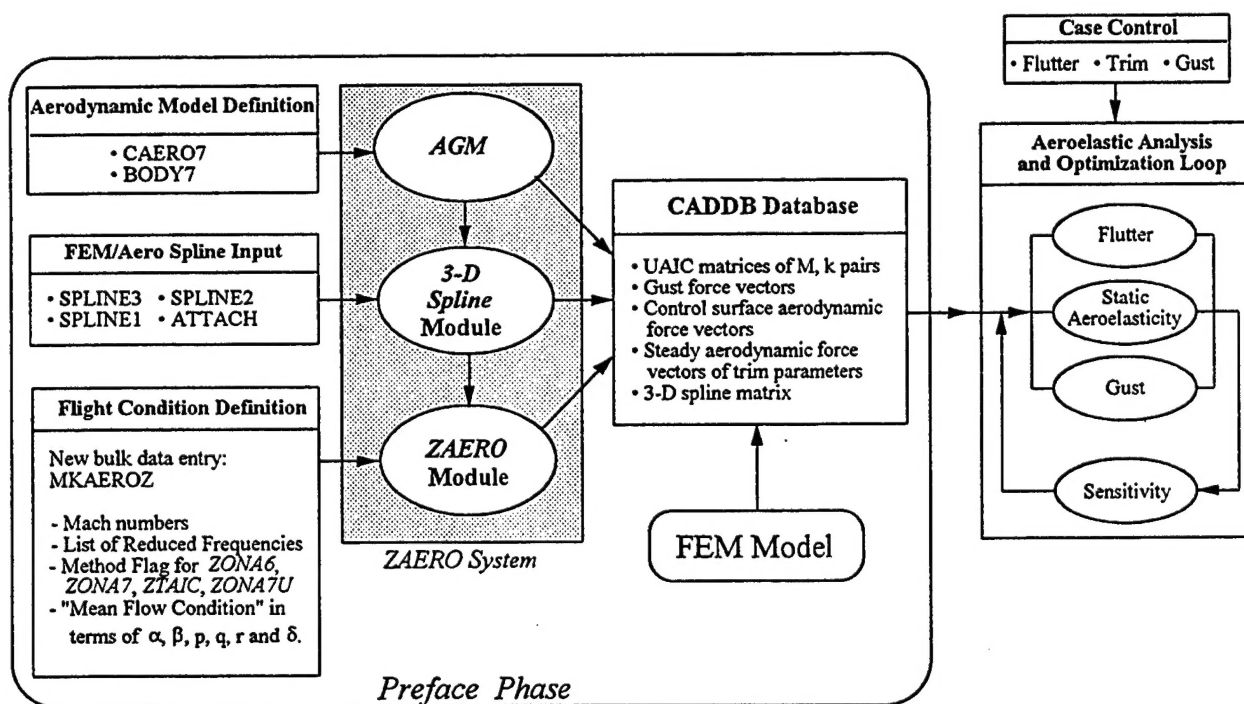


Figure 3. ASTROS/ZAERO (ASTROS*) Program Architecture.

3.0 ASTROS* SYSTEM GENERATION

3.1 Generation of the ASTROS* System

The ASTROS System Generation Process (SYSGEN) has been modified to include the compilation of the ZAERO module source code and the linking of the ZAERO module object code into the ASTROS system. For ease of use, the system generation process has been kept the same as that of ASTROS (Version 11.0). The change made to this process to incorporate the ZAERO module are:

1. Updates to the SYSGEN input files (described in Sections 3.2.1 through 3.2.5)
2. Modified script file **Makexqdriv** for compiling the ZAERO module source code (described in Section 3.1.1)
3. Modified script file **Makeastros** for linking of the ZAERO module object code into the ASTROS* system (described in Section 3.1.2)

The entire SYSGEN process is depicted in Figure 4 and is briefly outlined as follows.

The modified SYSGEN input files (1) are processed by SYSGEN (2). SYSGEN generates the ASTROS* System Database (SYSDB) (3), SYSGEN output file (4) and the fortran source code XQDRIV (5). Both the ZAERO engineering applications modules (6) and XQDRIV source code (5) are compiled by the **Makexqdriv** script file (7). The object library of ASTROS (Version 11.0) (8) and object files generated by **Makexqdriv** (7) are linked via the **Makeastros** script file called by **astlink** (9) to generate the ASTROS* Executable Image (10). The ASTROS* System Database (3) and ASTROS* Executable (10) make up the ASTROS* system.

3.1.1 Compiling the ZAERO Module

The Makefile (**Makexqdriv**) used to compile the **XQDRIV** file generated by SYSGEN and located in the ASTROS (Version 11.0) sysgen directory has been updated to compile the ZAERO source files listed in Table 1 (see Figure 5). Should any modifications to the source code be required, the corresponding files where changes are made must be re-compiled in **Makexqdriv**. If no changes are made and the user wishes to re-build the ASTROS* system, it is not necessary to re-compile these files. Therefore all corresponding lines in **Makexqdriv** can be commented out to speed up the ASTROS* regeneration process.

3.1.2 Linking the ZAERO Module

The Makefile (**Makeastros**) called by the **astlink** script file to relink ASTROS* and located in the ASTROS (Version 11.0) sysgen directory has been updated to link the ZAERO object files generated upon the compilation in **Makexqdriv** (see Figure 6).


```

update: compflgs

# clean up
    @ rm xqdriv.o
    @echo "astros.a now up to date"
xqdriv.o: xqdriv.f
    @echo ""
    @echo "compiling xqdriv.f with the " \"$(FC)\" " compiler and flags " \"$(FFLAGS)\"
    @echo ""
    $(FC) $(FFLAGS) -c xqdriv.f
#
# ZAERO Source Files
# -----
    @echo ""
    $(FC) $(FFLAGS) -c aerogm.f
    @echo ""
    $(FC) $(FFLAGS) -c fltqhz.f
    @echo ""
    $(FC) $(FFLAGS) -c splinz.f
    @echo ""
    $(FC) $(FFLAGS) -c utility.f
    @echo ""
    $(FC) $(FFLAGS) -c zaerom.f
# -----
#
    @echo ""
    $(FC) $(FFLAGS) -c XXBD.f
# now update the astros library with the new xqdriv
    @echo ""
    @echo "updating astros.a ... "
    /usr/ccs/bin/ar $(ARIFLGS) astros.a xqdriv.o
compflgs:
    @/usr/ccs/bin/make -f Makeflags $(TARGET) "MFILE = Makexqdriv" "RETURN = xqdriv.o"

```

THIS SECTION CAN BE COMMENTED OUT WITH (#)
IF NO CHANGES ARE MADE TO THE ZAERO
SOURCE CODE

Figure 5. Modified Makexqdriv File for ASTROS*.

```

# procedure to relink astros
#
# get the fortran compiler flags from Makeflags
#
load: compflgs
    @echo " "
    @echo "Linking complete new version of astros now exists"
compflgs:
    @/usr/ccs/bin/make -s -f Makeflags $(TARGET) "RETURN=lastros" "MFILE=Makeastros"
lastros:
    @echo ""
    @echo "Generating a new version of astros.bin"
    @echo ""
    @/usr/ccs/bin/ar $(AROFLGS) astros.a astros.o
    @echo "Relinking astros .... ( This will take a few minutes )"
#
    @$(LINK) $(ENTRY) $(LINIT) -o astros.bin astros.o aerogm.o XXBD.o astros.a $(LIBS)
    @$(LINK) $(ENTRY) $(LINIT) -o astros.bin astros.o XXBD.o aerogm.o fltqhz.o splinz.o utility.o
    zaerom.o zaerolib.o astros.a $(LIBS)
    @rm astros.o

```

Figure 6. Modified Makeastros File for ASTROS*.

3.2 ZAERO Sysgen Input

To facilitate the ASTROS* system generation described in Section 3.1, the five SYSGEN input data files, namely **MODDEF.DAT**, **MAPOLSEQ.DAT**, **TEMPLATE.DAT**, **RELATION.DAT** and **SERRMSG.DAT**, have been modified to include all components necessary for integration of ZAERO in ASTROS*. Modifications to each of these files are described in the following subsections. The physical changes made to each of these files are presented in Appendices A through E, respectively.

3.2.1 Functional Module Definition (MODDEF.DAT)

The ASTROS* run-time library of MAPOL addressable modules file (**MODDEF.DAT**) has been updated to account for all newly developed engineering application modules presented in Section 5. These module definitions provide the additional links between the ASTROS* executive system and the ZAERO engineering application modules. The ZAERO functional module definitions are presented in Appendix A. For a detailed description of this file, please see Ref 2.

3.2.2 MAPOL Sequence (MAPOLSEQ.DAT)

For seamless integration of ZAERO into ASTROS, the ASTROS MAPOL sequence (file **MAPOLSEQ.DAT**) has been modified. The complete ASTROS* MAPOL sequence listing is presented in Appendix B. All changes to the original ASTROS (Version 11.0) MAPOL sequence listing are highlighted in boldface text and are demarcated by arrows on the right. For a detailed description of this file, please see Ref 2.

3.2.3 Bulk Data Template Definition (TEMPLATE.DAT)

In the development of the ZAERO module, twenty three new bulk data entries were created. Bulk data template definitions for these new bulk data entries were added to those of ASTROS (Version 11.0) and are presented in Appendix C. For a detailed description of this file, please see Ref 2.

3.2.4 Relational Schema Definition (RELATION.DAT)

Schema definitions of all relational database entities used by the ZAERO module have been defined in file **RELATION.DAT**. These relational entity schema definitions are presented in Appendix D. For a detailed description of this file, please see Ref 2.

3.2.5 Error Message Text Definition (SERRMSG.DAT)

Three new error message definition modules have been developed corresponding to the following engineering application modules: **AEROGM**, **SPLINZ** and **ZAEROM**. These ZAERO error message module definitions are presented in Appendix E. For a detailed description of this file, please see Ref 2.

3.3 The ZAERO Software

Under the current contract, six computer files containing all ZAERO engineering application and utility modules are delivered. These six files along with corresponding file descriptions are listed in Table 1. These files contain all of the ZAERO engineering application modules.

Table 1. Computer Files Comprising ZAERO.

File Name	Description	File Type
aerogm.f	Code for processing of the wing/body aerodynamic geometry used by all ZAERO aerodynamic methods	source
fltqhz.f	Code for processing of matrices required for flutter analysis, including a newly developed K-method	source
splinz.f	Code for processing of spline matrices	source
utility.f	Additional math matrix in-core solvers	source
zaerom.f	Steady and unsteady aerodynamics processing for all of ZAERO's aerodynamic methods	source
zaerolib.o	ZONA's aerodynamic kernels	object

Note that all source code of ZAERO developed and integrated into ASTROS under this contract is being furnished to AFRL. The zaerolib.o code was developed prior to the current STTR Phases I & II and is ZONA Technology proprietary. This file is delivered in object code format only for specified computer platforms. To acquire updated object code for different computer platforms, please contact ZONA Technology at (602) 945-9988, POC: Darius Sarhaddi.

4.0 ZAERO ENGINEERING APPLICATION MODULES

Nine new engineering application modules have been developed as the ZAERO interface to ASTROS. The modules along with a brief functional descriptions are presented in Table 2.

Table 2. ZAERO Engineering Application Modules.

Module Name	Function
AEROGM	Aerodynamic Geometry Module
CONMOD	Control Surface Modes Generation
FLUTQHHZ	Process matrix [AJK] with normal modes for flutter
FLUTSENZ	To compute the sensitivities of active flutter constraints in the current boundary condition
FLUTTRAZ	Perform flutter analysis in the current boundary condition and to evaluate any flutter constraints if it is an optimization boundary condition with applied flutter constraints
QHHLGENZ	Compute the unsteady aerodynamic matrices in the modal dynamic degrees of freedom for gust analysis
SPLINZ	Generate the spline matrix that relates displacements and forces between the structural model and aerodynamic models
SZAERO	Generate steady aerodynamic AIC matrices and aerodynamic forces of unit configurations
UZAERO	Unsteady aeroelastic analysis preface

For ease of understanding, these new engineering modules are documented in the same format as those presented in the ASTROS Programmer's Manual (Ref 2). The modules presented provide the programmer a general description of the algorithm and clearly defines the module's arguments. In addition, the purpose, MAPOL calling sequence, FORTRAN subroutine name and method (i.e. function) of the module is presented. In cases of similar methods employed by modules to those of ASTROS (Version 11.0), the user is referred to the ASTROS Programmer's Manual (Ref 2).

Engineering Application Module: **AEROGM**

Entry Point: **AEROGM**

Purpose:

ZAERO geometry preface module.

MAPOL Calling Sequence:

```
CALL AEROGM ( AECOMPZ, GEOMZA, AGRIDZ );
```

AECOMPZ	A relation describing aerodynamic components (Output)
GEOMZA	A relation describing the aerodynamic boxes (Output)
AGRIDZ	A relation describing the corner points of aerodynamic boxes (Output)

Application Calling Sequence:

None

Method:

The **AEROGM** module processes all **BODY7** and **CAERO7** bulk data entries and computes the geometric data stored in the relational entites **AECOMPZ**, **GEOMZA**, and **AGRIDZ**. These relational entites are to be used by the **CONMOD**, **SPLINZ**, **UZAERO**, and **SZAERO** modules.

Design Requirements:

The **AEROGM** module is excuted in the preface phase. It is the aerodynamic geomety module for the **ZAERO** module.

Error Conditions:

None

Engineering Application Module: **CONMOD**

Entry Point: **CONMOD**

Purpose:

Control surface modes generation.

MAPOL Calling Sequence:

```
CALL CONMOD ( AECOMPZ, GEOMZA, [SCNTLG], [SCNTLK], [ACNTLG], [ACNTLK],  
              [LMOEG], [LMOEK] );
```

AECOMPZ	A relation created by the AEROGM module describing aerodynamic components (Character, Input)
GEOMZA	A relation created by the AEROGM module describing the aerodynamic boxes (Character, Input)
[SCNTLG]	Matrix whose rows contain the symmetric control surface modes defined at the G-set D.O.F. and columns are associated with the AESURFZ bulk data entries. [SCNTLG] is used to compute the inertia loads by unit deflection angle of control surfaces. (Output)
[SCNTLK]	Matrix whose rows contain the symmetric control surface modes defined at the K-set D.O.F. and columns are associated with the AESURFZ bulk data entries. [SCNTLK] is used to compute the unsteady aerodynamic forces [AJC] and steady aerodynamic forces [AIRFRC] by unit deflection angle of the control surfaces. (Output)
[ACNTLG]	Same as [SCNTLG] but for antisymmetric control surface modes (Output)
[ACNTLK]	Same as [SCNTLK] but for antisymmetric control surface modes (Output)
[LMOEG]	Matrix whose rows contain the load modes at the G-set D.O.F. and columns are associated with the LOADMOD bulk data entries (Output)
[LMOEK]	Matrix whose rows contain the load modes at the K-set D.O.F. and columns are associated with the LOADMOD bulk data entries (Output)

Application Calling Sequence:

None

Method:

First, the **CONMOD** module processes all **AESURFZ** bulk data entries (if there are any) and generates the control surface modes due to unit deflection angle of the control surfaces about the hinge lines in both G-set and K-set D.O.F. If **TYPE** = 'SYM' or 'ASYM', the control surface modes are stored in **[SCNTLG]** and **[SCNTLK]**. If **TYPE** = 'ANTISYM', the control surface modes are stored in **[ACNTLG]** and **[ACNTLK]**.

Next, the **CONMOD** module processes all **LOADMOD** bulk data entries (if there are any) and generates the load modes of each **LOADMOD**. The load modes are defined in the G-set and K-set D.O.F. and stored in each row of the matrix **[LMOEG]** and **[LMOEK]**, respectively.

Design Requirements:

None

Error Conditions:

None

Engineering Application Module: **FLUTQHHZ**

Entry Point: **FLTQHZ**

Purpose:

Processes matrix [AJK] with normal modes for flutter.

MAPOL Calling Sequence:

```
CALL FLUTQHHZ ( NITER, BCID, SUB, ESIZE(BC), PSIZE(BC), [AJK], [SKJ],  
                [UGTKA], [PHIA], USET(BC), [TMN(BC)], [GSUBO(BC)], NGDR,  
                AECOMPZ, GEOMZA, [PHIKH], [QHHLFL(BC, SUB)], OAGRDDSP );
```

NITER	Design iteration number (Integer, Input)
BCID	Boundary condition number (Integer, Input)
SUB	Flutter subcase number (Integer, Input)
ESIZE (BC)	Number of extra points for the current boundary condition (Integer, Input)
PSIZE (BC)	Number of physical degrees of freedom in the current boundary conditions (GSIZE+ESIZE) (Integer, Input)
[AJK]	Unsteady AIC matrices generated by the UZAERO module (Input)
[SKJ]	Integration matrix generated by the UZAERO module (Input)
[UGTKA]	The matrix of splining coefficients relating the aerodynamic pressures and forces at the structural grids and relating the structural displacements to the streamwise slopes of the aerodynamic boxes. [UGTKA] is reduced to the a-set DOF from [UGTKG]. (Input)
[PHIA]	Matrix of normal modes eigenvectors in the a-set (Input)
USET (BC)	Current boundary condition's unstructured entity of set definition masks (expanded to include extra points and any GDR scalar points) (Input)
[TMN (BC)]	Multipoint constraint transformation matrix for the current boundary condition (Input)
[GSUBO (BC)]	Static condensation or GDR reduction matrix for the current boundary condition (Input)
NGDR	Denotes dynamic reduction in the boundary condition = 0 No GDR = -1 GDR is used (Input, Integer)
AECOMPZ	A relation describing aerodynamic components created by the AEROGM module (Character, Input)

GEOMZA	A relation describing the aerodynamic boxes created by the AEROGM module (Character, Input)
[PHIKH]	A modal transformation matrix that relates the box-on-box aerodynamic motions to unit displacements of the generalized structural coordinates (modes) (Output)
[QHHLFL(BC, SUB)]	A matrix containing the list of $h \times h$ unsteady aerodynamics matrices for the current flutter subcase related to the generalized (modal) coordinates and including control effectiveness (CONEFFS), extra points and CONTROL matrix inputs, where BC represents the MAPOL boundary condition loop index number (Output)
OAGRDDSP	A relation containing the structural eigenvectors (generalized DOF) mapped to the aerodynamic boxes for those AIRDISP requests in the Solution Control. These terms are the columns of PHIKH put in relational form to satisfy the output requests. (Output)

Application Calling Sequence:

None

Method:

FLUTQHHZ is very similar to the **FLUTQHHL** module (see **FLUTQHHL** Engineering Application Module of ASTROS Programmer's Manual for description of Method). There are only two differences between these two modules.

1. **FLUTQHHZ** reads in **[AJK]** and **[SJK]** matrices and computes the **QKK** matrices as

$$[QKK] = [SJK]^T [AJK]^T$$

then computes the generalized aerodynamic forces as

$$[QHHLFL] = [PHIKH]^T [QKK] [PHIKH]$$

therefore, the **[QKK]** matrix is a intermediate matrix created in **FLUTQHHZ**. However, the actual procedure to compute **[QHHLFL]** in the **FLUTQHHZ** is described in ENTITY DESCRIPTIONS of **AJK**

2. **FLUTQHHZ** uses the relational entity **REUNMK** to retrieve the AIC matrices of the Mach number and associated reduced frequencies as defined in the **IDMK** of the **FLUTTER** bulk data entry.

Engineering Application Module: **FLUTSENZ**

Entry Point: **FLTSTZ**

Purpose:

To compute the sensitivities of active flutter constraints in the current boundary condition.

MAPOL Calling Sequence:

```
CALL FLUTSENZ ( NITER, BC, SUB, LOOP, GSIZEB, NDV, GLBDES, CONST, GMKCT,
                DKVI, GMMCT, DMVI, CLAMBDA, LAMBDA, [QHHLFL(BC, SUB)],
                [BHHFL(BC, SUB)], [KHHFL(BC, SUB)], [PHIG(BC)], [AMAT],
                AEROZ );
```

NITER	Design iteration number (Integer, Input)
BC	Boundary condition identification number (Integer, Input)
SUB	Flutter subcase number (Integer, Input)
LOOP	Logical flag indicating whether more flutter subcases exist in the current boundary condition (Logical, Input)
GSIZEB	The size of the structural set (Integer, Input)
NDV	The number of global design variables (Integer, Input)
GLBDES	Relation of global design variables (Character, Input)
CONST	Relation of constraint values (Character, Input)
GMKTC	Relation containing the connectivity data for the DKVI sensitivity matrix (Character, Input)
DKVI	Unstructured entity containing the stiffness design sensitivity matrix in a highly compressed format (Character, Input)
GMMCT	Relation containing connectivity data for DMVI sensitivity matrix (Character, Input)
DMVI	Unstructured entity containing the mass design sensitivity matrix in a highly compressed format (Character, Input)
CLAMBDA	Relation containing results of flutter analysis (Character, Input)
LAMBDA	Relation containing the output from the real eigenanalysis (Character, Input)
[QHHLFL(BC, SUB)]	A matrix containing the list of $h \times h$ unsteady aerodynamics matrices for the current flutter subcase related to the generalized (modal) coordinates and including control effectiveness (CONEFFS), extra points and CONTROL matrix inputs, where BC represents the MAPOL boundary condition loop index number (Input)

[MHHFL (BC, SUB)]	Modal mass matrix (Input)
[BHHFL (BC, SUB)]	Modal flutter damping matrix (Input)
[KHHFL (BC, SUB)]	Modal flutter stiffness matrix (Input)
[PHIG (BC)]	Matrix of real eigenvectors in the structural set (Input)
[AMAT]	Matrix of constraint sensitivities (Output)
AEROZ	Relation containing the definition of the aerodynamic coordinate system (Input)

Application Calling Sequence:

None

Method:

FLUTSENZ is very similar to the **FLUTSENS** module (see **FLUTSENZ** Engineering Application Module for description of Method). There is only one difference between these two modules. **FLUTSENZ** uses the relational entity **REUNMK** to retrieve the AIC matrices of the Mach number and associated reduced frequencies as defined in the **IDMK** of the **FLUTTER** bulk data entry.

Design Requirements:

The module assumes that at least one flutter subcase exists in the current boundary condition.

Error Conditions:

None.

Engineering Application Module: **FLUTTRAZ**

Entry Point: **FLTTAZ**

Purpose:

To perform flutter analyses in the current boundary condition and to evaluate any flutter constraints if the current boundary condition is an optimization boundary condition with applied flutter constraints.

MAPOL Calling Sequence:

```
CALL FLUTTRAZ ( NITER, BCID, SUB, [QHHFL(BC, SUB)], LAMBDA, HSIZE(BC),  
                ESIZE(BC), GMKCT, [MHHFL(BC, SUB)], [BHHFL(BC, SUB)],  
                KHHFL(BC, SUB)], CLAMBDA, AEROZ );
```

NITER	Design iteration number (Integer, Input)
BCID	User defined boundary condition identification number (Integer, Input)
SUB	Flutter subcase number (ranging from 1 to the total number of FLUTTER subcases) of the subcase to be processed in this pass (Integer, Input)
[QHHFL(BC, SUB)]	Matrix list of modal unsteady aerodynamic coefficients (Input)
LAMBDA	Relational entity containing the output from the real eigenanalysis (Character, Input)
HSIZE(BC)	Number of modal dynamic degrees of freedom in the current boundary condition (Input)
ESIZE(BC)	The number of extra point degrees of freedom in the current boundary condition (Integer, Input)
[MHHFL(BC, SUB)]	Modal mass matrix (Input)
[BHHFL(BC, SUB)]	Modal flutter damping matrix (Input)
[KHHFL(BC, SUB)]	Modal flutter stiffness matrix (Input)
CLAMBDA	Relation containing results of flutter analyses (Character, Input)
AEROZ	Relational entity of the configuration parameters defined by the AEROZ bulk data entry (Character, Input)

Application Calling Sequence:

None

Method:

FLUTTRAZ is very similar to the **FLUTTRAN** module (see **FLUTTRAN** Engineering Application Module of the **ASTROS** Programmer's Manual for a description of the Method). The difference is that rather than processing the **UNMK** unstructured entity, **FLUTTRAZ** reads the relational entity **REUNMK** for retrieving the Mach number and reduced frequency pairs.

Design Requirements:

The module assumes that at least one flutter subcase exists in the current boundary condition.

Error Conditions:

Referenced data on FLUTTER entries that do not exist on the database are flagged and the execution is terminated.

Engineering Application Module: **QHHLGENZ**

Entry Point: **QHJGEN**

Purpose:

To compute the unsteady aerodynamic matrices in the modal dynamic degrees of freedom for gust analysis.

MAPOL Calling Sequence:

```
CALL QHHLGENZ ( BC, ESIZE(BC), [AJK], [SKJ], [QGK], [UGTKA], [PHIA],  
                [PHIKH], [QHHL], [QHJL], AEROZ );
```

BC	Boundary condition identification number (Integer, Input)
ESIZE (BC)	The number of extra point degrees of freedom in the boundary condition (Integer, Input)
[AJK]	Unsteady AIC matrices generated by the UZAERO module (Input)
[SKJ]	Integration matrix generated by the UZAERO module (Input)
[QGK]	A matrix containing the intermediated gust vectors generated by the UZAERO module (Input)
[UGTKA]	The matrix of splining coefficients relating the aerodynamic pressures and forces at the structural grids and relating the structural displacements to the streamwise slopes of the aerodynamic boxes reduced to the a-set DOF. Generated by the SPLINZ module. (Input)
[PHIA]	Matrix of normal modes eigenvectors in the a-set (Input)
[PHIKH]	A modal tranformation matrix that relates the box-on-box aerodynamic motions to unit displacements of the generalized structural coordinates (modes) (Output)
[QHHL]	A matrix containing the list of h x h unsteady aerodynamics matrices of each reduced frequency for the current gust subcase related to the generalized (modal) coordinates (Output)
[QHJL]	A matrix containing the list of h x 1 unsteady harmonic gust vector of each reduced frequency (Output)
AEROZ	A relation containing the definition of the aerodynamic coordinate system (Input)

Application Calling Sequence:

None

Method:

QHHLGENZ is very similar to the **QHHLGEN** module (see **QHHLGEN** Engineering Application Module of the **ASTROS** Programmer's Manual for a description of the Method). There are only two differences between these two modules.

1. **QHHLGENZ** reads in **[AJK]** and **[SJK]** matrices and computes the **QKK** matrices as

$$[QKK] = [SJK]^T [AJK]^T$$

then computes the generalized aerodynamic forces as

$$[QHHL] = [PHIKH]^T [QKK] [PHIKH]$$

therefore, the **[QKK]** matrix is a intermediate matrix created in **QHHLGENZ**.

2. The gust vector is computed as:

$$[QHJL] = [PHIKH]^T [QKK] \exp(i*k/(REFC/2.)*x_o)$$

where k is the reduced frequency.
 $REFC$ is the reference chord.

and x_o is the location of thereference plane defined in the **GUST** bulk entry.

3. **QHHLGENZ** uses the relational entity **REUNMK** to retrieve the AIC matrices of the Mach number and associated reduced frequencies as defined in the **IDMK** of the **GUST** bulk data entry.

Engineering Application Module: **SPLINZ**

Entry Point: **SPLINZ**

Purpose:

Generates the spline matrix that relates displacements and forces between the structural model and the ZAERO aerodynamic model.

MAPOL Calling Sequence:

```
CALL SPLINZ ( GSIZEB, GEOMZA, AECOMPZ, AEROZ, [UGTKG] );
```

GSIZEB	The number of degrees of freedom in the set of all structural GRID and SCALAR points (Integer, Input)
GEOMZA	A relation describing the aerodynamic boxes for the ZAERO model. The location of the box centroid, normal and pitch moment axis are given. It is used in splining the aerodynamics to the structure and to map responses back to the aerodynamic boxes. (Character, Input)
AECOMPZ	A relation describing aerodynamic components for the ZAERO model. It is used in splining the aerodynamics to the structural model. (Character, Input)
AEROZ	A relation created by the AEROZ bulk entry (Character, Input)
[UGTKG]	Spline matrix relating the structural displacements at G-set d.o.f to the displacements and slopes at the K-set d.o.f of the aerodynamic boxes. (Output)

Application Calling Sequence:

None

Method:

The **SPLINZ** module is very similar to the **SPLINES** and **SPLINEU** modules (see ASTROS Programmer's Manual), except:

1. It only relates the aerodynamic boxes associated with **BODY7** and **CAERO7** to the structural model.
2. In addition to the **SPLINE1**, **SPLINE2** and **ATTACH** bulk data entries, it also reads the **SPLINE3** bulk data entry for 3D spline.
3. The spline matrix is used for both the steady and unsteady aeroelastic modules.

The spline matrix **[UGTKG]** is used for both steady aeroelastic analysis and dynamic aeroelastic analysis. For the definition of K-set d.o.f., please see entity descriptions of entity **UGTKG**.

Design Requirements:

None

Error Conditions:

1. Each aerodynamic box may appear on only one **SPLINE1**, **SPLINE2**, **SPLINE3** or **ATTACH** entry, although not all boxes need appear. Missing boxes will not influence the aeroelastic response.

2. Missing structural grids or aerodynamic elements appearing on the spline definitions will be flagged.

Engineering Application Module: **SZAERO**

Entry Point: **SZAERO**

Purpose:

Generates steady aerodynamic AIC matrices and aerodynamic forces of unit configuration parameters by the ZAERO module.

MAPOL Calling Sequence:

```
CALL SZAERO ( [AJK], MINDEX, LOOP, AECOMPZ, GEOMZA, AGRIDZ, STABCF,  
[AICMAT(MINDEX)], [AAICMAT(MINDEX)], [AIRFRC(MINDEX)],  
[SCNTLK], [ACNTLK] );
```

AJK	Unsteady AIC matrices generated by the UZAERO module (Input)
MINDEX	Mach number index for the current pass. Controls which Mach number/symmetry conditions will be processed in this pass by SZAERO . One pass for each unique Mach number will be performed with MINDEX incrementing by one until SZAERO returns LOOP = .FALSE. (Input)
LOOP	A logical flag set by SZAERO to indicate whether additional MINDEX subscripts are needed to complete the processing of all Mach number/symmetry conditions on all the TRIM bulk data entries. One pass for each unique Mach number will be performed with MINDEX incrementing by one until SZAERO returns LOOP = .FALSE. (Output)
AECOMPZ	A relation created by the AEROGM module describing aerodynamic components (Character, Input)
GEOMZA	A relation created by the AEROGM module describing the aerodynamic boxes (Character, Input)
AGRIDZ	A relation created by the AEROGM module describing the corner points of aerodynamic boxes (Character, Input)
STABCF	A relation of rigid aerodynamic stability coefficients for unit configuration parameters. The coefficients are stored in STABCF and the corresponding distributed forces are stored in [AIRFRC(MINDEX)] . The STABCF relation is used to pick the appropriate rigid loads from [AIRFRC(MINDEX)] when performing the aeroelastic trim as well as for retrieving the RIGID/FLEXIBLE stability coefficients for each configuration parameters. (Output)
[AICMAT(MINDEX)]	Matrix containing the steady aerodynamic influence coefficients for symmetric flight condition (Output)
[AAICMAT(MINDEX)]	Same as [AICMAT(MINDEX)] but for antisymmetric flight condition (Output)
[AIRFRC(MINDEX)]	Matrix containing the steady aerodynamic distributed forces for unit configuration parameters for the current Mach number index. If both symmetric and antisymmetric conditions exist for the Mach number, both sets of configuration parameters will coexist in [AIRFRC] . (Output)

[SCNTLK]

Matrix (created by the **CONMOD** module) whose rows contain the symmetric control surface modes defined at the K-set D.O.F. and columns are associated with the **AESURFZ** bulk data entries. [SCNTLK] is used to compute the aerodynamic stability coefficients and distributed forces contained in **STABCF** and [AIRFRC] by unit deflection of control surfaces. (Input)

[ACNTLK]

Same as [SCNTLK] but for antisymmetric control surface modes.

Application Calling Sequence:

None

Method:

The **SZAERO** module is very similar to the **STEADY** module (see **ASTROS Programmer's Manual**) except that **SZAERO** processes the aerodynamic geometry generated by the **AEROGM** module and computes the AIC matrices from **ZONA6**, **ZONA7**, **ZTAIC**, and **ZONA7U** methods for wing-body configurations. The output data format of **SZAERO** is identical to that of the **STEADY** module so that the output data can be directly used by the downstream steady aeroelastic trim modules.

The steady AIC matrices are obtained by taking the real part of the lowest reduced frequency of the matrix [AJK], where [AJK] is generated by **UZAERO** module.

Design Requirements:

See **STEADY** module.

Error Conditions:

See **STEADY** module.

Engineering Application Module: **UZAERO**

Entry Point: **UZAERO**

Purpose:

Unsteady aeroelastic analysis preface by ZAERO module.

MAPOL Calling Sequence:

```
CALL UZAERO ( AECOMPZ, GEOMZA, AGRIDZ, [AJK], [AJC], [AJL] [QGK], [SKJ],  
              [SCNTLK], [ACNTLK], [LMODEK] );
```

AECOMPZ	A relation created by the AEROGM module describing aerodynamic components (Character, Input)
GEOMZA	A relation created by the AEROGM module describing the aerodynamic boxes (Character, Input)
AGRIDZ	A relation created by the AEROGM module describing the corner points of aerodynamic boxes (Character, Input)
[AJK]	Matrix containing the transposed unsteady aerodynamic influence coefficient (AIC) matrices for all Mach, and reduced frequency pairs defined in all MKAEROZ bulk data entries (Output)
[AJC]	Matrix containing the unsteady pressure in J-set D.O.F. on aerodynamic boxes due to the control surface modes for all Mach number and reduced frequency pairs defined in all MKAEROZ bulk data entries (Output)
[AJL]	Matrix containing the unsteady pressure in J-set D.O.F. on aerodynamic boxes due to the load modes for all Mach number and reduced frequency pairs defined in all MKAEROZ bulk data entries (Output)
[QGK]	Gust matrix containing the intermediated gust force vectors at the K-set D.O.F. for all Mach number and reduced frequency pairs defined in all MKAEROZ bulk data entries (Output)
[SKJ]	Integration matrix to take pressures in J-set D.O.F. to forces in K-set D.O.F (Output)
[SCNTLK]	Matrix (created by the CONMOD module) whose rows contain the symmetric control surface modes defined at the K-set D.O.F. and columns are associated with the AESURFZ bulk data entries. [SCNTLK] is used to compute the unsteady aerodynamic forces [AJC] by unit deflection of control surfaces. (Input)
[ACNTLK]	Same as [SCNTLK] but for antisymmetric control surface modes (Input)
[LMODEK]	Matrix (created by CONMOD module) whose rows contain load modes defined at the K-set D.O.F. and columns are associated with the LOADMOD bulk data entries. [LMODEK] is used to compute the unsteady aerodynamic forces [AJL] of the load modes. (Input)

Application Calling Sequence:

None

Method:

The **UZAERO** module first reads in the relational entity **AEROZ** to check the symmetric condition of the aerodynamic geometry. If **XZSYM** = 'YES', the symmetric AIC and antisymmetric AIC matrices will be generated regardless of whether they are required for the downstream unsteady aeroelastic modules. The AIC matrices are generated according to the input sequence of **MKAEROZ** bulk data entries. Each **MKAEROZ** will produce a set of AIC matrices at the given Mach number and its associated list of reduced frequencies. The geometric data of the aerodynamic model is based on the relations **AECOMPZ**, **GEOMZA**, and **AGRIDZ**.

The AIC matrices of Mach, reduced frequency, symmetry pairs are stored in **[AJK]**. **[AJC]** is computed by:

$$[AJC] = [AJK]^T [SCNTLK], [ACNTLK]$$

pre-multiplied **[AJC]** by **[SKJ]^T** will yield the control surface aerodynamic forces at K-set D.O.F.

The intermediated gust force vector **[Q GK]** is computed by:

$$[Q GK] = [SKJ]^T [AJK]^T \{ \exp(-i * K * X / (REFC / 2.)) \}$$

where K is the reduced frequency.
 X is the aerodynamic box control point locations.
 REFC is the reference chord.

[AJL] is computed by:

$$[AJL] = [AJK]^T [LMODEK]$$

pre-multiplied **[AJL]** by **[SKJ]^T** will yield the load mode aerodynamic forces at K-set D.O.F.

The method to retrieve the **[AJK]** and **[AJC]**, and **[AJL]** matrices of a given Mach number, reduced frequency, and symmetry pair is described in relational entity **REUNMK**.

Design Requirements:

Unlike the **AMP** module, the **UZAERO** module does not generate the **[QKK]** matrix. The **[QKK]** matrix is computed by the **FLUTQHHZ** module from:

$$[QKK] = [SKJ]^T [AJK]^T$$

The unsteady forces due to control surface modes (defined as **[QKC]**) can be computed by:

$$[QKC] = [SKJ]^T [AJC]$$

Error Conditions:

None

5.0 ZAERO DATABASE ENTITY DESCRIPTIONS

To facilitate the communication of data among the ZAERO engineering application modules, fifteen new database entities (11 Matrix and 4 Relational) are created and are presented in Table 3.

Table 3. ZAERO Database Entities.

Entity Name	Description	Type
AJC	Basic name of the unsteady aerodynamic matrix containing unsteady pressure coefficients at J-set d.o.f. due to unit control surface deflections.	Matrix
QGK	Basic name of the unsteady aerodynamic gust force vector containing the intermediated unsteady forces at K-set d.o.f	Matrix
SKJ	Integration matrix relating the unsteady aerodynamic pressure coefficients at the J-set d.o.f. to the unsteady aerodynamic forces at the K-set d.o.f.	Matrix
AJK	Basic name of the unsteady aerodynamic AIC matrix relating the displacements at the K-set d.o.f to the pressure coefficients at the J-set d.o.f.	Matrix
ACNTLK	Displacements and slopes defined at K-set d.o.f. due to unit anti-symmetric control surface deflection.	Matrix
SCNTLK	Translational and rotational displacements defined at G-set d.o.f. due to unit symmetric control surface deflection.	Matrix
SCNTLG	Displacements and slopes defined at K-set d.o.f. due to unit symmetric control surface deflection.	Matrix
ACNTLG	Translational and rotational displacements defined at G-set d.o.f. due to unit anti-symmetric control surface deflection.	Matrix
LMODEG	Translational and rotational displacements defined at G-set d.o.f due to the load modes specified in bulk entries LOADMOD .	Matrix
LMODEK	Displacements and slopes defined at K-set d.o.f due to the load modes specified in bulk entries LOADMOD .	Matrix
UGTKG	Spline matrix relating the structural displacements at G-set d.o.f to the displacements and slopes at the K-set d.o.f of the aerodynamic boxes, but stored in the transposed form.	Matrix
AECOMPZ	Contains data on the aerodynamic components in the CAERO7 and BODY7 bulk entries.	Relation
GEOMZA	Contains data on the aerodynamic boxes of the CAERO7 and BODY7 bulk entries.	Relation
AGRIDZ	Contains data of the corner grid points on the CAERO7 and BODY7 boxes.	Relation
REUNMK	Contains the relations between the unsteady aerodynamic matrices generated by the UZAERO module to the bulk entries MKAEROZ .	Relation

The ZAERO database entities are documented similar to those in the ASTROS Programmer's Manual (Ref 2). A Usage section has been added to aide and clearly define to the programmer data stored on each database entity.

Entity: **AJC**

Entity Type: **MATRIX**

Description: Basic name of the unsteady aerodynamic matrix containing unsteady pressure coefficients at J-set d.o.f. due to unit control surface deflections. **AJC** is used during the aeroservoelastic analysis.

Matrix Form: Complex matrix with number of columns being equal to the number of control surfaces and J-set number of rows being equal to the number of J-set d.o.f.

Created by: **UZAERO**

Usage:

AJC contains a three characters string 'AJC' defined by **MAPOL**. To retrieve the **AJC** of a given Mach number, reduced frequency pair and symmetry condition, please see entity **REUNMK**.

The actual matrix name stored on the data base is **AJC_{siiijj}**,

where s='S' for symmetric or asymmetric case, ='A' for antisymmetric case.

ii=index of Mach number.

jj=index of reduced frequency.

The matrix **QKC** defined as the unsteady aerodynamic forces due to unit control surface deflections at K-set is computed by:

$$[QKC]=[SKJ]^T[AJC_{siiijj}]$$

The unsteady generalized aerodynamic control forces **[QHCLFL]** is computed by:

$$[QHCLFL]=[PHIKH]^T[QKC]$$

where **[PHIKH]** is the modal matrix at K-set d.o.f.

Therefore the number of rows of **[QHCLFL]** is the number of modes. Each column of **[QHCLFL]** corresponds to the generalized aerodynamic control forces due to each of the bulk entry **AESURFZ** with TYPE=SYM for **AJC_{siiijj}** and TYPE=ANTISYM for **AJC_{aiiijj}**.

Entity: **Q GK**

Entity Type: **MATRIX**

Description: Basic name of the unsteady aerodynamic gust force vector containing the intermediated unsteady forces at K-set d.o.f. **Q GK** is used by the aeroservoelastic gust analysis.

Matrix Form: Complex matrix with one column and K-set number of rows.

Created by: **UZAERO**

Usage:

Q GK contains a three character string 'Q GK' defined by **MAPOL**. To retrieve the **Q GK** of a given Mach number, reduced frequency pair and symmetry condition, please see entity **REUNMK**.

The actual matrix name stored on the data base is **Q GK_{siiijj}**,
 where s='S' for symmetric or asymmetric case, ='A' for antisymmetric case.
 ii=index of Mach number.
 jj=index of reduced frequency.

The actual gust generalized forces in modal space is computed by:

$$[Q GK_{siiijj}] = [Q GK_{siiijj}] * \exp(i * k * x_o / (REFC / 2.))$$

where x_o is the location of the reference plane defined in the bulk entry **GUST**.
 k is the corresponding reduced frequency.
 and REFC is the reference chord defined in bulk entry **AEROZ**.

Entity: **SKJ**

Entity Type: **MATRIX**

Description: Integration matrix relating the unsteady aerodynamic pressure coefficients at the J-set d.o.f. to the unsteady aerodynamic forces at the K-set d.o.f.

Matrix Form: Real matrix with J-set number of column and K-set number of rows but stored in the transposed form.

Created by: **UZAERO**

Usage: **SKJ** depends on the geometry of the aerodynamic model only and is independent of Mach number and reduced frequency.

Entity:	AJK
Entity Type:	MATRIX
Description:	Basic name of the unsteady aerodynamic AIC matrix relating the displacements at the K-set d.o.f to the pressure coefficients at the J-set d.o.f.
Matrix Form:	Complex matrix with K-set number of columns and J-set number of rows but stored in the transposed form.
Created by:	UZAERO
Usage:	

AJK contains a three characters string 'AJK' defined by **MAPOL**. To retrieve the **AJK** of a given Mach number, reduced frequency pair and symmetry condition, please see entity **REUNMK**.

The actual matrix name stored on the data base is **AJK_{siiijj}**,
where s='S' for symmetric or asymmetric case, ='A' for antisymmetric case.
ii=index of Mach number.
jj=ndex of reduced frequency.

The matrix **QKK** relating displacements at K-set to unsteady aerodynamic forces at K-set is computed by:

$$[QKK]=[SKJ]^T [AJK_{siiijj}]^T$$

The unsteady generalized aerodynamic forces **[QHHLFL]** is computed by:

$$[QHHLFL]=[PHIKH]^T [QKK][PHIKH]$$

where **[PHIKH]** is the modal matrix at K-set d.o.f.

However, in the **FLUTQHHZ** module and **QHHLGENZ** module, **[QHHLFL]** is computed by the following procedure:

The unsteady aerodynamic pressure coefficients **[CP]** at J-set d.o.f. is first obtained

$$[CP]=[AJK_{siiijj}]^T [PHIKH]$$

Then, the aerodynamic forces at K-set d.o.f are computed:

$$[FORCE]=[SKJ]^T [CP]$$

Finally, the generalized aerodynamic forces are computed:

$$[QHHLFL]=[PHIKH]^T [FORCE]$$

Matrices **[CP]** and **[FORCE]** are deleted after **[QHHLFL]** is obtained.

Entity: **ACNTLK**

Entity Type: **MATRIX**

Description: Displacements and slopes defined at K-set d.o.f. due to unit anti-symmetric control surface deflection. Each column is corresponding to each **AESURFZ** bulk entry with **TYPE=ANTISYM**.

Matrix Form: Real matrix with K-set number of rows and number of columns being equal to the number of **AESURFZ** bulk entries with **TYPE=ANTISYM**.

Created by: **CONMOD**

Usage:

1. **ACNTLK** is used by both **UZAERO** and **SZAERO** modules.

For the **UZAERO** module, it generates the **[AJC]** matrix for all **MKAEROZ** bulk entries by:

$$[AJC]=[AJK]^T[ACNTLK]$$

For the **SZAERO** module, it generates the matrix **[AIRFRC]** and the aerodynamic stability coefficients of control surfaces (stored in relation **STABCF**) for each **TRIM** bulk entry by:

$$[AIRFRC]=[AAICMAT]^T[ACNTLK]$$

2. **ACNTLK** does not exist if there are no **AESURFZ** with **TYPE=ANTISYM**.

Entity: **SCNTLK**

Entity Type: **MATRIX**

Description: Displacements and slopes defined at K-set d.o.f. due to unit symmetric control surface deflection. Each column corresponds to each **AESURFZ** bulk entry with **TYPE=SYM** or **ASYM**.

Matrix Form: Real matrix with K-set number of rows and number of columns being equal to the number of **AESURFZ** bulk entries with **TYPE=SYM** or **ASYM**.

Created by: **CONMOD**

Usage:

1. **SCNTLK** is used by both the **UZAERO** and **SZAERO** modules.

For **UZAERO** module, it generates the **[AJC]** matrix for all **MKAEROZ** bulk entries by:

$$[AJC]=[AJK]^T[SCNTLK]$$

For the **SZAERO** module, it generates the matrix **[AIRFRC]** and the aerodynamic stability coefficients of control surfaces (stored in relation **STABCF**) for each **TRIM** bulk entry by:

$$[AIRFRC]=[AICMAT]^T[SCNTLK]$$

2. **SCNTLK** does not exist if there are no **AESURFZ** with **TYPE=SYM** or **ASYM**.

Entity: SCNTLG

Entity Type: MATRIX

Description: Translational and rotational displacements defined at G-set d.o.f. due to unit symmetric control surface deflection. Each column corresponds to an AESURFZ bulk entry with TYPE=SYM or ASYM.

Matrix Form: Real matrix with G-set number of rows and number of columns being equal to the number of AESURFZ bulk entries with TYPE=SYM or ASYM.

Created by: CONMOD

Usage:

1. SCNTLG is used to compute the inertial matrix of the control surfaces in modal space by:

$[\text{PHIG}]^T [\text{MGG}] [\text{SCNTLG}]$ in G-set d.o.f.

or

$[\text{PHIA}]^T [\text{MAA}] [\text{SCNTLA}]$ in A-set d.o.f. Where [SCNTLA] can be computed by the reduction of [SCNTLG] from G-set to A-set.

2. SCNTLG does not exist if there are no AESURFZ with TYPE=SYM or ASYM.

Entity: **ACNTLG**

Entity Type: **MATRIX**

Description: Translational and rotational displacements defined at G-set d.o.f. due to unit anti-symmetric control surface deflection. Each column corresponds to an **AESURFZ** bulk entry with **TYPE=ANTISYM**.

Matrix Form: Real matrix with G-set number of rows and number of columns being equal to the number of **AESURFZ** bulk entries with **TYPE=ANTISYM**.

Created by: **CONMOD**

Usage:

1. **ACNTLG** is used to compute the inertial matrix of the control surfaces in modal space by:

$$[\text{PHIG}]^T [\text{MGG}] [\text{ACNTLG}] \text{ in G-set d.o.f.}$$

or

$$[\text{PHIA}]^T [\text{MAA}] [\text{ACNTLA}] \text{ in A-set d.o.f. Where } [\text{ACNTLA}] \text{ can be computed by the reduction of } [\text{ACNTLG}] \text{ from G-set to A-set.}$$

2. **ACNTLG** does not exist if there are no **AESURFZ** with **TYPE=ANTISYM**.

Entity: **LMODEG**

Entity Type: **MATRIX**

Description: Translational and rotational displacements defined at G-set d.o.f due to the load modes specified in bulk entries **LOADMOD**.

Matrix Form: Real matrix with G-set number of rows and number of columns being equal to the number of **LOADMOD** bulk entries.

Created by: **CONMOD**

Usage:

1. **LMODEG** is used to compute the sectional forces or moments at the structural grid points defined by the **LOADMOD** bulk entries. **LMODEG** can be reduced from G-set to A-set d.o.f. by the A-set reduction procedures.
2. **LMODEG** does not exist if there are no **LOADMOD** bulk data entries.

Entity: **LMODEK**

Entity Type: **MATRIX**

Description: Displacements and slopes defined at K-set d.o.f due to the load modes specified in bulk entries **LOADMOD**.

Matrix Form: Real matrix with K-set number of rows and number of columns being equal to the number of **LOADMOD** bulk entries.

Created by: **CONMOD**

Usage:

1. **LMODEK** is used to compute the sectional forces or moments at the aerodynamic boxes defined by the **LOADMOD** bulk entries.
2. **LMODEK** does not exist if there are no **LOADMOD** bulk data entries.

Entity: **UGTKG**

Entity Type: **MATRIX**

Description: Spline matrix relating the structural displacements at G-set d.o.f to the displacements and slopes at the K-set d.o.f of the aerodynamic boxes, but stored in the transposed form.

Matrix Form: Real matrix with G-set number of rows and K-set number of columns.

Created by: **SPLINZ**

Usage:

1. The definition of K-set d.o.f. is:

For each aerodynamic box, six d.o.f.'s are assigned and defined as:

{T1, T2, T3, d(T1)/dx, d(T2)/dx, d(T3)/dx}, where T1, T2, and T3 are the displacements at the centroid of the aerodynamic box along x, y, and z directions, respectively. d()/dx denotes as the slope of () with respect to the free stream direction (the x-axis of the aerodynamic coordinates).

Therefore, for N number of aerodynamic boxes (number of J-set d.o.f.'s = N), number of K-set d.o.f.'s = $6 * N$.

2. [UGTKG] can be reduced to [UGTKA] by the A-set reduction procedures, where [UGTKA] is used to transform the displacements at A-set to K-set and transform the aerodynamic forces from K-set to A-set by the transposed of [UGTKA].
3. [UGTKG] is computed according to the **SPLINE1**, **SPLINE2**, **SPLINE3**, and **ATTACH** bulk entries.

Entity: **AECOMPZ**

Entity Type: Relation

Description: Contains data on the aerodynamic components in the **CAERO7** and **BODY7** bulk data entries.

Relation Attributes:

NAME	TYPE/KEY	DESCRIPTION
ACID	Integer>0	Identification number of CAERO7 or BODY7 bulk entries.
MACROTYP	Text(8)	Either 'CAERO7' or 'BODY7'.
GROUP	Integer	Identification number of the ACOORD bulk entry.
ACMPNT	Text(8)	Component type. One of WING or BODY .
TYPE	Integer>0	TYPE=2 for CAERO7 , 3 for BODY7 .
FIINTID	Integer>0	First internal aerodynamic box identification number.
NCBOX	Integer>0	Number of chordwise boxes for CAERO7 . =1 for BODY7 .
NSBOX	Integer>0	Number of spanwise boxes for CAERO7 . Number of boxes for BODY7 .
BNDRY	R Vector(12)	For CAERO7 : BNDRY(i), i=1,3: x, y, z of leading edge at root. BNDRY(i), i=4,6: x, y, z of trailing edge at root. BNDRY(i), i=7,9: x, y, z of leading edge at tip. BNDRY(i), i=10,12: x, y, z of trailing edge at tip. For BODY7 : BNDRY(i), i=1,3: x, y, z of the nose. BNDRY(4): base pressure of the body wake. BNDRY(5): X location of the steady point singularity of the body wake. BNDRY(6): X location of the unsteady point singularity of the body wake. BNDRY(i), i=7,8: Y and Z offset for the point singularity of the body wake. BNDRY(9): Body length. BNDRY(10): Flag for body wake. (Integer) BNDRY(11): Number of inlet boxes. (Integer) BNDRY(12): Number of wake boxes on the body.
WCOS		For CAERO7 : Cos(theta), where theta = dihedral angle. For BODY7 : Number of segments. (Integer)
WSIN		For CAERO7 : Sin(theta), where theta = dihedral angle. For BODY7 : Not used.
IWING	Integer	Flag for vertical fin on the X-Z plane. =0: yes. =1, no.
ATTR	Integer	=0: CAERO7 root is not attached to BODY7 . >0: CAERO7 root is attached to BODY7 with ID=ATTR. Not used for BODY7 .
YRB	Real	Y location of the center line of BODY7 to which the CAERO7 root is attached.
ZRB	Real	Z location of the center line of BODY7 to which the CAERO7 root is attached.

FLCOSR	Real	Cos(theta), where theta is the dihedral angle of the vortex-carry-through boxes at root.
FLSINR	Real	Sin(theta), where theta is the dihedral angle of the vortex-carry-through boxes at root.
ATTT	Integer	=0: CAERO7 Tip is not attached to BODY7. >0: CAERO7 Tip is attached to BODY7 with ID=ATTT Not used for BODY7.
YTB	Real	Y location of the center line of BODY7 if CAERO7 tip is attached to it.
ZTB	Real	Z location of the center line of BODY7 if CAERO7 root is attached to it.
FLCOST	Real	Cos(theta), where theta is the dihedral angle of the vortex-carry-through boxes at tip.
FLSINT	Real	Sin(theta), where theta is the dihedral angle of the vortex-carry-through boxes at tip.
LABEL	Text(8)	Label of CAERO7 or BODY7 bulk entries.

Created by:

AEROGM

Usage:

AECOMPZ is used by **SPLINZ**, **UZAERO** and **SZAERO** modules.

Entity: **GEOMZA**

Entity Type: Relation

Description: Contains data on the aerodynamic boxes of the **CAERO7** and **BODY7** bulk data entries.

Relation Attributes:

NAME	TYPE/KEY	DESCRIPTION
MACROID	Integer	Component identification number of the associated CAERO7 or BODY7 .
ACMPNT	Text(8)	'FUSEL' for BODY7 box, 'WING' for CAERO7 box.
NDOF	Integer	=3 for BODY7 box, =2 for CAERO7 box.
EXTID	Integer	External identification number of the box.
INTID	Integer	Internal identification number of the box.
AREA	Real	Area of the box.
X	Real	X location of centroid of the box.
Y	Real	Y location of centroid of the box.
Z	Real	Z location of centroid of the box.
N1	Real	X component of the box normal in basic coordinates.
N2	Real	Y component of the box normal in basic coordinates.
N3	Real	Z component of the box normal in basic coordinates.
R1	Real	X component of the box local pitch axis in basic coordinates.
R2	Real	Y component of the box local pitch axis in basic coordinates.
R3	Real	Z component of the box local pitch axis in basic coordinates.
RTHETA	Real	For BODY7 box: dihedral angel of the box. For CAERO7 box: Thickness slope at 50% chord.
RDELTA	Real	For BODY7 box: Inclination angel of the box. For CAERO7 box: Camber slope at 50% chord.
CHORD	Real	Chord length.
ID1	Integer	Aerodynamic grid identification number at left hand side corner of the box leading edge.
ID2	Integer	Aerodynamic grid identification number at left hand side corner of the box trailing edge.
ID3	Integer	Aerodynamic grid identification number at right hand side corner of the box leading edge.
ID4	Integer	Aerodynamic grid identification number at right hand side corner of the box trailing edge.
CAM85	Real	Camber slope at 85% chord for CAERO7 box. Not used for BODY7 box.
CAM95	Real	Camber slope at 95% chord for CAERO7 box. Not used for BODY7 box.
DZX85	Real	Thickness slope at 85% chord for CAERO7 box. Not used for BODY7 box.
DZX95	Real	Thickness slope at 95% chord for CAERO7 box. Not used for BODY7 box.

DZXLE	Real	Thickness slope at leading edge of the mid-chord for CAERO7 box. Not used for BODY7 box.
DZXTE	Real	Thickness slope at trailing edge of the mid-chord for CAERO7 box. Inlet panel flow ratio in percentage for BODY7 box.
IWAKE	Integer	For BODY7 box=1, box is inlet panel. =0, box is not inlet panel. Not used for CAERO7 box.

Created by:

AEROGM

Usage:

GEOMZA is used by **SPLINZ**, **UZAERO** and **SZAERO** modules.

Entity: **AGRIDZ**

Entity Type: Relation

Description: Contains data of the corner grid points on the **CAERO7** and **BODY7** boxes.

Relation Attributes:

NAME	TYPE/KEY	DESCRIPTION
EXTID	Integer>0	External identification of the grid point.
INTID	Integer>0	Internal identification of the grid point.
CORD	Integer	Identification number of ACOORD bulk entry.
X	Real	X location of the grid point.
Y	Real	Y location of the grid point.
Z	Real	Z location of the grid point.

Created by: **AEROGM**

Usage: **AGRIDZ** is used by **UZAERO** and **SZAERO** modules.

Entity: **REUNMK**

Entity Type: Relation

Description: Contains the relations between the unsteady aerodynamic matrices generated by the **UZAERO** module to the bulk entries **MKAEROZ**.

Relation Attributes:

NAME	TYPE/KEY	DESCRIPTION
IDMK	Integer>0	Identification number specified in the bulk entries MKAEROZ .
MACH	Real \geq 0.	Mach number specified in bulk entries MKAEROZ .
METHOD	Integer	Method flag specified in bulk entries MKAEROZ .
SYMXZ	Integer	Symmetry flag. SYMXZ=1 for symmetric case, =-1 for antisymmetric case, =0 for asymmetric case.
ALPHA	Real	Angle of attack specified in the TRIMFLT bulk entry of the current MKAEROZ .
BETA	Real	Side slip angle specified in the TRIMFLT bulk entry of the current MKAEROZ .
PRATE	Real	Non-dimensional roll rate specified in the TRIMFLT bulk entry of the current MKAEROZ .
QRATE	Real	Nondimensional pitch rate specified in the TRIMFLT bulk entry of the current MKAEROZ .
RRATE	Real	A non-dimensional yaw rate specified in the TRIMFLT bulk entry of the current MKAEROZ .
MINDEX	Integer>0	Index of the MKAEROZ bulk entry ranging from 1 to the number of the MKAEROZ bulk entries.
KINDEX	Integer>0	Index of the reduced frequency ranging from 1 to the number of reduced frequencies specified in the current MKAEROZ .
RFREQ	Real>0.0	The KINDEX'th reduced frequency specified in the current MKAEROZ .

Created by: **UZAERO**

Usage:

The **UZAERO** module generates the unsteady aerodynamic matrices [AJK], [AJC], and [QGK] of all **MKAEROZ** bulk entries in the input file regardless of whether or not they are required for the downstream unsteady aeroelastic modules. To retrieve these matrices, please see the example on the following page:

For a given pair of IDMK and SYMXZ found in either the FLUTTER or GUST bulk entry, to retrieve the corresponding matrix [AJK]:

```

CHARACTER*8 UNLIST(12),NAME
DATA UNLIST/'IDMK','MACH','METHOD','SYMXZ','ALPHA','BETA','PRATE','QRATE'
*      'RRATE','MINDEX','KINDEX','RFREQ'/
INTEGER INFO(20),IGET(12),MINDEX(100),KINDEX(100),SYMXZ
REAL RGET(12),K(100),MACH
EQUIVALENCE (RGET(1),IGET(1))
CHARACTER*1 S
CALL DBOPEN(REUNMK,INFO,'RO','NOFLUSH',ISTAT)
CALL REPROJ(REUNMK,12,UNLIST)
NMK=INFO(3)
C      NMK = total number of MKAEROZ bulk entries.
INDEX=0
DO I=1,NMK
    CALL REGET(REUNMK,IGET,ISTAT)
    IF(IDMK.EQ.IGET(1)) THEN
        INDEX=INDEX+1
        MACH=REGET(2)
        METHOD=IGET(3)
        ISYM=IGET(4)
        MINDEX(INDEX)=IGET(10)
        KINDEX(INDEX)=IGET(11)
        K(INDEX)=RGET(12)
    ENDIF
ENDDO
CALL DBCLOS(REUNMK)
KTOTAL=INDEX
C KTOTAL is the total number of reduced frequencies specified in the MKAEROZ bulk entry
C with IDMK as the identification number.
C IF one wishes to retrieve the [AJK] matrix of the second reduced frequency, do the
C following:
    KTH=2
    IF(SYMXZ.EQ.1.OR.SYMXZ.EQ.0) THEN
        S='S'
    ELSE
        S='A'
    ENDIF
C Subroutine MYNAME is an utility routine to assemble the matrix name.
C INPUT:  AJK      A three characters string contains the basic name of the matrix.
C          S='S' for symmetric or asymmetric case, ='A' for antisymmetric case.
C          MINDEX(KTH)  KTH'th Mach number index found in the REUNMK relation.
C          KINDEX(KTH)  KTH'th reduced frequency index found in the REUNMK relation.
C OUTPUT: A character*8 string of the matrix created by UZAERO module with the form:
C          AJKsiijj, where s=S, ii=MINDEX(KTH), and jj=KINDEX(KTH)
    CALL MYNAME(AJK,S,MINDEX(KTH),KINDEX(KTH),NAME)
C Now, NAME is the matrix name of the AIC matrix of the corresponding Mach number and
C reduced frequency.
    CALL MYNAME(AJC,S,MINDEX(KTH),KINDEX(KTH),NAME)
C Now, NAME is the matrix name of the control surface forces matrix of the corresponding
C Mach number and reduced frequency.
    CALL MYNAME(QGK,S,MINDEX(KTH),KINDEX(KTH),NAME)
C Now, NAME is the matrix name of the gust force matrix of the corresponding
C Mach number and reduced frequency.
C      .....
C      .....

```

6.0 REFERENCES

1. D.J. Neill, D.L. Herendeen, "ASTROS User's Manual," Volume I, WL-TR-96-3004, May 1995.
2. D.J. Neill, D.L. Herendeen, R.L. Hoesly, "ASTROS Programmer's Manual," Volume II, WL-TR-93-3038, March 1993.
3. Johnson, E.H. and Venkayya, V.B., "Automated Structural Optimization System (ASTROS), Theoretical Manual," AFWAL-TR-88-3028, Vol. 1, December 1988.

APPENDIX A

ZAERO FUNCTIONAL MODULE DEFINITION (MODDEF.DAT)

The following is a list of all ZAERO module definitions added to ASTROS and found in file MODDEF.DAT.

```
AEROGM      3
102  7  7  7
C
C  AERO GEOMETRY FOR ZAERO MODULE
C  NOTE: ALPHABETICAL ORDER IN FILE MODDEF.DAT IS NOT REQUIRED
C
C  CALL AEROGM ( EP(1), EP(2), EP(3) )
END
```

```
CONMOD      8
102  7  7  8  8  8  8  8  8
C
C  ZAERO CONTROL MODE GENERATOR
C
C  CALL CONMOD ( EP(1), EP(2), EP(3), EP(4), EP(5), EP(6), EP(7),
1  EP(8) )
END
```

```
FLUTQHHZ   18
102 -1  1  1  1  1  8  8  8  8  9  8  8  1  7  7  8  8  7
C
C  PROCESS THE 'FLUTQHHL' MODULE - FLUTTER AEROMATRIX PROCESSOR
C
C  CALL FLTQHZ ( IP(1), IP(2), IP(3), IP(4), IP(5), EP(6), EP(7),
1  EP(8), EP(9), EP(10), EP(11), EP(12), IP(13),
2  EP(14), EP(15), EP(16), EP(17), EP(18))
END
```

```
FLUTSENZ   21
102  1  1  1  4  1  1  7  7  7  9  7  9  7  7  8  8  8  8  8
8  7
C
C  PROCESS THE 'FLTSTY' MODULE TO OBTAIN FLUTTER CONST. SENSITIV.
C
C  CALL FLTSTZ ( IP(1), IP(2), IP(3), LP(4), IP(5), IP(6), EP(7),
*  EP(8), EP(9), EP(10), EP(11), EP(12), EP(13),
*  EP(14), EP(15), EP(16), EP(17), EP(18), EP(19),
*  EP(20), EP(21) )
END
```

```
FLUTTRAZ   13
102 -1  1  1  8  7  1  1  8  8  8  7 -7  7
C
C  PROCESS THE 'FLUTAN' MODULE TO PERFORM FLUTTER ANALYSIS
C
C  CALL FLUTAZ ( IP(1), IP(2), IP(3), EP(4), EP(5), IP(6), IP(7),
1  EP(8), EP(9), EP(10), EP(11), EP(12), EP(13) )
END
```

```
QHHLGENZ   11
102  1  1  8  8  8  8  8  8  8  8  7
C
C  'QHHLGENZ' - GENERATE THE QHH MATRIX LIST FOR FLUTTER ANALYSIS
C
C  CALL QHJGEN ( IP(1), IP(2), EP(3), EP(4), EP(5), EP(6),
1  EP(7), EP(8), EP(9), EP(10), EP(11) )
END
```

```
SPLINZ      5
102  1  7  7  7  8
C
C  PROCESS THE UNSTEADY AERODYNAMIC SPLINE
C
C  CALL SPLINZ ( IP(1), EP(2), EP(3), EP(4), EP(5) )
END
```

```

SZAERO      12
102  8  1  4  7  7  7  7  8  8  8  8  8
C
C   PROCESS ZAERO STEADY AERODYNAMICS
C   (PREFACE TO STATIC AEROELASTICITY DISCIPLINE)
C
C   CALL SZAERO ( EP(1), IP(2), LP(3), EP(4), EP(5), EP(6), EP(7),
1      EP(8), EP(9), EP(10),EP(11),EP(12) )
END

```

```

UZAERO      11
102  7  7  7  8  8  8  8  8  8  8  8
C
C   AIC GENERATION BY ZAERO MODULE
C
C   CALL UZAERO ( EP(1), EP(2), EP(3), EP(4), EP(5), EP(6),
1      EP(7), EP(8), EP(9), EP(10),EP(11) )
END

```

```

INPUT4      6
102 -1  1  7  8  8  8
C
C   READ MODAL RESULTS FROM NASTRAN OUTPUT4 SOLUTION
C   AND REPLACE THE ASTROS DATABASE MATRICIES KAA, MAA, PHIA
C   AND RELATION LAMBDA
C
C   CALL INPUT4 (IP(1),IP(2),EP(3),EP(4),EP(5),EP(6))
END

```


APPENDIX B

ASTROS* MAPOL SEQUENCE LISTING

The following ASTROS* MAPOL sequence listing documents all changes made to the original ASTROS MAPOL sequence. All newly added lines and commented lines for integration of ZAERO into ASTROS are highlighted in boldfaced text. Arrows are also used at the ends of the lines to demarcate the beginning and ending of changes.

ASTROS* MAPOL Sequence Listing:

***** MAPOL SOURCE CODE LISTING *****

```

STAT.LEVL
1  1!$***$
2  1!$ CSCIID <@(#) MC0083-MAPOLSEQ 11.1 4/29/94 17:00:35> $
3  1!$***$
4  1!$*****$!
5  1!$ EXECUTIVE SEQUENCE FOR ASTROS $!
6  1!$*****$!
7  1!$*****$!
8  1!$ CONSTANTS FOR SDCOMP SET SINGULARITY MESSAGES $!
9  1!$*****$!
10 1!$INTEGER SINGOSET, SINGASET, SINGLSET; $!
11 1!$*****$!
12 1!$ VARIABLE DECLARATION SEGMENT $!
13 1!$*****$!
14 1!$ $!
15 1!$INTEGER GSIZE, NDV, NITER, BC, $!
16 1!$ ESIZE(1000), PSIZE(1000), GSIZEB; $!
17 1!$REAL CTL, CTLMIN; $!
18 1!$LOGICAL GLBCNVRG, APPCNVRG, PFLAG; $!
19 1!$UNSTRUCT DCENT, GRIDTEMP, SMPLOD; $!
20 1!$RELATION DESHIST, CONST, MPPARM, CONVERT, OCPARM, $!
21 1!$ MFORM, GRID, SPOINT, SEQGP, $!
22 1!$ BGPDT(1000), CSTM, FORCE, FORCE1, MOMENT, $!
23 1!$ MOMENT1, PLOAD, GRAV, LOAD, EIGR, $!
24 1!$ TEMP, TEMPD, OPNLBUCK, OEULBUCK, $!
25 1!$ CORD1C, CORD1R, CORD1S, CORD2C, CORD2R, $!
26 1!$ CORD2S, GPWGGRID, OGPWG, GRADIENT; $!
27 1!$ $!
28 1!$*****$!
29 1!$ DECLARATIONS FOR MODULE MKUSET $!
30 1!$*****$!
31 1!$ $!
32 1!$UNSTRUCT USET(1000), GPST(1000); $!
33 1!$RELATION SPC, SPC1, SPCADD, MPC, MPCADD, $!
34 1!$ ASET, ASET1, OMIT, OMIT1, SUPORT, $!
35 1!$ JSET, JSET1, RBAR, RBE1, RBE2, RBE3, RR0D; $!
36 1!$MATRIX [PGMN(1000)], [PNSF(1000)], [PFOA(1000)], [PARL(1000)], [TMN(1000)], $!
37 1!$ [YS(1000)]; $!
38 1!$MATRIX [PGMNS(1000)], [PNSFS(1000)], [PFOAS(1000)], $!
39 1!$ [PARLS(1000)]; $!
40 1!$ $!
41 1!$*****$!
42 1!$ DECLARATIONS FOR MODULES MAKEST AND EMG $!
43 1!$*****$!
44 1!$ $!
45 1!$UNSTRUCT TREF, DVSIZE, PCOMPS; $!
46 1!$UNSTRUCT KELM, MELM, TELM; $!
47 1!$RELATION CQDMEM1, QDMM1EST, CROD, CONROD, RODEST, $!
48 1!$ CSHEAR, SHEAREST, CTRMEM, TRMEMEST, CMAS1, $!
49 1!$ CMAS2, MASSEST, CONM1, CONM1EST, CONM2, $!
50 1!$ CONM2EST, CBAR, BEAMEST, CQUAD4, QUAD4EST, $!
51 1!$ CIHEX1, IHEX1EST, CIHEX2, IHEX2EST, CIHEX3, $!
52 1!$ IHEX3EST, CELAS1, CELAS2, ELASEST, $!
53 1!$ PCOMP, PQDMEM1, PROD, PSHEAR, $!
54 1!$ PTRMEM, PMASS, PELAS, PBAR, PSHELL, $!
55 1!$ PCOMP1, PCOMP2, PIHEX, MAT1, MAT2, $!
56 1!$ MAT8, MAT9, CTRIA3, TRIA3EST; $!
57 1!$ $!
58 1!$*****$!
59 1!$ DECLARATIONS FOR DESIGN VARIABLES/CONSTRAINTS AND LINKING $!
60 1!$*****$!
61 1!$ $!
62 1!$RELATION DESELM, DESVARP, DESVARS, PLIST, ELIST, $!
63 1!$ SHAPE, SHPGEN; $!
64 1!$RELATION DCONVM, DCONTW, DCONEP, DCONFT, DCONVMM, $!

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65 1! DCONTWM, DCONEPM, DCONFTM, DCONVMP, DCONTWP,
66 1! DCONEP, DCONFTP, DCONALE, DCONCLA, DCONFLT,
67 1! DCONTRM, DCONSCE,
68 1!RELATION DCONDSP, DCONFRQ, DCONTHK, DCONTH2;
69 1!RELATION DCONPMN, DCONLMN, DCONLAM;
70 1!RELATION DCONBK, DCONBKE;
71 1!RELATION GLBDES, DESLINK, TFIXED, LOCLVAR, DVCT;
72 1!MATRIX [PTRANS];
73 1!MATRIX [PMINT], [PMAXT], [SMAT];
74 1!$
75 1!$*****$
76 1!$ DECLARATIONS FOR OUTPUT FILE PROCESSING (EDR/OFF) $
77 1!$*****$
78 1!$
79 1!RELATION GRIDLIST, MODELIST, ELEMLIST, FREQLIST, TIMELIST,
80 1! ITERLIST, GVDLIST, LDVLIST, DCONLIST, PLYLIST;
81 1!$
82 1!RELATION GPFELEM, EOSUMRY, EOBAR, EOELAS, EOHEX1,
83 1! EOHEX2, EOHEX3, EOQDMM1, EOQUAD4, EOROD,
84 1! EOSHEAR, EOTRMEM, GPFDATA, EOTRIA3;
85 1!UNSTRUCT EODISC;
86 1!$
87 1!RELATION OGRIDLOD, OGRIDDSP, OLOCALDV, OAGRDDSP, OAGRDL0D;
88 1!MATRIX [FLUTMODE], [PTGLOAD], [PFGLOAD], [PTHLOAD], [PFHLOAD];
89 1!$
90 1!$*****$
91 1!$ DECLARATIONS FOR MODULES EMAL, EMA2 AND GLOBAL $
92 1!$ MATRIX PARTITION/REDUCTION $
93 1!$*****$
94 1!$
95 1!UNSTRUCT DKVI, DMVI;
96 1!RELATION GMKCT, GMMCT;
97 1!MATRIX [KGG], [KNN], [KFF], [KAA], [KLL],
98 1! [MGG], [MNN], [MFF], [MAA], [MLL],
99 1! [MRRBAR], [MLR], [KFS], [KSS], [KOOINV(1000)],
100 1! [GSUBO(1000)], [KLLINV(1000)], [MRR(1000)],
101 1! [IFM(1000)], [M1GG], [IFR(1000)], [KRR], [D(1000)],
102 1! [KLR], [K1GG], [LHS(1000)], [M2GG], [MOO],
103 1! [MOA], [K2GG], [MAABAR];
104 1!MATRIX [TMP1], [TMP2];
105 1!MATRIX [PG], [PN], [PF], [PA],
106 1! [PO], [PLBAR], [PR], [RHS(1000)], [UG(1000)],
107 1! [UN], [UF], [UA], [UL], [UM],
108 1! [AG(1000)], [AN], [AF], [AA], [AR],
109 1! [AL], [UO], [UOO], [PS];
110 1!LOGICAL M2GGFLAG, K2GGFLAG;
111 1!$
112 1!$*****$
113 1!$ DECLARATIONS FOR SOLUTION CONTROL $
114 1!$*****$
115 1!$
116 1!INTEGER NUMOPTBC, NBNDCOND, MAXITER,
117 1! MPS, MPE,
118 1! OCS, OCE,
119 1! FSDE,
120 1!INTEGER BLOAD, BMASS, BMODES, BSAERO, BFLUTR,
121 1! BDRSP, BDTR, BMTR, BDFR,
122 1! BMFR, BGUST, BELAST, NMPC, NSPC,
123 1! NOMIT, NRSET, DMODES;
124 1!REAL MOVLM, WINDOW, OCMOVLIM, ALPHA, CNVRGLIM,
125 1! NRFAC, EPS;
126 1!RELATION JOB, OPTIMIZE, CASE;
127 1!$
128 1!$*****$
129 1!$ DECLARATIONS FOR SENSITIVITY EVALUATION $
130 1!$*****$
131 1!$
132 1!INTEGER DDFLG, NACSD, NAUS, NAUA;
133 1!LOGICAL ACTBOUND, ACTFLUT, ACTDYN, ACTAERO, ACTAEFF,
134 1! ACTUAG, ACTUAGG, ACTPNL, ACTBAR;
135 1!UNSTRUCT PCAS, PCAA, PCAE;
136 1!RELATION PDLIST;
137 1!MATRIX [DFDU], [PGAS], [UGA], [DUG], [DMUG],
138 1! [DPFV], [DPOV], [DPNV], [DPAV], [DUAV],
139 1! [DUAD], [DUFV], [AGA], [AMAT], [DKUG],
140 1! [DPGV], [DPLV], [DURD], [DULD], [DULV],
141 1! [DDELVD], [DPRV], [DRHS], [DFDUF], [PGAA],
142 1! [DFDUN], [DMAG], [DMUN], [DMUF], [DMUA],
143 1! [DMUO], [DMUL], [DMUR], [DMU], [DP1],
144 1! [DK1V], [AUAGC], [DURV], [EFFSENS], [DU1L],
145 1! [DU1R], [DU2], [LHSL], [LHSU], [PGAU],

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146 1! [SENSMT];
147 1!IMATRIX [GLBSIG], [DPHVI], [DPGRVI], [DPVJ];
148 1!$
149 1!$*****
150 1!$ AERODYNAMIC ENTITIES
151 1!$*****
152 1!$
153 1!INTEGER SYM, MINDEX, SUB, S;
154 1!REAL QDP, MACH;
155 1!LOGICAL LOOP, AEFLG(1000), NONPONLY;
156 1!UNSTRUCT ACPT, UNMK;
157 1!RELATION AESURF, AIRFOIL, AEROS, AEFACT, AXSTA,
158 1! BODY, SPLINE1, SET1, SET2, ATTACH,
159 1! TRIM, AERO, BLAST, CAERO6, PAERO6,
160 1! GEOMSA, AECOMPS, STABCF, CAERO1, PAERO1,
161 1! CAERO2, PAERO2, MKAERO1, MKAERO2, FLUTTER,
162 1! FLFACT, CLAMBDA, CONEFFS, CONLINK, GEOMUA,
163 1! AECOMPU, SPLINE2, CONEFFS, AEROGEO, CAROGEOM,
164 1! AERUGEOM, CAROUGE, ACOORD, AGRID, AGRIDZ,
165 1! AQUAD4, ATRIA3, CAERO7, PAFOIL7, BODY7,
166 1! PBODY7, SEGMENT, CHORDCP, MACHCP, ZTAIC,
167 1! AECOMP2, GEOMZA, MKAEROZ, AEROZ, REUNMK,
168 1! PANLST1, PANLST2, SPLINE3, AESURF2, TRIMFLT,
169 1! LOADMOD;
170 1!IMATRIX [AIRFR(1000)], [AICMAT(1000)], [AAICMAT(1000)],
171 1! [AICS], [KAFF], [PAF], [KAAA], [PAA],
172 1! [GASUBO(30,33)], [SKJ], [D1JK], [D2JK],
173 1! [KARL], [R11], [K21(30,33)], [PARBAR], [PAL],
174 1! [PAR(30,33)], [K112(30,33)], [AIRFORCE], [K22],
175 1! [GTKG], [GTKN], [GTKF], [GSTKG], [GSTKN],
176 1! [GSTKF], [GSKF], [UGTKG], [UGTKN], [UGTKF],
177 1! [UGTKA], [UGTKO], [UGTKAB], [AITD], [KARR],
178 1! [R12(30,33)], [R22], [R32(30,33)], [K11], [K12(30,33)],
179 1! [P1], [R21(30,33)], [R31(30,33)], [RL11(30,33)],
180 1! [RU11(30,33)], [P2], [MAAA], [IFMA(30,33)],
181 1! [R13(30,33)], [R33], [DELIC], [PRIGID],
182 1! [AARC], [AAR], [AAA(1000)], [UAA(1000)], [AAAGC],
183 1! [PAO(1000)], [AAFTMP], [UAFTMP], [UAN], [AAN],
184 1! [UAG(1000)], [AAG(1000)], [AAL], [AAF], [UAF],
185 1! [KOOL(30,33)], [KOOU(30,33)], [LHSA(30,33)],
186 1! [POARO(30,33)], [KAO(30,33)], [UAR], [RHSA(30,33)],
187 1! [DELTA(1000)], [PAOC(1000)], [UAAC(1000)], [AAAC(1000)],
188 1! [UAFC(1000)], [UANC(1000)], [UAGC(30,33)], [AAFC(1000)],
189 1! [AANC(1000)], [AAGC(30,33)], [KL11(30,33)], [KU11(30,33)],
190 1! [R11DPL], [R11PAL(30,33)], [R1112(30,33)],
191 1! [R1113(30,33)], [UAL];
192 1!IMATRIX [AJJTL], [QJUL], [QKUL], [QHHL], [AJK],
193 1! [AJC], [SCNTLG], [SCNTLK], [ACNTLK], [ACNTLG],
194 1! [QGK], [LMODEG], [LMODEK], [AJL];
195 1!$
196 1!$*****
197 1!$ DYNAMIC RESPONSE DECLARATIONS
198 1!$*****
199 1!$
200 1!INTEGER HSIZE(1000);
201 1!UNSTRUCT TFDATA, ICDATA, UDLOLY;
202 1!RELATION LAMBDA, OEIGS, DLONLY, DLOAD, TABLED1,
203 1! IC, TLOAD1, TLOAD2, RLOAD1, RLOAD2,
204 1! TSTEP, VSDAMP, TABDMP1, DLAGS, TF,
205 1! DMIG, GUST, FREQ, FREQ1, FREQ2,
206 1! FFT, FLUTREL;
207 1!IMATRIX [PHIKH], [QHJL], [QKJL], [PHIA], [MII],
208 1! [PHIO], [PHIF], [PHIN], [PHIG(1000)], [KHHT],
209 1! [KHFF], [BHH], [MHH], [PDT], [PDF],
210 1! [KDDT], [KDDF], [BDD], [MDD], [ICMATRIX],
211 1! [UTRANA], [UFREQA], [UTRANI], [UFREQI], [UFREQE],
212 1! [UTRANE], [UTRANF], [UTRANQ], [UTRANN], [UFREQN],
213 1! [UTRANG], [UFREQG], [MHHFL(30,33)], [BHHFL(30,33)],
214 1! [QHHLFL(30,33)], [KHHFL(30,33)];
215 1!$
216 1!$*****
217 1!$ DECLARATIONS FOR GENERALIZED DYNAMIC REDUCTION (GDR)
218 1!$*****
219 1!$
220 1!INTEGER LKSET, LJSET, NEIV, GNORM, NGDR,
221 1! ASIZE, LSIZE;
222 1!REAL FMAX;
223 1!RELATION DYNRED;
224 1!IMATRIX [PGDRG(1000)], [PHIOK], [KOO], [GGO], [KSOO],
225 1! [KOA], [LSOO], [PAJK], [PFJK], [UFGDR],
226 1! [AFGDR], [UJK], [GTMP];

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227 1!$
228 1!$*****$!
229 1!$ BLAST RESPONSE DECLARATIONS $!
230 1!$*****$!
231 1!$ $!
232 1!REAL BQDP; $!
233 1!MATRIX [MPART], [ID2], [PHIE], [PHIR], [PHIB], $!
234 1! [GENM], [GENK], [GENF], [GENQ], [GENQL], $!
235 1! [DTSLP], [FTF], [QRE], [QEE], [KEQE], $!
236 1! [LKQ], [UKQ], [GFR], [GFE], [BTEM], $!
237 1! [BLSTJA], [BLGTJA], [BFRC], [MATTR], [MATSS], $!
238 1! [KEE], [DELB], [DELM], [URDB], [GENFA], $!
239 1! [DWNWSH], [ELAS], [SLPMOD], [QRR], [UBLASTI], $!
240 1! [UBLASTG], [UBLASTF]; $!
241 1!$ $!
242 1!$*****$!
243 1!$ $!
244 1!$ BEGIN MAPOL SOLUTION SEQUENCE $!
245 1!$ $!
246 1!$*****$!
247 1!$ PREFACE MODULES $!
248 1!$*****$!
249 1!SINGOSET := 1; $!
250 1!SINGASET := 2; $!
251 1!SINGLSET := 3; $!
252 1!$*****$!
253 1!$ $!
254 1!$ INITIALIZE SUBSCRIPT VALUES TO "1" TO AVOID RUN TIME PROBLEMS $!
255 1!$ $!
256 1!$*****$!
257 1!SUB := 1; $!
258 1!PRINT("LOG=('BEGIN PREFACE MODULES')"); $!
259 1!CALL SOLUTION ( NUMOPTBC, NBNDCOND, MPS, MPE, OCS, OCE, FSDE, FSDE, $!
260 1! MAXITER, MOVLIM, WINDOW, OCMOVLIM, ALPHA, CNVRGLIM, $!
261 1! NREAC, EPS ); $!
262 1!CALL IFP ( GSIZEB ); $!
263 1!$*****$!
264 1!$ TRY USING A UTILITY TO PRINT OUT THE GRID RELATIONAL ENTITY $!
265 1!$ $!
266 1!$ GENERATE THE ELEMENT MATRICES $!
267 1!$ $!
268 1!$*****$!
269 1!PRINT("LOG=('ELEMENT MATRIX GENERATION')"); $!
270 1!$*****$!
271 1!$ $!
272 1!$*****$!
273 1!CALL MAKEST ( NDV, GLBDES, [PTRANS], [PMINT], [PMAXT], LOCLVAR, $!
274 1! TFIXED, DESLINK ); $!
275 1!$*****$!
276 1!$ $!
277 1!$*****$!
278 1!CALL EMG ( NDV, GSIZEB, GLBDES, DESLINK, [SMAT], DVCT, DVSIZE, $!
279 1! KELM, MELM, TELM, TREF ); $!
280 1!CALL PFBULK ( GSIZEB, EOSUMMRY, EODISC, GPFELEM ); $!
281 1!$*****$!
282 1!$ HANDLE THE NON-PLANAR STEADY AERODYNAMICS ANALYSES $!
283 1!$ TERMINATE THE EXECUTION IF THE ONLY DISCIPLINE IS NPSAERO $!
284 1!$ $!
285 1!$PRINT("LOG=('NON-PLANAR STEADY AERODYNAMICS')"); $!
286 1!$CALL STEADYNP ( NONPONLY, AECOMPS, GEOMSA, STABCT, [AIRFORCE], AEROGEOM, $!
287 1!$ CAROGEOM, OAGRDLOD ); $!
288 1!$IF NONPONLY CALL EXIT; $!
289 1!$ $!
290 1!$ ASSEMBLE THE ELEMENT MATRICES $!
291 1!$ TO THE SENSITIVITY MATRICES $!
292 1!$ $!
293 1!$*****$!
294 1!PRINT("LOG=('PHASE 1 ELEM. MATRIX ASSEMBLY')"); $!
295 1!CALL EMAL ( NDV, GLBDES, DVCT, KELM, MELM, GMKCT, DKVI, GMMCT, DMVI ); $!
296 1!$*****$!
297 1!$ GENERATE THE SIMPLE LOAD VECTORS $!
298 1!$ AND LOAD SENSITIVITIES $!
299 1!$ $!
300 1!$*****$!
301 1!PRINT("LOG=('PHASE 1 STATIC LOADS GENER.')"); $!
302 1!CALL LODGEN ( GSIZEB, GLBDES, DVCT, DVSIZE, GMMCT, DMVI, TELM, TREF, $!
303 1! SMPLOD, [DPGRVI] ); $!
304 1!$*****$!
305 1!$ $!
306 1!$ GENERATE THE STEADY AIC MATRIX AND THE $!
307 1!$ STEADY SPLINE TRANSFORMATION MATRICES $!

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308 1!$
309 1!$PRINT("LOG=('STEADY AERODYNAMICS')");
310 1!$LOOP := TRUE;
311 1!$MINDEX := 0;
312 1!$WHILE LOOP DO
313 1!$ MINDEX := MINDEX + 1;
314 1!$ CALL STEADY ( MINDEX, LOOP, AECOMPS, GEOMSA, STABCF, [AICMAT(MINDEX)],
315 1!$ [AAICMAT(MINDEX)], [AIRFC(MINDEX)], AEROGEO, CAROGEOM );
316 1!$ENDDO;
317 1!$CALL SPLINES ( GSIZEB, GEOMSA, AECOMPS, AEROS, [GTKG], [GSTKG] );
318 1!$
319 1!$ GENERATE THE UNSTEADY AIC MATRIX AND THE
320 1!$ UNSTEADY SPLINE TRANSFORMATION MATRIX
321 1!$
322 1!$PRINT("LOG=('UNSTEADY AERODYNAMICS')");
323 1!$CALL UNSTEADY ( GEOMUA, AECOMPU, [AJJTL], [D1JK], [D2JK], [SKJ],
324 1!$ AERUGEOM, CAROUGEOM );
325 1!$CALL AMP ( [AJJTL], [D1JK], [D2JK], [SKJ], [QKGL], [QJTL], [QJL] );
326 1!$CALL SPLINEU ( GSIZEB, GEOMUA, AECOMPU, AERO, [UGTKG] );
327 1!$*****
328 1!$
329 1!$ ZAERO MODULE P. C. CHEN 3-28-1997
330 1!$
331 1!$*****
332 1!$*****
333 1!$PRINT("LOG=('ZAERO AERODYNAMIC GEOMETRY')");
334 1!$PRINT("LOG=('ZAERO AERODYNAMIC GEOMETRY')");
335 1!$*****
336 1!$ CALL AEROGM MODULE
337 1!$ FOR BOTH STEADY AND UNSTEADY GEOMETRY GENERATIONS
338 1!$*****
339 1!$CALL AEROGM ( AECOMPE, GEOMZA, AGRIDZ );
340 1!$*****
341 1!$PRINT("LOG=('ZAERO CONTROL MODE MODULE ')");
342 1!$PRINT("LOG=('ZAERO CONTROL MODE MODULE ')");
343 1!$*****
344 1!$CALL CONMOD ( GEOMZA, AECOMPE, [SCNTLG], [SCNTLK], [ACNTLG], [ACNTLK], [LMODEG],
345 1!$ [LMODEK] );
346 1!$*****
347 1!$PRINT("LOG=('ZAERO SPLINE MODULE ')");
348 1!$PRINT("LOG=('ZAERO SPLINE MODULE ')");
349 1!$*****
350 1!$CALL SPLINZ ( GSIZEB, GEOMZA, AECOMPE, AEROZ, [UGTKG] );
351 1!$*****
352 1!$*****
353 1!$ CALL ZAEROM MODULE
354 1!$ FOR BOTH STEADY AND UNSTEADY AIC GENERATIONS
355 1!$*****
356 1!$PRINT("LOG=('ZAERO UNSTEADY AERODYNAMICS ')");
357 1!$PRINT("LOG=('ZAERO UNSTEADY AERODYNAMICS ')");
358 1!$CALL ZUAERO ( AECOMPE, GEOMZA, AGRIDZ, [AJK], [AJC], [AJL], [QKG],
359 1!$ [SKJ], [SCNTLK], [ACNTLK], [LMODEK] );
360 1!$PRINT("LOG=('ZAERO STEADY AERODYNAMICS')");
361 1!$PRINT("LOG=('ZAERO STEADY AERODYNAMICS')");
362 1!$LOOP := TRUE;
363 1!$MINDEX := 0;
364 1!$WHILE LOOP DO
365 2! MINDEX := MINDEX + 1;
366 2! CALL SZAERO ( [AJK], MINDEX, LOOP, AECOMPE, GEOMZA, AGRIDZ, STABCF,
367 2! [AICMAT(MINDEX)], [AAICMAT(MINDEX)], [AIRFC(MINDEX)],
368 2! [SCNTLK], [ACNTLK] );
369 2!ENDDO;
370 1!$*****
371 1!$
372 1!$*****
373 1!$ BEGIN OPTIMIZATION LOOP
374 1!$*****
375 1!$
376 1!$IF NUMOPTBC > 0 THEN
377 2! PRINT("LOG=('*****')");
378 2! PRINT("LOG=('BEGIN OPTIMIZATION')");
379 2!$
380 2!$ INITIALIZE MAPOL PARAMETERS
381 2!$
382 2! GLBCNVRG := FALSE;
383 2! APPCNVRG := FALSE;
384 2!$
385 2!$ BEGIN CONVERGENCE LOOP
386 2!$
387 2! WHILE NOT GLBCNVRG AND NITER <= MAXITER DO
388 3!$

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389 3!$ ASSEMBLE THE GLOBAL MATRICES $!
390 3!$ $!
391 3! NITER := NITER + 1; !
392 3! PRINT("LOG=('------')"); !
393 3! PRINT("LOG=(' DESIGN ITERATION ',I3)",NITER); !
394 3! CALL ITERINIT ( NITER, CONST ); !
395 3! CALL UTMPRG ( [GLBSIG] ); !
396 3! CALL TCEVAL ( NITER, NDV, MOVLIM, WINDOW, GLBDES, LOCLVAR, [PMINT], !
397 3! [PMAXT], TFIXED, CONST ); !
398 3! CALL LAMINCON ( NITER, NDV, DCONLAM, DCONLMN, DCONPMN, TFIXED, GLBDES, !
399 3! LOCLVAR, [PTRANS], CONST ); !
400 3! CALL EMA2 ( NITER, NDV, GSIZEB, GLBDES, GMKCT, DKVI, [K1GG], !
401 3! GMCT, DMVI, [M1GG] ); !
402 3!$ $!
403 3!$ BEGIN BOUNDARY CONDITION LOOP FOR OPTIMIZATION $!
404 3!$ $!
405 3! FOR BC = 1 TO NUMOPTBC DO !
406 4! PRINT("LOG=(' BOUNDARY CONDITION ',I3)",BC); !
407 4!$ $!
408 4!$ ESTABLISH THE BASE USET AND PARTITIONING DATA FOR THE BC $!
409 4!$ THIS DATA MUST BE RECREATED EACH ITERATION SINCE GDR CAN CHANGE IT $!
410 4!$ $!
411 4! CALL MKUSET( BC, GSIZEB, [YS(BC)], [TMN(BC)], [PGMN(BC)], [PNSF(BC)], !
412 4! [PFOA(BC)], [PARL(BC)], USET(BC) ); !
413 4!$ $!
414 4!$ MAKE B.C.-DEPENDENT BGPDT FROM BASE, ADDING THE EXTRA POINTS FOR $!
415 4!$ THIS B.C. $!
416 4!$ $!
417 4! CALL BCBGPD( BC, GSIZEB, BGPDT(BC), ESIZE(BC) ); !
418 4! GSIZE := GSIZEB; !
419 4! PSIZE(BC) := ESIZE(BC) + GSIZE; !
420 4!$ $!
421 4!$ PROCESS MATRICES, TRANSFER FUNCTIONS, AND INITIAL CONDITIONS FOR $!
422 4!$ THIS B.C. $!
423 4!$ $!
424 4! CALL BCBULK( BC, PSIZE(BC), BGPDT(BC), USET(BC) ); !
425 4!$ $!
426 4! CALL BOUND ( BC, GSIZE, ESIZE(BC), USET(BC), BLOAD, BMASS, DMOES, !
427 4! BMOES, BSAERO, BELUTR, BDYN, BDRSP, BDTR, BMTR, BDFR, !
428 4! BMFR, BGUST, BBLAST, NMPC, NSPC, NOMIT, NRSET, NGDR ); !
429 4!$ $!
430 4!$ DETERMINE IF ANY M2GG/K2GG INPUT DATA ARE TO BE ADDED $!
431 4!$ $!
432 4! CALL NULLMAT ( [KGG], [MGG] ); !
433 4! CALL MK2GG ( BC, GSIZEB, [M2GG], M2GGFLAG, [K2GG], K2GGFLAG ); !
434 4! IF M2GGFLAG THEN !
435 5! [MGG] := [M1GG] + [M2GG]; !
436 5! ELSE !
437 5! [MGG] := [M1GG]; !
438 5! ENDIF; !
439 4! IF K2GGFLAG THEN !
440 5! [KGG] := [K1GG] + [K2GG]; !
441 5! ELSE !
442 5! [KGG] := [K1GG]; !
443 5! ENDIF; !
444 4!$ $!
445 4!$ CALL THE GRID POINT WEIGHT GENERATOR FOR THIS BOUNDARY CONDITON $!
446 4!$ $!
447 4! CALL GPWG ( NITER, BC, GPWGGRID, [MGG], OGPWG ); !
448 4!$ $!
449 4! IF BLOAD <> 0 CALL GTLOAD (NITER, BC, GSIZE, BGPDT(BC), GLBDES, !
450 5! SMPLD, [DPHVI], [DPGRVI], [PG], OGRIDLOD); !
451 4!$ $!
452 4!$ PARTITION-REDUCTION OF GLOBAL MATRICES $!
453 4!$ $!
454 4!$***** TAKEN OUT FOR ZAERO *****$! <-
455 4!$ IF NUMOPTBC > 1 CALL NULLMAT ( [KNN], [PN], [MNN], !
456 4!$ [GTKN], [GSTKN], [UGTKN] ); !
457 4!$*****$!
458 4! IF NUMOPTBC > 1 CALL NULLMAT ( [KNN], [PN], [MNN], [UGTKN] ); ! <-
459 4! IF NMPC <> 0 THEN !
460 5!$ $!
461 5!$ PERFORM MPC REDUCTION $!
462 5!$ $!
463 5! PRINT("LOG=(' MPC REDUCTION'"); !
464 5! CALL GREduce ( [KGG], [PG], [PGMN(BC)], [TMN(BC)], [KNN], [PN] ); !
465 5! IF BMASS <> 0 CALL GREduce ( [MGG], [PGMN(BC)], [TMN(BC)], [MNN] ); !
466 5!$***** TAKEN OUT FOR ZAERO *****$! <-
467 5!$ IF BSAERO <> 0 THEN !
468 5!$ CALL GREduce (, [GTKG], [PGMN(BC)], [TMN(BC)],, [GTKN]); !
469 5!$ CALL GREduce (, [GSTKG], [PGMN(BC)], [TMN(BC)],, [GSTKN]); $!

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470 5!$          ENDIF;                                     $!
471 5!$*****                                     $!
472 5!          IF BFLUTR <> 0 OR BGUST <> 0 OR BELAST <> 0 OR BSAERO <> 0      ! ←
473 6!          CALL GREduce (, [UGTKG], [PGMN(BC)], [TMN(BC)], , [UGTKN] );    !
474 5!          ELSE                                         !
475 5!$          NO MPC REDUCTION                             $!
476 5!$          NO MPC REDUCTION                             $!
477 5!$          NO MPC REDUCTION                             $!
478 5!          [KNN] := [KGG];                             !
479 5!          IF BLOAD <> 0 [PN] := [PG];                     !
480 5!          IF BMAS <> 0 [MNN] := [MGG];                     !
481 5!$***** TAKEN OUT FOR ZAERO *****$! ←
482 5!$          IF BSAERO <> 0 THEN                             $!
483 5!$          [GTKN] := [GTKG];                             $!
484 5!$          [GSTKN] := [GSTKG];                          $!
485 5!$          ENDIF;                                       $!
486 5!$*****                                     $!
487 5!          IF BFLUTR <> 0 OR BGUST <> 0 OR BELAST <> 0 OR BSAERO <> 0      !
488 6!          [UGTKN] := [UGTKG];                          ! ←
489 5!          ENDIF;                                       !
490 4!$          PERFORM AUTOSPC CALCULATIONS ON THE KNN MATRIX      $!
491 4!$          PERFORM AUTOSPC CALCULATIONS ON THE KNN MATRIX      $!
492 4!$          PERFORM AUTOSPC CALCULATIONS ON THE KNN MATRIX      $!
493 4!          PRINT("LOG=('          AUTOSPC COMPUTATIONS')");    !
494 4!          CALL GPSP ( NITER, BC, NGDR, [KNN], BGPDT(BC), [YS(BC)],    !
495 4!          USET(BC), GPST(BC) );                          !
496 4!          CALL MKPVECT ( USET(BC), [PGMN(BC)], [PNSF(BC)],    !
497 4!          [PFOA(BC)], [PARL(BC)] );                      !
498 4!          CALL BOUNDUPD ( BC, GSIZE, ESIZE(BC), USET(BC), NSPC, NOMIT, NRSET ); !
499 4!$          FOR SENSITIVITY ANALYSIS, SAVE A COPY OF THE PRE-GDR PART. VECTS. $!
500 4!$          FOR SENSITIVITY ANALYSIS, SAVE A COPY OF THE PRE-GDR PART. VECTS. $!
501 4!$          FOR SENSITIVITY ANALYSIS, SAVE A COPY OF THE PRE-GDR PART. VECTS. $!
502 4!          CALL MKPVECT ( USET(BC), [PGMNS(BC)], [PNSFS(BC)],    !
503 4!          [PFOAS(BC)], [PARLS(BC)] );                  !
504 4!$          PERFORM SPC REDUCTION                             $!
505 4!$***** TAKEN OUT FOR ZAERO *****$! ←
506 4!$          IF NUMOPTBC > 1 CALL NULLMAT ( [KFF], [PF], [MFF], [GTKF], [GSTKF], $!
507 4!$          [UGTKF] );                                     $!
508 4!$*****                                     $!
509 4!          IF NUMOPTBC > 1 CALL NULLMAT ( [KFF], [PF], [MFF], [UGTKF] );    ! ←
510 4!          IF NSPC <> 0 THEN                                     !
511 5!$          PERFORM SPC REDUCTION                             $!
512 5!$          PERFORM SPC REDUCTION                             $!
513 5!$          PERFORM SPC REDUCTION                             $!
514 5!          PRINT("LOG=('          SPC REDUCTION')");          !
515 5!          CALL NREDUCE ( [KNN], [PN], [PNSF(BC)], [YS(BC)], [KFF], [KFS],    !
516 5!          [KSS], [PF], [PS] );                          !
517 5!          IF BMAS <> 0 CALL NREDUCE ( [MNN], , [PNSF(BC)], , [MFF] );    !
518 5!$***** TAKEN OUT FOR ZAERO *****$! ←
519 5!$          IF BSAERO <> 0 THEN                             $!
520 5!$          CALL NREDUCE ( , [GTKN], [PNSF(BC)], , , , [GTKF] );    $!
521 5!$          CALL NREDUCE ( , [GSTKN], [PNSF(BC)], , , , [GSTKF] );    $!
522 5!$          ENDIF;                                       $!
523 5!$*****                                     $!
524 5!          IF BFLUTR <> 0 OR BGUST <> 0 OR BELAST <> 0 OR BSAERO <> 0      ! ←
525 6!          CALL NREDUCE (, [UGTKN], [PNSF(BC)], , , , [UGTKF] );    !
526 5!          ELSE                                         !
527 5!$          NO SPC REDUCTION                             $!
528 5!$          NO SPC REDUCTION                             $!
529 5!$          NO SPC REDUCTION                             $!
530 5!          [KFF] := [KNN];                             !
531 5!          IF BLOAD <> 0 [PF] := [PN];                     !
532 5!          IF BMAS <> 0 [MFF] := [MNN];                     !
533 5!$***** TAKEN OUT FOR ZAERO *****$! ←
534 5!$          IF BSAERO <> 0 THEN                             $!
535 5!$          [GTKF] := [GTKN];                             $!
536 5!$          [GSTKF] := [GSTKN];                          $!
537 5!$          ENDIF;                                       $!
538 5!$*****                                     $!
539 5!          IF BFLUTR <> 0 OR BGUST <> 0 OR BELAST <> 0 OR BSAERO <> 0      !
540 6!          [UGTKF] := [UGTKN];                          ! ←
541 5!          ENDIF;                                       !
542 4!$          IF NUMOPTBC > 1 CALL NULLMAT ( [KAA], [PA], [MAA],    $!
543 4!$          [KAAA], [PAA], [UGTKA] );                  !
544 5!$          IF NGDR <> 0 THEN                                     !
545 4!$          IF NGDR <> 0 THEN                                     !
546 4!          IF NGDR <> 0 THEN                                     !
547 5!$          PERFORM THE GENERAL DYNAMIC REDUCTION WHICH IS DISCIPLINE    $!
548 5!$          INDEPENDENT. THE RESULTING [GSUBO] MATRIX WILL BE USED BY    $!
549 5!$          ALL DISCIPLINES                                     $!
550 5!$          ALL DISCIPLINES                                     $!

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551 5!$ PRINT("LOG=(' DYNAMIC REDUCTION')");
552 5!$
553 5!$ OBTAIN THE OMITTED DOF PARTITION OF KFF AND MFF
554 5!$
555 5!$ CALL PARTN ( [KFF], [KOO], , [KOA], , [PFOA(BC)] );
556 5!$ CALL PARTN ( [MFF], [MOO], , , [PFOA(BC)] );
557 5!$ ASIZE := GSIZE - NMPC - NSPC - NOMIT;
558 5!$ LSIZE := ASIZE - NRSET;
559 5!$ CALL GDR1 ( [KOO], [MOO], [KSOO], [GGO], LKSET, LJSET, NEIV,
560 5!$ FMAX, BC, BGPDT(BC), USET(BC), NOMIT, LSIZE );
561 5!$
562 5!$ LKSET MEANING
563 5!$ <> 0 APPROX. MODE SHAPES SELECTED
564 5!$ = 0 NO APPROX. MODE SHAPES IN GDR
565 5!$
566 5!$ IF LKSET <> 0 THEN
567 5!$ CALL SDCOMP ( [KSOO], [LSOO], USET(BC), SINGOSET );
568 5!$ CALL GDR2 ( [LSOO], [MOO], [PHIOK], LKSET, LJSET,
569 5!$ NEIV, FMAX, BC );
570 5!$
571 5!$ ENDIF;
572 5!$ CALL GDR3 ( [KOO], [KOA], [MGG], [PHIOK], [TMN(BC)], [GGO],
573 5!$ [PGMN(BC)], [PNSF(BC)], [PFOA(BC)], [GSUBO(BC)],
574 5!$ BGPDT(BC), USET(BC),
575 5!$ LKSET, LJSET, ASIZE, GNORM, BC );
576 5!$ CALL GDR4 ( BC, GSIZE, PSIZE(BC), LKSET, LJSET, NUMOPTBC, NBNDCOND,
577 5!$ [PGMN(BC)], [TMN(BC)], [PNSF(BC)], [PFOA(BC)],
578 5!$ [PARL(BC)], [PGDRG(BC)], [PAJK], [PFJK], BGPDT(BC),
579 5!$ USET(BC) );
580 5!$
581 4!$ ENDIF;
582 4!$ IF BLOAD <> 0 OR BMODES <> 0 OR BFLUTR <> 0 OR BDN <> 0 THEN
583 5!$
584 5!$ REDUCE THE MATRICES WITHOUT AEROELASTIC CORRECTIONS
585 5!$
586 5!$ IF NGDR <> 0 THEN
587 5!$
588 5!$ PERFORM THE GENERAL DYNAMIC REDUCTION
589 5!$
590 5!$ PRINT("LOG=(' SYMMETRIC DYNAMIC REDUCTION')");
591 5!$
592 5!$ [MAA] := TRANS ( [GSUBO(BC)] ) * [ [MFF] * [GSUBO(BC)] ];
593 5!$ [KAA] := TRANS ( [GSUBO(BC)] ) * [ [KFF] * [GSUBO(BC)] ];
594 5!$ IF BLOAD <> 0 [PA] := TRANS ( [GSUBO(BC)] ) * [PF];
595 5!$ IF BFLUTR <> 0 OR BGUST <> 0 OR BBLAST <> 0 THEN
596 5!$ [TMP1] := TRANS ( [UGTKF] ) * [GSUBO(BC)];
597 5!$ CALL TRNPOSE ( [TMP1], [UGTKA] );
598 5!$ ENDIF;
599 5!$ ELSE
600 5!$ IF NOMIT <> 0 THEN
601 5!$
602 5!$ PERFORM THE STATIC REDUCTION
603 5!$
604 5!$ PRINT("LOG=(' STATIC CONDENSATION')");
605 5!$
606 5!$ CALL FREDUCE ( [KFF], [PF], [PFOA(BC)], , [KOOINV(BC)], ,
607 5!$ [GSUBO(BC)], [KAA], [PA], [PO], USET(BC) );
608 5!$
609 5!$ IF BMAS <> 0 THEN
610 5!$
611 5!$ PERFORM GUYAN REDUCTION OF THE MASS MATRIX
612 5!$
613 5!$ CALL PARTN ( [MFF], [MOO], , [MOA], [MAABAR], [PFOA(BC)] );
614 5!$ [MAA] := [MAABAR] + TRANS([MOA]) * [GSUBO(BC)] +
615 5!$ TRANS([GSUBO(BC)]) * [MOA] +
616 5!$ TRANS([GSUBO(BC)]) * [ [MOO] * [GSUBO(BC)] ];
617 5!$ IF NRSET <> 0 [IFM(BC)] := [MOO] * [GSUBO(BC)] + [MOA];
618 5!$ ENDIF;
619 5!$ IF BFLUTR <> 0 OR BGUST <> 0 OR BBLAST <> 0 THEN
620 5!$ CALL ROWPART ( [UGTKF], [UGTKO], [UGTKAB], [PFOA(BC)] );
621 5!$ [TMP1] := TRANS ( [UGTKO] ) * [GSUBO(BC)];
622 5!$ CALL TRNPOSE ( [TMP1], [TMP2] );
623 5!$ [UGTKA] := [UGTKAB] + [TMP2];
624 5!$ ENDIF;
625 5!$ ELSE
626 5!$
627 5!$ NO F-SET REDUCTION
628 5!$
629 5!$ [KAA] := [KFF];
630 5!$ IF BLOAD <> 0 [PA] := [PF];
631 5!$ IF BFLUTR <> 0 OR BGUST <> 0 OR BBLAST <> 0 [UGTKA] := [UGTKF];

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632 7!          IF BMASS <> 0 [MAA] := [MFF];
633 7!          ENDIF;
634 6!          ENDIF;
635 5!$
636 5!          IF NRSET <> 0 THEN
637 6!$
638 6!$          PERFORM THE SUPPORT SET REDUCTION
639 6!$
640 6!          PRINT("LOG=('          SUPPORT REDUCTION')");
641 6!          IF NITER = 1 THEN
642 7!              CALL PARTN ( [KAA], [KRR], [KLR], , [KLL], [PARL(BC)] );
643 7!              CALL SDCOMP ( [KLL], [KLLINV(BC)], USET(BC), SINGLSET );
644 7!              CALL FBS ( [KLLINV(BC)], [KLR], [D(BC)], -1 );
645 7!              CALL RBCHECK ( BC, USET(BC), BGPDT(BC), [D(BC)], [KLL],
646 7!                  [KRR], [KLR] );
647 7!          ELSE
648 7!              IF BLOAD <> 0 THEN
649 8!                  CALL PARTN ( [KAA], , [KLR], , [KLL], [PARL(BC)] );
650 8!                  CALL SDCOMP ( [KLL], [KLLINV(BC)], USET(BC), SINGLSET );
651 8!              ENDIF;
652 7!          ENDIF;
653 6!$
654 6!$          CALCULATE THE REDUCED MASS MATRIX
655 6!$
656 6!          CALL PARTN ([MAA], [MRRBAR], [MLR], , [MLL], [PARL(BC)]);
657 6!          [IFR(BC)] := [MLL] * [D(BC)] + [MLR];
658 6!          [MRR(BC)] := [MRRBAR] + TRANS ( [MLR] ) * [D(BC)] +
659 6!              TRANS ( [D(BC)] ) * [IFR(BC)];
660 6!          [R22] := TRANS ( [D(BC)] ) * [MLR] + [MRRBAR];
661 6!$
662 6!          IF BLOAD <> 0 THEN
663 7!$
664 7!$          PROCESS STATICS WITH INERTIA RELIEF
665 7!$
666 7!          PRINT(
667 7!              "LOG=('          >>>DISCIPLINE: STATICS(INERTIA RELIEF)')");
668 7!          CALL ROWPART ( [PA], [PR], [PLBAR], [PARL(BC)] );
669 7!          [LHS(BC)] := [MRR(BC)];
670 7!          [RHS(BC)] := TRANS([D(BC)]) * [PLBAR] + [PR];
671 7!          CALL INERTIA ( [LHS(BC)], [RHS(BC)], [AR] );
672 7!          [AL] := [D(BC)] * [AR];
673 7!          CALL ROWMERGE ( [AA], [AR], [AL], [PARL(BC)] );
674 7!          [RHS(BC)] := [PLBAR] - [IFR(BC)] * [AR];
675 7!          CALL FBS ( [KLLINV(BC)], [RHS(BC)], [UL] );
676 7!          CALL YSMERGE ( [UA], , [UL], [PARL(BC)] );
677 7!          ENDIF;
678 6!          IF BMODES <> 0 THEN
679 7!              PRINT("LOG=('          >>>DISCIPLINE: NORMAL MODES')");
680 7!              CALL REIG ( NITER, BC, USET(BC), [KAA], [MAA], [MRR(BC)],
681 7!                  [D(BC)], LAMBDA, [PHIA], [MII], HSIZE(BC) );
682 7!              CALL OFFPMROOT ( NITER, BC, NUMOPTBC, LAMBDA );
683 7!              CALL FCEVAL ( NITER, BC, LAMBDA, CONST );
684 7!          ENDIF;
685 6!          ELSE
686 6!$
687 6!$          NO SUPPORT SET REDUCTION
688 6!$
689 6!          IF BLOAD <> 0 THEN
690 7!              PRINT("LOG=('          >>>DISCIPLINE: STATICS')");
691 7!              CALL SDCOMP ( [KAA], [KLLINV(BC)], USET(BC), SINGASET );
692 7!              CALL FBS ( [KLLINV(BC)], [PA], [UA] );
693 7!          ENDIF;
694 6!          IF BMODES <> 0 THEN
695 7!              PRINT("LOG=('          >>>DISCIPLINE: NORMAL MODES')");
696 7!              CALL REIG ( NITER, BC, USET(BC), [KAA], [MAA], , , LAMBDA,
697 7!                  [PHIA], [MII], HSIZE(BC) );
698 7!              CALL OFFPMROOT ( NITER, BC, NUMOPTBC, LAMBDA );
699 7!              CALL FCEVAL ( NITER, BC, LAMBDA, CONST );
700 7!          ENDIF;
701 6!          ENDIF;
702 5!          ENDIF;
703 4!          IF BSAERO <> 0 THEN
704 5!$
705 5!$          PERFORM STATIC AEROELASTIC ANALYSES
706 5!$
707 5!          PRINT("LOG=('          SAERO INITIALIZATION')");
708 5!$***** TAKEN OUT FOR LAERO *****$!
709 5!$          CALL TRNPOSE ( [GSTKF], [GSKF] );
710 5!$*****$!
711 5!          CALL TRNPOSE ( [UGTKF], [GSKF] );
712 5!          LOOP := TRUE;

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713 5! SUB := 0;
714 5! WHILE LOOP DO
715 6! SUB := SUB + 1;
716 6! CALL SAERODRV (BC, SUB, LOOP, MINDEX, SYM, MACH, QDP, 1);
717 6!$
718 6!$ ADJUST THE KFF MATRIX AND DETERMINE THE RIGID AIR LOADS
719 6!$
720 6!$***** TAKEN OUT FOR LAERO *****$!
721 6!$ IF SYM = 1 [AICS] := [GTKF]*[TRANS([AICMAT(MINDEX)])]*[GSKF]; $!
722 6!$ IF SYM = -1 [AICS] := [GTKF]*[TRANS([AAICMAT(MINDEX)])]*[GSKF]; $!
723 6!$*****$!
724 6!$ IF SYM = 1 [AICS] := [UGTKF]*[TRANS([AICMAT(MINDEX)])]*[GSKF]; $!
725 6!$ IF SYM = -1 [AICS] := [UGTKF]*[TRANS([AAICMAT(MINDEX)])]*[GSKF]; $!
726 6!$ [PAF] := (QDP) [UGTKF] * [AIRPRC(MINDEX)];
727 6!$ [KAFF] := [KFF] - (QDP) [AICS];
728 6!$
729 6!$ REDUCE THE MATRICES WITH AEROELASTIC CORRECTIONS
730 6!$ SAVE THE SUBCASE/BC DEPENDENT DATA FOR SENSITIVITY ANALYSIS
731 6!$
732 6!$ IF NGDR <> 0 THEN
733 7!$
734 7!$ PERFORM THE GENERAL DYNAMIC REDUCTION
735 7!$
736 7!$ PRINT("LOG=(' SAERO DYNAMIC REDUCTION')");
737 7!$ [MAAA] := TRANS ([GSUBO(BC)] ) * [ [MFF] * [GSUBO(BC)] ];
738 7!$ [KAAA] := TRANS ([GSUBO(BC)] ) * [ [KAFF] * [GSUBO(BC)] ];
739 7!$ [PAA] := TRANS ([GSUBO(BC)] ) * [PAF];
740 7!$ ELSE
741 7!$ IF NOMIT <> 0 THEN
742 8!$
743 8!$ PERFORM THE STATIC REDUCTION
744 8!$
745 8!$ PRINT("LOG=(' SAERO STATIC CONDENSATION')");
746 8!$
747 8!$ IF NITER = 1 AND SUB = 1 AND NRSET <> 0 AND BLOAD = 0 AND
748 9!$ BMODES = 0 AND BFLUTR = 0 AND BDYN = 0 THEN
749 9!$
750 9!$ FORM [KAA] ON FIRST PASS SO [D] CAN BE FORMED
751 9!$
752 9!$ CALL FREDUCE ([KFF], , [PFOA(BC)], , [KOOINV(BC)], ,
753 9!$ [GSUBO(BC)], [KAA], , , USET(BC) );
754 9!$
755 8!$ ENDIF;
756 8!$ CALL FREDUCE ( [KAFF], [PAF], [PFOA(BC)], BSAERO,
757 8!$ [KOOL(BC,SUB)], [KOOV(BC,SUB)],
758 8!$ [KAO(BC,SUB)], [GASUBO(BC,SUB)], [KAAA],
759 8!$ [PAA], [POARO(BC,SUB)], USET(BC));
760 8!$
761 8!$ IF BMAS <> 0 THEN
762 9!$
763 9!$ PERFORM GUYAN REDUCTION OF THE MASS MATRIX
764 9!$
765 9!$ CALL PARTN ( [MFF], [MOO], , [MOA], [MAABAR],
766 9!$ [PFOA(BC)] );
767 9!$ [MAAA] := [MAABAR] + TRANS([MOA]) * [GASUBO(BC,SUB)] +
768 9!$ TRANS([GASUBO(BC,SUB)]) * [MOA] +
769 9!$ TRANS([GASUBO(BC,SUB)]) * [[MOO] *
770 9!$ [GASUBO(BC,SUB)]];
771 9!$ IF NRSET <> 0
772 10!$ [IFMA(BC,SUB)] := [MOO]*[GASUBO(BC,SUB)]+[MOA];
773 9!$ ENDIF;
774 8!$ ELSE
775 8!$
776 8!$ NO F-SET REDUCTION
777 8!$
778 8!$ IF NITER = 1 AND SUB = 1 AND NRSET <> 0 AND BLOAD = 0 AND
779 9!$ BMODES = 0 AND BFLUTR = 0 AND BDYN = 0 THEN
780 9!$
781 9!$ FORM [KAA] ON FIRST PASS SO [D] CAN BE FORMED
782 9!$
783 9!$ [KAA] := [KFF];
784 9!$ ENDIF;
785 8!$ [KAAA] := [KAFF];
786 8!$ [MAAA] := [MFF];
787 8!$ [PAA] := [PAF];
788 8!$ ENDIF;
789 7!$ ENDIF;
790 6!$
791 6!$ IF NRSET <> 0 THEN
792 7!$
793 7!$ PERFORM THE SUPPORT SET REDUCTION

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794 7!$ PRINT("LOG=(' SAERO SUPPORT REDUCTION')"); $!
795 7!
796 7!$
797 7! IF NITER = 1 AND SUB = 1 AND BLOAD = 0 AND BMODES = 0 AND $!
798 8! BFLUTR = 0 AND BDMN = 0 THEN $!
799 8!$
800 8!$ [D] WAS NOT COMPUTED FOR NON-SAERO DISCIPLINES SO $!
801 8!$ NEED TO COMPUTE IT NOW $!
802 8!$
803 8! CALL PARTN ( [KAA], [KRR], [KLR], , [KLL], [PARL(BC)] ); $!
804 8! CALL SDCOMP ( [KLL], [KLLINV(BC)], USET(BC), SINGLSET ); $!
805 8! CALL FBS ( [KLLINV(BC)], [KLR], [D(BC)], -1 ); $!
806 8! CALL RBCHECK ( BC, USET(BC), BGPDT(BC), [D(BC)], [KLL], $!
807 8! [KRR], [KLR] ); $!
808 8!
809 7!$
810 7!$ CALCULATE THE REDUCED MASS MATRIX $!
811 7!$
812 7! CALL PARTN ([MAAA], [MRRBAR], [MLR], , [MLL], [PARL(BC)]); $!
813 7! [R13(BC,SUB)] := [MLL] * [D(BC)] + [MLR]; $!
814 7! [R33] := [MRRBAR] + TRANS ( [MLR] ) * [D(BC)] + $!
815 7! TRANS ( [D(BC)] ) * [R13(BC,SUB)]; $!
816 7! [R22] := TRANS ( [D(BC)] ) * [MLR] + [MRRBAR]; $!
817 7! CALL TRNPOSE ( [R13(BC,SUB)], [R21(BC,SUB)] ); $!
818 7!$
819 7!$ PROCESS STEADY AEROELASTIC DISCIPLINE $!
820 7!$
821 7! PRINT("LOG=(' >>>DISCIPLINE: STEADY AERO')"); $!
822 7! CALL PARTN ( [KAAA], [KARR], [R12(BC,SUB)], [KARL], [R11], $!
823 7! [PARL(BC)] ); $!
824 7! [R32(BC,SUB)] := TRANS([D(BC)]) * [R12(BC,SUB)] + [KARR]; $!
825 7! [R31(BC,SUB)] := TRANS([D(BC)]) * [R11] + [KARL]; $!
826 7!$
827 7! CALL DECOMP ( [R11], [RL11(BC,SUB)], [RU11(BC,SUB)] ); $!
828 7!$
829 7! CALL ROWPART ( [PAA], [PARBAR], [PAL], [PARL(BC)] ); $!
830 7! CALL GFBS ( [RL11(BC,SUB)], [RU11(BC,SUB)], [PAL], $!
831 7! [R11PAL(BC,SUB)], -1); $!
832 7! [PRIGID] := [PARBAR] + TRANS([D(BC)]) * [PAL]; $!
833 7! [P1] := [R21(BC,SUB)] * [R11PAL(BC,SUB)]; $!
834 7! [P2] := [PRIGID] + [R31(BC,SUB)] * [R11PAL(BC,SUB)]; $!
835 7!$
836 7! CALL GFBS ( [RL11(BC,SUB)], [RU11(BC,SUB)], [R12(BC,SUB)], $!
837 7! [R1112(BC,SUB)], -1); $!
838 7! CALL GFBS ( [RL11(BC,SUB)], [RU11(BC,SUB)], [R13(BC,SUB)], $!
839 7! [R1113(BC,SUB)], -1); $!
840 7! [K11] := [R22] + [R21(BC,SUB)] * [R1112(BC,SUB)]; $!
841 7! [K12(BC,SUB)] := [R21(BC,SUB)] * [R1113(BC,SUB)]; $!
842 7! [K21(BC,SUB)] := [R32(BC,SUB)] + $!
843 7! [R31(BC,SUB)] * [R1112(BC,SUB)]; $!
844 7! [K22] := [R33] + [R31(BC,SUB)] * [R1113(BC,SUB)]; $!
845 7!$
846 7! CALL DECOMP ( [K11], [KL11(BC,SUB)], [KU11(BC,SUB)] ); $!
847 7! CALL GFBS ( [KL11(BC,SUB)], [KU11(BC,SUB)], [P1], $!
848 7! [PAR(BC,SUB)] ); $!
849 7! CALL GFBS ( [KL11(BC,SUB)], [KU11(BC,SUB)], [K12(BC,SUB)], $!
850 7! [K1112(BC,SUB)], -1); $!
851 7! [LHSA(BC,SUB)] := [K22] + [K21(BC,SUB)] * [K1112(BC,SUB)]; $!
852 7! [RHSA(BC,SUB)] := [P2] - [K21(BC,SUB)] * [PAR(BC,SUB)]; $!
853 7!$***** CALL SAERO NOW ! *****$!
854 7! CALL SAERO ( NITER, BC, MINDEX, SUB, SYM, QDP, STABCF, $!
855 7! BGPDT(BC), [LHSA(BC,SUB)], [RHSA(BC,SUB)], [AAR], $!
856 7! [DELTA(SUB)], [PRIGID], [R33], $!
857 7! CONST, AEFLG(SUB), [AARC], [DELC]); $!
858 7!$*****$!
859 7! [AAL] := [D(BC)] * [AAR]; $!
860 7! CALL ROWMERGE ( [AAA(SUB)], [AAR], [AAL], [PARL(BC)] ); $!
861 7! [UAR] := [K1112(BC,SUB)] * [AAR] + [PAR(BC,SUB)] * $!
862 7! [DELTA(SUB)]; $!
863 7! [UAL] := [R1112(BC,SUB)] * [UAR] + [R1113(BC,SUB)] * [AAR] $!
864 7! - [R11PAL(BC,SUB)] * [DELTA(SUB)]; $!
865 7! CALL ROWMERGE ( [UAA(SUB)], [UAR], [UAL], [PARL(BC)] ); $!
866 7! IF NOMIT <> 0 [PAO(SUB)] := [POARO(BC,SUB)] * [DELTA(SUB)]; $!
867 7! IF AEFLG(SUB) THEN $!
868 8! [AAL] := [D(BC)] * [AARC]; $!
869 8! CALL ROWMERGE ( [AAAC(SUB)], [AARC], [AAL], [PARL(BC)] ); $!
870 8! [UAR] := [K1112(BC,SUB)] * [AARC] + [PAR(BC,SUB)] * $!
871 8! [DELC]; $!
872 8! [UAL] := [R1112(BC,SUB)] * [UAR] + $!
873 8! [R1113(BC,SUB)] * [AARC] - $!
874 8! [R11PAL(BC,SUB)] * [DELC]; $!

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875      8!          CALL ROWMERGE ( [UAAC(SUB)], [UAR], [UAL], [PARL(BC)] );
876      8!          IF NOMIT <> 0 [PAOC(SUB)] := [POARO(BC,SUB)]*[DELIC] ;
877      8!          ENDIF;
878      7!          ELSE
879      7!$
880      7!$          NO SUPPORT SET REDUCTION
881      7!$          PROCESS STEADY AEROELASTIC DISCIPLINE
882      7!$
883      7!          PRINT("LOG=('          >>>DISCIPLINE: STEADY AERO')");
884      7!$
885      7!          ENDIF;
886      6!          ENDDO;
887      5!          ENDIF;
888      4!$
889      4!$          PERFORM ANY DYNAMIC ANALYSES -- NOTE THAT THESE ARE INDEPENDENT
890      4!$          OF THE SUPPORT SET
891      4!$
892      4!          IF BDDYN <> 0 THEN
893      5!          IF BFLUTR <> 0 THEN
894      6!          PRINT("LOG=('          >>>DISCIPLINE: FLUTTER')");
895      6!          SUB := 0;
896      6!          LOOP := TRUE;
897      6!          WHILE LOOP DO
898      7!          SUB := SUB + 1;
899      7!          CALL FLUTDRV ( BC, SUB, LOOP );
900      7!          CALL FLUTQHMZ ( NITER, BC, SUB, ESIZE(BC), PSIZE(BC), [AJK],
901      7!          [SKJ],[UGTKA], [PHIA], USET(BC),
902      7!          [TMN(BC)], [GSUBO(BC)], NGDR, AECOMPZ, GEOMZA,
903      7!          [PHIKH], [QHHLFL(BC,SUB)], OAGRDDSP );
904      7!          CALL FLUTDMA ( NITER, BC, SUB, ESIZE(BC), PSIZE(BC),
905      7!          BGPDT(BC), USET(BC), [MAA], [KAA], [TMN(BC)],
906      7!          [GSUBO(BC)], NGDR, LAMBDA, [PHIA],
907      7!          [MHHLFL(BC,SUB)], [BHHFL(BC,SUB)], [KHHFL(BC,SUB)] );
908      7!          CALL FLUTTRAZ ( NITER, BC, SUB, [QHHLFL(BC,SUB)], LAMBDA,
909      7!          HSIZE(BC), ESIZE(BC), [MHHLFL(BC,SUB)],
910      7!          [BHHFL(BC,SUB)], [KHHFL(BC,SUB)],
911      7!          CLAMBDA, CONST,AEROZ );
912      7!          ENDDO;
913      6!          ENDIF;
914      5!$
915      5!          IF BDRSP <> 0 THEN
916      6!          IF BMTR <> 0 OR BDTR <> 0 THEN
917      7!          PRINT("LOG=('          >>>DISCIPLINE: TRANSIENT RESPONSE')");
918      7!          ENDIF;
919      6!          IF BMFR <> 0 OR BDFR <> 0 THEN
920      7!          PRINT("LOG=('          >>>DISCIPLINE: FREQUENCY RESPONSE')");
921      7!          ENDIF;
922      6!$
923      6!$          CALL QHHLGEN ( BC, ESIZE(BC), [QKGL], [QKJL], [UGTKA], [PHIA],
924      6!$          [PHIKH], [QHHL], [QHJL] );
925      6!$
926      6!$          CALL QHHLGENZ ( BC, ESIZE(BC), [AJK],[SKJ],[QKGL],[UGTKA], [PHIA],
927      6!$          [PHIKH], [QHHL], [QHJL], AEROZ );
928      6!          CALL DMA ( NITER, BC, ESIZE(BC), PSIZE(BC), BGPDT(BC), USET(BC),
929      6!          [MAA], [KAA], [TMN(BC)], [GSUBO(BC)], NGDR,
930      6!          LAMBDA, [PHIA], [MDD], [BDD], [KDDT], [KDDF],
931      6!          [MHHL], [BHH], [KHHT], [KHHL] );
932      6!          CALL DYNLOAD ( NITER, BC, GSIZE, ESIZE(BC), PSIZE(BC), SMPLOD,
933      6!          BGPDT(BC), USET(BC), [TMN(BC)], [GSUBO(BC)],
934      6!          NGDR, [PHIA], [QHJL], [PDT], [PDF],
935      6!          [PTGLOAD], [PTHLOAD], [PFGLOAD], [PFHLOAD] );
936      6!          CALL DYNRSP ( BC, ESIZE(BC), [MDD], [BDD], [KDDT], [KDDF],
937      6!          [MHHL], [BHH], [KHHT], [KHHL], [PDT], [PDF],
938      6!          [QHHL], [UTRANA], [UFREQA], [UTRANI], [UFREQI],
939      6!          [UTRANE], [UFREQE] );
940      6!          IF BMTR <> 0 [UTRANA] := [PHIA] * [UTRANI];
941      6!          IF BMFR <> 0 [UFREQA] := [PHIA] * [UFREQI];
942      6!          ENDIF;
943      5!          ENDIF;
944      4!          IF BELAST <> 0 THEN
945      5!          PRINT("LOG=('          >>>DISCIPLINE: BLAST')");
946      5!          CALL BLASTFIT ( BC, [QHJL], [MATTR], [MATSS], BQDP, [BFRC],
947      5!          [DWNWSH], HSIZE(BC), [ID2], [MPART], [UGTKA],
948      5!          [BLGTJA], [BLSTJA] );
949      5!          CALL COLPART ( [PHIA], , [PHIE], [MPART] );
950      5!          CALL ROWMERGE ( [PHIR], [ID2], [D(BC)], [PARL(BC)] );
951      5!          CALL COLMERGE ( [PHIB], [PHIR], [PHIE], [MPART] );
952      5!          [GENM] := TRANS ( [PHIB] ) * [ [MAA] * [PHIB] ];
953      5!          [GENK] := TRANS ( [PHIB] ) * [ [KAA] * [PHIB] ];
954      5!          [DTSLP] := TRANS ( [BLSTJA] ) * [PHIB];
955      5!          [FTF] := TRANS ( [PHIB] ) * [BLGTJA];

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956 5!      [GENF] := (BQDP) [FTF] * [BFRC];
957 5!      [GENFA] := (BQDP) [FTF] * [MATSS];
958 5!      [GENQ] := [GENFA] * [DTSLP];
959 5!      [GENQL] := (BQDP) [FTF] * [MATTR];
960 5!      CALL PARTN ( [GENQ], [QRR], , [QRE], [QEE], [MPART] );
961 5!      CALL PARTN ( [GENK], , , [KEE], [MPART] );
962 5!      [KEQE] := [QEE] + [KEE];
963 5!      CALL DECOMP ( [KEQE], [LKQ], [UKQ] );
964 5!      CALL ROWPART ( [GENF], [GFR], [GFE], [MPART] );
965 5!      CALL GFBS ( [LKQ], [UKQ], [GFE], [BTEM] );
966 5!      [DELM] := -[QRE] * [BTEM] + [GFR];
967 5!      CALL BLASTRIM ( BC, [DELM], [MRR(BC)], [URDB], [DELB] );
968 5!      [ELAS] := [BTEM] * [DELB];
969 5!      [SLPMOD] := TRANS ( [BLSTJA] ) * [PHIE];
970 5!      CALL BLASTDRV ( BC, [GENM], [GENK], [GENFA], [GENQL], [DELB],
971 5!                      [URDB], [DWNWSH], [SLPMOD], [ELAS], [UBLASTI] );
972 5!      ENDIF;
973 4!$
974 4!$      BEGIN THE DATA RECOVERY OPERATIONS
975 4!$
976 4!      PRINT("LOG=('          DATA RECOVERY')");
977 4!      IF NUMOPTBC > 1 CALL NULLMAT ([UF], [AF], [PHIF], [UTRANF], [UFREQF]);
978 4!      IF NGDR <> 0 THEN
979 5!$
980 5!$          DATA RECOVERY WITH GDR
981 5!$          APPEND THE GDR-GENERATED DOFS TO THE F-SET
982 5!$
983 5!      PRINT("LOG=('          DYNAMIC REDUCTION RECOVERY')");
984 5!      IF BLOAD <> 0 THEN
985 6!          [UFGDR] := [GSUBO(BC)] * [UA];
986 6!          CALL ROWPART ( [UA], [UJK], , [PAJK] );
987 6!          CALL ROWMERGE ( [UF], [UJK], [UFGDR], [PFJK] );
988 6!          IF NRSET <> 0 THEN
989 7!              [AFGDR] := [GSUBO(BC)] * [AA];
990 7!              CALL ROWPART ( [AA], [UJK], , [PAJK] );
991 7!              CALL ROWMERGE ( [AF], [UJK], [AFGDR], [PFJK] );
992 7!          ENDIF;
993 6!      ENDIF;
994 5!      IF BSAERO <> 0 THEN
995 6!          FOR S = 1 TO SUB DO
996 7!              [UFGDR] := [GSUBO(BC)] * [UAA(S)];
997 7!              CALL ROWPART ( [UAA(S)], [UJK], , [PAJK] );
998 7!              CALL ROWMERGE ( [UAFTMP], [UJK], [UFGDR], [PFJK] );
999 7!$
1000 7!$          MERGE THE CURRENT SUBCASE DEPENDENT RESULTS INTO A SINGLE
1001 7!$          MATRIX OF RESPONSE QUANTITIES FOR FURTHER RECOVERY
1002 7!$
1003 7!          CALL SAEROMRG ( BC, S, [UAF], [UAFTMP] );
1004 7!          IF NRSET <> 0 THEN
1005 8!              [AFGDR] := [GSUBO(BC)] * [AAA(S)];
1006 8!              CALL ROWPART ( [AAA(S)], [UJK], , [PAJK] );
1007 8!              CALL ROWMERGE ( [AAFTMP], [UJK], [AFGDR], [PFJK] );
1008 8!              CALL SAEROMRG ( BC, S, [AAF], [AAFTMP] );
1009 8!          ENDIF;
1010 7!          IF AEFLG(S) THEN
1011 8!              [UFGDR] := [GSUBO(BC)] * [UAAC(S)];
1012 8!              CALL ROWPART ( [UAAC(S)], [UJK], , [PAJK] );
1013 8!              CALL ROWMERGE ( [UAFC(S)], [UJK], [UFGDR], [PFJK] );
1014 8!              [AFGDR] := [GSUBO(BC)] * [AAAC(S)];
1015 8!              CALL ROWPART ( [AAAC(S)], [UJK], , [PAJK] );
1016 8!              CALL ROWMERGE ( [AAFC(S)], [UJK], [AFGDR], [PFJK] );
1017 8!          ENDIF;
1018 7!      ENDDO;
1019 6!      ENDIF;
1020 5!      IF BMODES <> 0 THEN
1021 6!          [UFGDR] := [GSUBO(BC)] * [PHIA];
1022 6!          CALL ROWPART ( [PHIA], [UJK], , [PAJK] );
1023 6!          CALL ROWMERGE ( [PHIF], [UJK], [UFGDR], [PFJK] );
1024 6!      ENDIF;
1025 5!      IF BDTR <> 0 OR BMTR <> 0 THEN
1026 6!          [UFGDR] := [GSUBO(BC)] * [UTRANA];
1027 6!          CALL ROWPART ( [UTRANA], [UJK], , [PAJK] );
1028 6!          CALL ROWMERGE ( [UTRANF], [UJK], [UFGDR], [PFJK] );
1029 6!      ENDIF;
1030 5!      IF BDFR <> 0 OR BMFR <> 0 THEN
1031 6!          [UFGDR] := [GSUBO(BC)] * [UFREQA];
1032 6!          CALL ROWPART ( [UFREQA], [UJK], , [PAJK] );
1033 6!          CALL ROWMERGE ( [UFREQF], [UJK], [UFGDR], [PFJK] );
1034 6!      ENDIF;
1035 5!      ELSE
1036 5!          IF NOMIT <> 0 THEN

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1037 6!$ DATA RECOVERY WITH STATIC CONDENSATION $!
1038 6!$ $!
1039 6!$ $!
1040 6! PRINT("LOG=(' STATIC CONDENSATION RECOVERY')"); !
1041 6! IF BLOAD <> 0 THEN !
1042 7! CALL RECOVA ( [UA], [PO], [GSUBO(BC)], NRSET, [AA], !
1043 7! [IFM(BC)], , [KOOINV(BC)], , [PFOA(BC)], [UF] ); !
1044 7! IF NRSET <> 0 CALL RECOVA ( [AA], , [GSUBO(BC)], , , !
1045 8! [PFOA(BC)], [AF] ); !
1046 7! ENDF; !
1047 6! IF BSAERO <> 0 THEN !
1048 7! FOR S = 1 TO SUB DO !
1049 8! CALL RECOVA ( [UAA(S)], [PAO(S)], [GASUBO(BC,S)], !
1050 8! NRSET, [AAA(S)], [IFMA(BC,S)], BSAERO, !
1051 8! [KOOL(BC,S)], [KOOU(BC,S)], !
1052 8! [PFOA(BC)], [UAFTMP] ); !
1053 8!$ $!
1054 8!$ MERGE THE CURRENT SUBCASE DEPENDENT RESULTS INTO A SINGLE $!
1055 8!$ MATRIX OF RESPONSE QUANTITIES FOR FURTHER RECOVERY $!
1056 8!$ $!
1057 8! CALL SAEROMRG ( BC, S, [UAF], [UAFTMP] ); !
1058 8! IF NRSET <> 0 THEN !
1059 9! CALL RECOVA ( [AAA(S)], , [GASUBO(BC,S)], , , !
1060 9! [PFOA(BC)], [AAFTMP] ); !
1061 9! CALL SAEROMRG ( BC, S, [AAF], [AAFTMP] ); !
1062 9! ENDF; !
1063 8! IF AEFLG(S) THEN !
1064 9! CALL RECOVA ( [UAAC(S)], [PAOC(S)], [GASUBO(BC,S)], !
1065 9! NRSET, [AAAC(S)], [IFMA(BC,S)], BSAERO, !
1066 9! [KOOL(BC,S)], [KOOU(BC,S)], !
1067 9! [PFOA(BC)], [UAFC(S)] ); !
1068 9! CALL RECOVA ( [AAAC(S)], , [GASUBO(BC,S)], , , !
1069 9! [PFOA(BC)], [AAFC(S)] ); !
1070 9! ENDF; !
1071 8! ENDDO; !
1072 7! ENDF; !
1073 6! IF BMODES <> 0 THEN !
1074 7! [PHIO] := [GSUBO(BC)] * [PHIA]; !
1075 7! CALL ROWMERGE ( [PHIF], [PHIO], [PHIA], [PFOA(BC)] ); !
1076 7! ENDF; !
1077 6! IF BDTR <> 0 OR BMTR <> 0 THEN !
1078 7! CALL RECOVA ( [UTRANA], , [GSUBO(BC)], , , !
1079 7! [PFOA(BC)], [UTRANF] ); !
1080 7! ENDF; !
1081 6! IF BDFR <> 0 OR BMFR <> 0 THEN !
1082 7! CALL RECOVA ( [UFREQA], , [GSUBO(BC)], , , !
1083 7! [PFOA(BC)], [UFREQF] ); !
1084 7! ENDF; !
1085 6! ELSE !
1086 6!$ $!
1087 6!$ DATA RECOVERY WITHOUT F-SET REDUCTION $!
1088 6!$ $!
1089 6! IF BLOAD <> 0 THEN !
1090 7! [UF] := [UA]; !
1091 7! IF NRSET <> 0 [AF] := [AA]; !
1092 7! ENDF; !
1093 6! IF BSAERO <> 0 THEN !
1094 7! FOR S = 1 TO SUB DO !
1095 8!$ $!
1096 8!$ MERGE THE CURRENT SUBCASE DEPENDENT RESULTS INTO A SINGLE $!
1097 8!$ MATRIX OF RESPONSE QUANTITIES FOR FURTHER RECOVERY $!
1098 8!$ $!
1099 8! CALL SAEROMRG ( BC, S, [UAF], [UAA(S)] ); !
1100 8! IF NRSET <> 0 CALL SAEROMRG ( BC, S, [AAF], [AAA(S)] ); !
1101 8! IF AEFLG(S) THEN !
1102 9! [UAFC(S)] := [UAAC(S)]; !
1103 9! [AAFC(S)] := [AAAC(S)]; !
1104 9! ENDF; !
1105 8! ENDDO; !
1106 7! ENDF; !
1107 6! IF BMODES <> 0 [PHIF] := [PHIA]; !
1108 6! IF BDTR <> 0 OR BMTR <> 0 [UTRANF] := [UTRANA]; !
1109 6! IF BDFR <> 0 OR BMFR <> 0 [UFREQF] := [UFREQA]; !
1110 6! ENDF; !
1111 5! ENDF; !
1112 4!$ $!
1113 4! IF NUMOPTBC > 1 CALL NULLMAT ( [UN], [AN], [PHIN] ); !
1114 4! IF NSPC <> 0 THEN !
1115 5!$ $!
1116 5!$ DATA RECOVERY WITH SPC-REDUCTION $!
1117 5!$ $!

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1118 5! PRINT("LOG=(' SPC RECOVERY')"); !
1119 5! IF BLOAD <> 0 THEN !
1120 6! CALL YSMERGE ( [UN], [YS(BC)], [UF], [PNSF(BC)] ); !
1121 6! CALL OFFSPCF ( NITER, BC, 1, 1, GSIZE, ESIZE(BC), NGDR, !
1122 6! [KFS], [KSS], [UF], [YS(BC)], [PS], !
1123 6! [PNSF(BC)], [PGMN(BC)], [PFJK], , , , !
1124 6! BGPDT(BC), OGRIDLOD ); !
1125 6! IF NRSET <> 0 CALL YSMERGE ( [AN], , [AF], [PNSF(BC)] ); !
1126 6! ENDIF; !
1127 5! IF BSAERO <> 0 THEN !
1128 6! CALL YSMERGE ( [UAN], [YS(BC)], [UAF], [PNSF(BC)] ); !
1129 6! IF NRSET <> 0 CALL YSMERGE ( [AAN], , [AAF], [PNSF(BC)] ); !
1130 6! FOR S = 1 TO SUB DO !
1131 7! IF AEFLG(S) THEN !
1132 8! CALL YSMERGE ([UANC(S)], [YS(BC)], [UAFC(S)], [PNSF(BC)]); !
1133 8! CALL YSMERGE ([AANC(S)], , [AAFC(S)], [PNSF(BC)]); !
1134 8! ENDIF; !
1135 7! ENDDO; !
1136 6! ENDIF; !
1137 5! IF BMODES <> 0 THEN !
1138 6! CALL YSMERGE ( [PHIN], [YS(BC)], [PHIF], !
1139 6! [PNSF(BC)] ); !
1140 6! IF DMODES <> 0 CALL OFFSPCF ( NITER, BC, 2, 1, GSIZE, !
1141 7! ESIZE(BC), NGDR, !
1142 7! [KFS], , [PHIF], , , !
1143 7! [PNSF(BC)], [PGMN(BC)], [PFJK], !
1144 7! , , , BGPDT(BC), OGRIDLOD ); !
1145 6! ENDIF; !
1146 5! IF BDTR <> 0 OR BMTR <> 0 !
1147 6! CALL YSMERGE ( [UTRANN], [YS(BC)], [UTRANF], !
1148 6! [PNSF(BC)], BDTR ); !
1149 5! IF BDFR <> 0 OR BMFR <> 0 !
1150 6! CALL YSMERGE ( [UFREQN], [YS(BC)], [UFREQF], !
1151 6! [PNSF(BC)], BDFR ); !
1152 5! IF BBLAST <> 0 THEN !
1153 6! [UBLASTF] := [PHIF]*[UBLASTI]; !
1154 6! CALL OFFSPCF ( NITER, BC, 8, 1, GSIZE, ESIZE(BC), NGDR, !
1155 6! [KFS], , [UBLASTF], , , [PNSF(BC)], [PGMN(BC)], !
1156 6! [PFJK], , , , BGPDT(BC), OGRIDLOD ); !
1157 6! ENDIF; !
1158 5! ELSE !
1159 5!$ !
1160 5!$ DATA RECOVERY WITHOUT SPC-REDUCTION !
1161 5!$ !
1162 5! IF BLOAD <> 0 THEN !
1163 6! [UN] := [UF]; !
1164 6! IF NRSET <> 0 [AN] := [AF]; !
1165 6! ENDIF; !
1166 5! IF BSAERO <> 0 THEN !
1167 6! [UAN] := [UAF]; !
1168 6! IF NRSET <> 0 [AAN] := [AAF]; !
1169 6! FOR S = 1 TO SUB DO !
1170 7! IF AEFLG(S) THEN !
1171 8! [UANC(S)] := [UAFC(S)]; !
1172 8! [AANC(S)] := [AAFC(S)]; !
1173 8! ENDIF; !
1174 7! ENDDO; !
1175 6! ENDIF; !
1176 5! IF BMODES <> 0 [PHIN] := [PHIF]; !
1177 5! IF BDTR <> 0 OR BMTR <> 0 [UTRANN] := [UTRANA]; !
1178 5! IF BDFR <> 0 OR BMFR <> 0 [UFREQN] := [UFREQA]; !
1179 5! ENDIF; !
1180 4!$ !
1181 4! IF NUMOPTBC > 1 CALL NULLMAT ( [UG(BC)], [AG(BC)], [UAG(BC)], !
1182 5! [AAG(BC)], [PHIG(BC)] ); !
1183 4!$ !
1184 4! IF NMPC <> 0 THEN !
1185 5!$ !
1186 5!$ DATA RECOVERY WITH MPC-REDUCTION !
1187 5!$ !
1188 5! PRINT("LOG=(' MPC RECOVERY')"); !
1189 5! IF BLOAD <> 0 THEN !
1190 6! [UM] := [TMN(BC)] * [UN]; !
1191 6! CALL ROWMERGE ( [UG(BC)], [UM], [UN], [PGMN(BC)] ); !
1192 6! IF NRSET <> 0 THEN !
1193 7! [UM] := [TMN(BC)] * [AN]; !
1194 7! CALL ROWMERGE ( [AG(BC)], [UM], [AN], [PGMN(BC)] ); !
1195 7! ENDIF; !
1196 6! ENDIF; !
1197 5! IF BSAERO <> 0 THEN !
1198 6! [UM] := [TMN(BC)] * [UAN]; !

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1199 6!      CALL ROWMERGE ( [UAG(BC)], [UM], [UAN], [PGMN(BC)] );
1200 6!      IF NRSET <> 0 THEN
1201 7!          [UM] := [TMN(BC)] * [AAN];
1202 7!          CALL ROWMERGE ( [AAG(BC)], [UM], [AAN], [PGMN(BC)] );
1203 7!      ENDIF;
1204 6!      FOR S = 1 TO SUB DO
1205 7!          IF AEFLG(S) THEN
1206 8!              [UM] := [TMN(BC)] * [UANC(S)];
1207 8!              CALL ROWMERGE ([UAGC(BC,S)], [UM], [UANC(S)], [PGMN(BC)]);
1208 8!              [UM] := [TMN(BC)] * [AANC(S)];
1209 8!              CALL ROWMERGE ([AAGC(BC,S)], [UM], [AANC(S)], [PGMN(BC)]);
1210 8!          ENDIF;
1211 7!      ENDDO;
1212 6!      ENDIF;
1213 5!      IF BMODES <> 0 THEN
1214 6!          [UM] := [TMN(BC)] * [PHIN];
1215 6!          CALL ROWMERGE ( [PHIG(BC)], [UM], [PHIN], [PGMN(BC)] );
1216 6!      ENDIF;
1217 5!      IF BDTR <> 0 OR BMTR <> 0 THEN
1218 6!          [UM] := [TMN(BC)] * [UTRANN];
1219 6!          CALL ROWMERGE ( [UTRANG], [UM], [UTRANN], [PGMN(BC)] );
1220 6!      ENDIF;
1221 5!      IF BDFR <> 0 OR BMFR <> 0 THEN
1222 6!          [UM] := [TMN(BC)] * [UFREQN];
1223 6!          CALL ROWMERGE ( [UFREQG], [UM], [UFREQN], [PGMN(BC)] );
1224 6!      ENDIF;
1225 5!      ELSE
1226 5!$      DATA RECOVERY WITHOUT MPC-REDUCTION
1227 5!$
1228 5!$
1229 5!      IF BLOAD <> 0 THEN
1230 6!          [UG(BC)] := [UN];
1231 6!          IF NRSET <> 0 [AG(BC)] := [AN];
1232 6!      ENDIF;
1233 5!      IF BSAERO <> 0 THEN
1234 6!          [UAG(BC)] := [UAN];
1235 6!          IF NRSET <> 0 [AAG(BC)] := [AAN];
1236 6!          FOR S = 1 TO SUB DO
1237 7!              IF AEFLG(S) THEN
1238 8!                  [UAGC(BC,S)] := [UANC(S)];
1239 8!                  [AAGC(BC,S)] := [AANC(S)];
1240 8!              ENDIF;
1241 7!          ENDDO;
1242 6!      ENDIF;
1243 5!      IF BMODES <> 0 [PHIG(BC)] := [PHIN];
1244 5!      IF BDTR <> 0 OR BMTR <> 0 [UTRANG] := [UTRANN];
1245 5!      IF BDFR <> 0 OR BMFR <> 0 [UFREQG] := [UFREQN];
1246 5!      ENDIF;
1247 4!$      RECOVER PHYSICAL BLAST DISCIPLINE DISPLACEMENTS
1248 4!$
1249 4!$
1250 4!      IF BBLAST <> 0 [UBLASTG] := [PHIG(BC)] * [UBLASTI];
1251 4!$
1252 4!$      PERFORM CONSTRAINT EVALUATION FOR STATIC DISCIPLINES
1253 4!$
1254 4!      PRINT("LOG=('          CONSTRAINT EVALUATION')");
1255 4!      IF BLOAD <> 0 THEN
1256 5!          CALL DCEVAL ( NITER, BC, [UG(BC)], CONST );
1257 5!          CALL SCEVAL ( NITER, BC, [UG(BC)], [SMAT], TREF, [GLBSIG], CONST );
1258 5!      ENDIF;
1259 4!      IF BSAERO <> 0 THEN
1260 5!          CALL DCEVAL ( NITER, BC, [UAG(BC)], CONST, BSAERO );
1261 5!          CALL SCEVAL ( NITER, BC, [UAG(BC)], [SMAT], TREF, [GLBSIG], CONST,
1262 5!                      BSAERO );
1263 5!      ENDIF;
1264 4!$      HANDLE OUTPUT REQUESTS
1265 4!$
1266 4!$
1267 4!      PRINT("LOG=('          OUTPUT PROCESSING')");
1268 4!      IF BSAERO <> 0 THEN
1269 5!$      RECOVER STATIC AEROELASTIC LOADS DATA
1270 5!$
1271 5!$
1272 5!      LOOP := TRUE;
1273 5!      SUB := 0;
1274 5!      WHILE LOOP DO
1275 6!          SUB := SUB + 1;
1276 6!          CALL SAERODRV (BC, SUB, LOOP, MINDEX, SYM, MACH, QDP );
1277 6!$      CALL THE TRIMMED LOADS COMPUTATION WITH PROPER MATRICES
1278 6!$
1279 6!$

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1280 6! IF SYM = 1 THEN
1281 7!$***** TAKEN OUT FOR ZAERO *****$!
1282 7!$ CALL OFFPALOAD ( NITER, BC, MINDEX, SUB, GSIZE, BGPDT(BC), $!
1283 7!$ [GTKG], [GSTKG], QDP, [AIRFRM(MINDEX)], $!
1284 7!$ [DELTA(SUB)], [AICMAT(MINDEX)], $!
1285 7!$ [UAG(BC)], [MGG], [AAG(BC)], [KFS], $!
1286 7!$ [KSS], [UAF], [YS(BC)], [PNSF(BC)], $!
1287 7!$ [PGMN(BC)], [PFJK], NGDR, USET(BC), $!
1288 7!$ OGRIDLOD ); $!
1289 7!$*****$!
1290 7! CALL OFFPALOAD ( NITER, BC, MINDEX, SUB, GSIZE, BGPDT(BC), $!
1291 7! [UGTKG], [UGTKG], QDP, [AIRFRM(MINDEX)], $!
1292 7! [DELTA(SUB)], [AICMAT(MINDEX)], $!
1293 7! [UAG(BC)], [MGG], [AAG(BC)], [KFS], $!
1294 7! [KSS], [UAF], [YS(BC)], [PNSF(BC)], $!
1295 7! [PGMN(BC)], [PFJK], NGDR, USET(BC), $!
1296 7! OGRIDLOD ); $!
1297 7! ELSE
1298 7! IF SYM = -1 THEN
1299 8!$***** TAKEN OUT FOR ZAERO *****$!
1300 8!$ CALL OFFPALOAD ( NITER, BC, MINDEX, SUB, GSIZE, BGPDT(BC), $!
1301 8!$ [GTKG], [GSTKG], QDP, [AIRFRM(MINDEX)], $!
1302 8!$ [DELTA(SUB)], [AICMAT(MINDEX)], $!
1303 8!$ [UAG(BC)], [MGG], [AAG(BC)], [KFS], $!
1304 8!$ [KSS], [UAF], [YS(BC)], [PNSF(BC)], $!
1305 8!$ [PGMN(BC)], [PFJK], NGDR, USET(BC), $!
1306 8!$ OGRIDLOD ); $!
1307 8!$*****$!
1308 8! CALL OFFPALOAD ( NITER, BC, MINDEX, SUB, GSIZE, BGPDT(BC), $!
1309 8! [UGTKG], [UGTKG], QDP, [AIRFRM(MINDEX)], $!
1310 8! [DELTA(SUB)], [AICMAT(MINDEX)], $!
1311 8! [UAG(BC)], [MGG], [AAG(BC)], [KFS], $!
1312 8! [KSS], [UAF], [YS(BC)], [PNSF(BC)], $!
1313 8! [PGMN(BC)], [PFJK], NGDR, USET(BC), $!
1314 8! OGRIDLOD ); $!
1315 8! ENDIF;
1316 7! ENDIF;
1317 6!$
1318 6!$ CALL TO COMPUTE THE TRIMMED LOADS/DISPLACEMENTS ON THE $!
1319 6!$ AERODYNAMIC MODEL $!
1320 6!$
1321 6! IF SYM = 1 THEN
1322 7!$***** TAKEN OUT FOR ZAERO *****$!
1323 7!$ CALL OFFPAEROM ( NITER, BC, MINDEX, SUB, GSIZE, GEOMSA, $!
1324 7!$ [GTKG], [GSTKG], QDP, [AIRFRM(MINDEX)], $!
1325 7!$ [DELTA(SUB)], [AICMAT(MINDEX)], $!
1326 7!$ [UAG(BC)], OAGRDLOD, OAGRDDSP ); $!
1327 7!$*****$!
1328 7! CALL OFFPAEROM ( NITER, BC, MINDEX, SUB, GSIZE, GEOMSA, $!
1329 7! [UGTKG], [UGTKG], QDP, [AIRFRM(MINDEX)], $!
1330 7! [DELTA(SUB)], [AICMAT(MINDEX)], $!
1331 7! [UAG(BC)], OAGRDLOD, OAGRDDSP ); $!
1332 7! ELSE
1333 7! IF SYM = -1 THEN
1334 8!$***** TAKEN OUT FOR ZAERO *****$!
1335 8!$ CALL OFFPAEROM ( NITER, BC, MINDEX, SUB, GSIZE, GEOMSA, $!
1336 8!$ [GTKG], [GSTKG], QDP, [AIRFRM(MINDEX)], $!
1337 8!$ [DELTA(SUB)], [AICMAT(MINDEX)], $!
1338 8!$ [UAG(BC)], OAGRDLOD, OAGRDDSP ); $!
1339 8!$*****$!
1340 8! CALL OFFPAEROM ( NITER, BC, MINDEX, SUB, GSIZE, GEOMSA, $!
1341 8! [UGTKG], [UGTKG], QDP, [AIRFRM(MINDEX)], $!
1342 8! [DELTA(SUB)], [AICMAT(MINDEX)], $!
1343 8! [UAG(BC)], OAGRDLOD, OAGRDDSP ); $!
1344 8! ENDIF;
1345 7! ENDIF;
1346 6! ENDDO;
1347 5! ENDIF;
1348 4! IF BDRSP <> 0 THEN
1349 5! CALL OFFPDLOAD ( NITER, BC, BGPDT(BC), PSIZE(BC), ESIZE(BC), $!
1350 5! [PHIG(BC)], [PTGLOAD], [PTHLOAD], [PFGLOAD], $!
1351 5! [PFHLOAD], OGRIDLOD ); $!
1352 5! IF BDRTR <> 0 OR BMTR <> 0
1353 6! CALL OFFSPCF ( NITER, BC, 5, 1, GSIZE, ESIZE(BC), $!
1354 6! NGDR, [KFS], , [UTRANF], , $!
1355 6! [PNSF(BC)], [PGMN(BC)], [PFJK], $!
1356 6! [PHIG(BC)], [PTGLOAD], [PTHLOAD], $!
1357 6! BGPDT(BC), OGRIDLOD ); $!
1358 5! IF BDFR <> 0 OR BMFR <> 0
1359 6! CALL OFFSPCF ( NITER, BC, 6, 2, GSIZE, ESIZE(BC), $!
1360 6! NGDR, [KFS], , [UFREQF], , $!

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1361 6! [PNSF(BC)], [PGMN(BC)], [PFJK], !
1362 6! [PHIG(BC)], [PFGLOAD], [PFHLOAD], !
1363 6! BGPDT(BC), OGRIDLOD); !
1364 5! ENDIF; !
1365 4! CALL OFFLOAD ( NUMOPTBC, BC, NITER, GSIZE, BGPDT(BC), PSIZE(BC), !
1366 4! [PG]); !
1367 4! CALL OFFDISP ( NUMOPTBC, BC, NITER, GSIZE, BGPDT(BC), ESIZE(BC), !
1368 4! PSIZE(BC), OGRIDDSP, [UG(BC)], [AG(BC)], [UAG(BC)], !
1369 4! [AAG(BC)], [UBLASTG], , [UTRANG], [UTRANE], [UFREQG], !
1370 4! [UFREQE], LAMBDA, [PHIG(BC)] ); !
1371 4! CALL EDR ( NUMOPTBC, BC, NITER, NDV, GSIZE, EOSUMRY, EODISC, !
1372 4! GLBDES, LOCLVAR, [PTRANS], !
1373 4! [UG(BC)], [UAG(BC)], , [UTRANG], [UFREQG], [PHIG(BC)] ); !
1374 4! CALL PBKLEVAL ( BC, NITER, NDV, GLBDES, LOCLVAR, [PTRANS], PDLIST, !
1375 4! OPNLBUCK ); !
1376 4! CALL EBKLEVAL ( BC, NITER, NDV, GLBDES, LOCLVAR, [PTRANS], OEULBUCK ); !
1377 4! CALL OFFPEDR ( BC, HSIZE(BC), NITER ); !
1378 4! ENDDO; !
1379 3!$ $!
1380 3!$ $!
1381 3!$ $!
1382 3! PRINT("LOG=(' SENSITIVITY ANALYSIS')"); !
1383 3! CALL ACTCON ( NITER, MAXITER, NRFAC, NDV, GLBDES, LOCLVAR, [PTRANS], !
1384 3! EPS, APPCNVRG, GLBCNVRG, !
1385 3! CTL, CTLMIN, CONST, [AMAT], DESHIST, PFLAG, OLOCALDV ); !
1386 3! CALL DESPUNCH ( NITER, PFLAG, OLOCALDV ); !
1387 3!$ $!
1388 3! IF GLBCNVRG OR NITER > MAXITER THEN !
1389 4!$ $!
1390 4!$ $!
1391 4!$ $!
1392 4! FOR BC = 1 TO NUMOPTBC DO !
1393 5! CALL OFFPMROOT ( NITER, BC, NUMOPTBC, LAMBDA, 1 ); !
1394 5! CALL OFFDISP ( NUMOPTBC, BC, NITER, GSIZE, BGPDT(BC), ESIZE(BC), !
1395 5! PSIZE(BC), OGRIDDSP, , , LAMBDA, , 1 ); !
1396 5! CALL OFFPEDR ( BC, HSIZE(BC), NITER, 1 ); !
1397 5! ENDDO; !
1398 4! ENDIF; !
1399 3!$ $!
1400 3! IF NOT GLBCNVRG AND NITER <= MAXITER THEN !
1401 4!$ $!
1402 4!$ $!
1403 4!$ $!
1404 4! USE APPROPRIATE RESIZING METHOD !
1405 5! IF NITER >= FSDE AND NITER <= FSDE THEN !
1406 5! CALL FSD ( NDV, NITER, FSDE, FSDE, MPS, OCS, ALPHA, !
1407 5! CNVRGLIM, GLBDES, LOCLVAR, [PTRANS], CONST, !
1408 5! APPCNVRG, CTL, CTLMIN, DESHIST ); !
1409 4!$ $!
1410 4! IF ( NITER >= MPS AND NITER <= MPE ) OR !
1411 5! ( NITER >= OCS AND NITER <= OCE ) THEN !
1412 5!$ $!
1413 5!$ $!
1414 5!$ $!
1415 5!$ $!
1416 5!$ $!
1417 5!$ $!
1418 5! CALL MAKDFV ( NITER, NDV, [PMINT], [PMAXT], CONST, [AMAT] ); !
1419 5! CALL LAMINSNS ( NITER, NDV, GLBDES, LOCLVAR, [PTRANS], CONST, !
1420 5! [AMAT] ); !
1421 5!$ $!
1422 5!$*****$!
1423 5!$ SENSITIVITY EVALUATION FOR BOUNDARY CONDITION DEPENDENT CONSTRAINTS$!
1424 5!$*****$!
1425 5!$ $!
1426 5! FOR BC = 1 TO NUMOPTBC DO !
1427 6! CALL ABOUND ( NITER, BC, CONST, ACTBOUND, NAUS, NACSD, [PGAS], !
1428 6! PCAS, ACTAERO, ACTDYN, ACTFLUT, ACTPNL, ACTBAR, !
1429 6! NMFC, NSPC, NOMIT, NRSET, NGDR, USET(BC) ); !
1430 6! IF ACTBOUND THEN !
1431 7!$ $!
1432 7!$ REESTABLISH THE BASE USET AND PARTITIONING DATA FOR THE BC $!
1433 7!$ IF GDR CHANGED IT $!
1434 7!$ NOTE, THIS LEAVES AN INCOMPATIBILITY BETWEEN USET(BC) AND $!
1435 7!$ BGPDT(BC) SINCE THE LATTER IS NOT REGENERATED. $!
1436 7!$ THIS INCOMPATIBILITY WILL NOT AFFECT THE SENSITIVITY ANALYSIS$!
1437 7!$ AND WILL BE CORRECTED IN THE SUBSEQUENT ANALYSIS $!
1438 7!$ $!
1439 7! IF NGDR <> 0 THEN !
1440 8! CALL MKUSET(BC, GSIZE, [YS(BC)], [TMN(BC)], [PGMN(BC)], !
1441 8! [PNSF(BC)], [PFOA(BC)], [PARL(BC)], USET(BC)); !

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1442      8!      ENDIF;
1443      7!$
1444      7!$      EVALUATE FREQUENCY CONSTRAINT SENSITIVITIES
1445      7!$
1446      7!      IF ACTDYN THEN
1447      8!          IF NGDR <> 0 THEN
1448      9!              CALL ROWPART ( [PHIG(BC)], , [GTMP], [PGDRG(BC)] );
1449      9!              CALL FREQSENS ( NITER, BC, NDV, GLBDES, CONST, LAMBDA,
1450      9!                  GMKCT, DKVI, GMMCT, DMVI,
1451      9!                  [GTMP], [AMAT] );
1452      9!          ELSE
1453      9!              CALL FREQSENS ( NITER, BC, NDV, GLBDES, CONST, LAMBDA,
1454      9!                  GMKCT, DKVI, GMMCT, DMVI,
1455      9!                  [PHIG(BC)], [AMAT] );
1456      9!          ENDIF;
1457      8!      ENDIF;
1458      7!$
1459      7!$      EVALUATE FLUTTER CONSTRAINT SENSITIVITIES
1460      7!$
1461      7!      IF ACTFLUT THEN
1462      8!          SUB := 0;
1463      8!          LOOP := TRUE;
1464      8!          IF NGDR <> 0 CALL ROWPART ([PHIG(BC)],, [GTMP], [PGDRG(BC)]);
1465      8!          WHILE LOOP DO
1466      9!              SUB := SUB + 1;
1467      9!              IF NGDR <> 0 THEN
1468      10!                  CALL FLUTSENS (NITER, BC, SUB, LOOP, GSIZEB, NDV,
1469      10!                      GLBDES, CONST, GMKCT, DKVI, GMMCT,
1470      10!                      DMVI, CLAMBDA, LAMBDA,
1471      10!                      [QHHLFL(BC,SUB)],
1472      10!                      [MHHLFL(BC,SUB)], [BNHHLFL(BC,SUB)],
1473      10!                      [KHHLFL(BC,SUB)], [GTMP], [AMAT],
1474      10!                      AEROZ );
1475      10!              ELSE
1476      10!                  CALL FLUTSENS (NITER, BC, SUB, LOOP, GSIZEB, NDV,
1477      10!                      GLBDES, CONST, GMKCT, DKVI, GMMCT,
1478      10!                      DMVI, CLAMBDA, LAMBDA,
1479      10!                      [QHHLFL(BC,SUB)],
1480      10!                      [MHHLFL(BC,SUB)], [BNHHLFL(BC,SUB)],
1481      10!                      [KHHLFL(BC,SUB)], [PHIG(BC)], [AMAT],
1482      10!                      AEROZ );
1483      10!              ENDIF;
1484      9!          ENDDO;
1485      8!      ENDIF;
1486      7!$
1487      7!$      EVALUATE ACTIVE DISPLACEMENT DEPENDENT CONSTRAINTS FROM
1488      7!$      THE STATICS DISCIPLINE
1489      7!$
1490      7!      IF NAUS > 0 THEN
1491      8!$          SENSITIVITIES OF CONSTRAINTS WRT DISPLACEMENTS FOR STATICS
1492      8!$
1493      8!$          CALL NULLMAT ( [DFDU], [DPGV] );
1494      8!          IF NACSD > NAUS * NDV THEN
1495      8!              USE GRADIENT METHOD
1496      9!$
1497      9!$          CALL MAKDFU ( NITER, BC, GSIZEB, [SMAT], [GLBSIG],
1498      9!$              CONST, [DFDU] );
1499      9!          ELSE
1500      9!              USE VIRTUAL LOAD METHOD
1501      9!$
1502      9!$          CALL MAKDFU ( NITER, BC, GSIZEB, [SMAT], [GLBSIG],
1503      9!$              CONST, [DPGV] );
1504      9!          ENDIF;
1505      8!$
1506      8!$      SOME RELATIVELY SIMPLE CALCULATIONS THAT PRECEDE THE
1507      8!$      LOOP ON THE DESIGN VARIABLES
1508      8!$
1509      8!$      IF NGDR <> 0 THEN
1510      8!$          CALL PARTN ( [UG(BC)],, , [UGA], [PGAS], [PGDRG(BC)] );
1511      8!$      ELSE
1512      8!$          CALL COLPART ( [UG(BC)], , [UGA], [PGAS] );
1513      8!$      ENDIF;
1514      8!$
1515      8!$      OBTAIN THE SENSITIVITIES OF THE DESIGN
1516      8!$      DEPENDENT LOADS
1517      8!$
1518      8!$      CALL DDLOAD(NDV, GSIZEB, BC, SMPLOD, DDFLG, [PGAS], [DPVJ]);
1519      8!$
1520      8!$
1521      8!$
1522      8!$

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1523      8!      CALL MAKDVU ( NITER, NDV, GLBDES, [UGA], [DKUG],      !
1524      8!      GMKCT, DKVI );      !
1525      8!      CALL NULLMAT ( [DUG] );      !
1526      8!      IF NRSET <> 0 THEN      !
1527      9!      IF NGDR <> 0 THEN      !
1528      10!      CALL PARTN ([AG(BC)],,, [AGA], [PGAS], [PGDRG(BC)]);      !
1529      10!      ELSE      !
1530      10!      CALL COLPART ( [AG(BC)], , [AGA], [PGAS] );      !
1531      10!      ENDIF;      !
1532      9!      CALL MAKDVU ( NITER, NDV, GLBDES, [AGA], [DMAG],      !
1533      9!      GMMCT, DMVI );      !
1534      9!      [DUG] := [DKUG] + [DMAG];      !
1535      9!      ELSE      !
1536      9!      [DUG] := [DKUG];      !
1537      9!      ENDIF;      !
1538      8!$      $!
1539      8!$      ACCOUNT FOR VIRTUAL LOAD METHOD      $!
1540      8!$      $!
1541      8!      IF NACSD > NAUS * NDV THEN      $!
1542      9!$      $!
1543      9!$      USE GRADIENT METHOD      $!
1544      9!$      $!
1545      9!      IF DDFLG > 0 THEN      !
1546      10!      [DPGV] := [DPVJ] + [DUG];      !
1547      10!      ELSE      !
1548      10!      [DPGV] := [DUG];      !
1549      10!      ENDIF;      !
1550      9!      ELSE      $!
1551      9!$      $!
1552      9!$      USE VIRTUAL LOAD METHOD      $!
1553      9!$      $!
1554      9!      IF DDFLG > 0 THEN      !
1555      10!      [DFDU] := [DPVJ] + [DUG];      !
1556      10!      ELSE      !
1557      10!      [DFDU] := [DUG];      !
1558      10!      ENDIF;      !
1559      9!      ENDIF;      $!
1560      8!$      $!
1561      8!$      REDUCE THE RIGHT HAND SIDES TO THE L SET      $!
1562      8!$      $!
1563      8!      CALL NULLMAT ( [DPNV], [DMUN] );      !
1564      8!      IF NMPC <> 0 THEN      !
1565      9!      CALL GREduce (,[DPGV], [PGMNS(BC)], [TMN(BC)],, [DPNV]);      !
1566      9!      ELSE      !
1567      9!      [DPNV] := [DPGV];      !
1568      9!      ENDIF;      $!
1569      8!$      $!
1570      8!      CALL NULLMAT ( [DPFV], [DMUF] );      !
1571      8!      IF NSPC <> 0 THEN      !
1572      9!      CALL NREDUCE (, [DPNV], [PNSFS(BC)], , , , [DPFV]);      !
1573      9!      ELSE      !
1574      9!      [DPFV] := [DPGV];      !
1575      9!      ENDIF;      $!
1576      8!$      $!
1577      8!      CALL NULLMAT ( [DPAV], [DMUA] );      !
1578      8!      IF NGDR <> 0 THEN      !
1579      9!      [DPAV] := TRANS( [GSUBO(BC)] ) * [DPFV];      !
1580      9!      ELSE      !
1581      9!      IF NOMIT <> 0 THEN      !
1582      10!      CALL FREDUCE (, [DPFV], [PFOAS(BC)], ,      !
1583      10!      [KOOINV(BC)], , , [GSUBO(BC)], ,      !
1584      10!      [DPAV], [DPOV], );      !
1585      10!      ELSE      !
1586      10!      [DPAV] := [DPFV];      !
1587      10!      ENDIF;      !
1588      9!      ENDIF;      $!
1589      8!$      $!
1590      8!      IF NRSET <> 0 THEN      !
1591      9!      CALL ROWPART ( [DPAV], [DPRV], [DPLV], [PARLS(BC)] );      !
1592      9!      [DRHS] := TRANS( [D(BC)] ) * [DPLV] + [DPRV];      !
1593      9!$      $!
1594      9!$      PROCESS ACTIVE CONSTRAINTS FOR STATICS DISCIPLINE      $!
1595      9!$      $!
1596      9!      CALL INERTIA ( [MRR(BC)], [DRHS], [DURD] );      !
1597      9!      [DULD] := [D(BC)] * [DURD];      !
1598      9!      CALL ROWMERGE ( [DUAD], [DURD], [DULD], [PARLS(BC)] );      !
1599      9!      [DPLV] := [DPLV] + [IFR(BC)] * [DURD];      !
1600      9!      CALL FBS ( [KLLINV(BC)], [DPLV], [DULV] );      !
1601      9!      CALL YSMERGE ( [DUAV], , [DULV], [PARLS(BC)] );      !
1602      9!      ELSE      !
1603      9!      CALL FBS ( [KLLINV(BC)], [DPAV], [DUAV] );      !

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1604 9!      ENDIF;
1605 8!$
1606 8!$      RECOVER TO THE F SET
1607 8!$
1608 8!      CALL NULLMAT ( [DUFV] );
1609 8!      IF NRSET <> 0 THEN
1610 9!          [DUFV] := [GSUBO(BC)] * [DUAV];
1611 9!      ELSE
1612 9!          IF NOMIT <> 0 THEN
1613 10!              IF NRSET <> 0 THEN
1614 11!                  [TMP1] := [DPOV] - [IFM(BC)] * [DUAD];
1615 11!              ELSE
1616 11!                  [TMP1] := [DPOV];
1617 11!              ENDIF;
1618 10!              CALL FBS ( [KOOINV(BC)], [TMP1], [UOO] );
1619 10!              [UO] := [GSUBO(BC)] * [DUAV] + [UOO];
1620 10!              CALL ROWMERGE ([DUFV], [UO], [DUAV], [PFOAS(BC)]);
1621 10!          ELSE
1622 10!              [DUFV] := [DUAV];
1623 10!          ENDIF;
1624 9!      ENDIF;
1625 8!$
1626 8!$      REDUCE THE LEFT HAND SIDE MATRIX
1627 8!$
1628 8!      IF NMPC <> 0 THEN
1629 9!          CALL GREduce (, [DFDU], [PGMNS(BC)], [TMN(BC)],, [DFDUN]);
1630 9!      ELSE
1631 9!          [DFDUN] := [DFDU];
1632 9!      ENDIF;
1633 8!$
1634 8!      IF NSPC <> 0 THEN
1635 9!          CALL ROWPART ( [DFDUN],, [DFDUF], [PNSFS(BC)] );
1636 9!      ELSE
1637 9!          [DFDUF] := [DFDUN];
1638 9!      ENDIF;
1639 8!$
1640 8!$      ACCOUNT FOR VIRTUAL LOAD METHOD
1641 8!$
1642 8!      IF NACSD > NAUS * NDV THEN
1643 9!$
1644 9!$          USE GRADIENT METHOD
1645 9!$
1646 9!          CALL MKAMAT ([AMAT], [DFDUF], [DUFV], PCAS, [PGAS] );
1647 9!      ELSE
1648 9!$
1649 9!$          USE VIRTUAL LOAD METHOD
1650 9!$
1651 9!          CALL MKAMAT ([AMAT], [DUFV], [DFDUF], PCAS, [PGAS] );
1652 9!      ENDIF;
1653 8!$
1654 8!      ENDIF; $ END IF ON ACTIVE APPLIED STATIC LOADS
1655 7!$
1656 7!$      EVALUATE ACTIVE CONSTRAINTS FROM
1657 7!$      THE STATIC AEROELASTICITY DISCIPLINE
1658 7!$
1659 7!      IF ACTAERO THEN
1660 8!          LOOP := TRUE;
1661 8!          ACTUAGG := FALSE;
1662 8!          SUB := 0;
1663 8!          CALL NULLMAT ( [DUFV] );
1664 8!          WHILE LOOP DO
1665 9!              SUB := SUB + 1;
1666 9!              CALL AROSNSDR ( NITER, BC, SUB, LOOP, MINDEX, CONST,
1667 9!                  SYM, NGDR,
1668 9!                  [PGDRG(BC)], [UAG(BC)], [AAG(BC)],
1669 9!                  ACTUAG, [UGA], [AGA], [PGAA], [PGAU],
1670 9!                  PCAA, [UAGC(BC,SUB)], [AAGC(BC,SUB)],
1671 9!                  ACTAEFF, [AUAGC], [AAAGC], PCAE );
1672 9!          IF ACTAEFF THEN
1673 10!$
1674 10!$          PROCESS PSEUDO DISPLACEMENTS FOR EFFECTIVENESS
1675 10!$          CONSTRAINTS
1676 10!$
1677 10!          CALL MAKDVU ( NITER, NDV, GLBDES, [AUAGC], [DKUG],
1678 10!              GMMCT, DKVI );
1679 10!          IF NRSET <> 0 THEN
1680 11!              CALL MAKDVU ( NITER, NDV, GLBDES, [AAAGC], [DMAG],
1681 11!                  GMMCT, DMVI );
1682 11!              [DPGV] := [DKUG] + [DMAG];
1683 11!              CALL MAKDVU ( NITER, NDV, GLBDES, [AUAGC], [DMUG],
1684 11!                  GMMCT, DMVI );

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1685 11! ELSE !
1686 11! [DPGV] := [DKUG]; !
1687 11! ENDIF; !
1688 10!$ !
1689 10!$ REDUCE THE RIGHT HAND SIDES TO THE L SET $!
1690 10!$ !
1691 10! CALL NULLMAT ( [DPNV], [DMUN] ); !
1692 10! IF NMPC <> 0 THEN !
1693 11! CALL GREduce ( , [DPGV], [PGMNS(BC)], [TMN(BC)], !
1694 11! [DPNV]); !
1695 11! IF NRSET <> 0 CALL GREduce ( , [DMUG], !
1696 12! [PGMNS(BC)], [TMN(BC)], [DMUN] ); !
1697 11! ELSE !
1698 11! [DPNV] := [DPGV]; !
1699 11! IF NRSET <> 0 [DMUN] := [DMUG]; !
1700 11! ENDIF; !
1701 10!$ !
1702 10! CALL NULLMAT ( [DPFV], [DMUF] ); !
1703 10! IF NSPC <> 0 THEN !
1704 11! CALL NREDUCE ( , [DPNV], [PNSFS(BC)], [DPFV]; !
1705 11! IF NRSET <> 0 !
1706 12! CALL NREDUCE ( , [DMUN], [PNSFS(BC)], [DMUF]; !
1707 11! ELSE !
1708 11! [DPFV] := [DPGV]; !
1709 11! IF NRSET <> 0 [DMUF] := [DMUN]; !
1710 11! ENDIF; !
1711 10!$ !
1712 10! CALL NULLMAT ( [DPAV], [DMUA] ); !
1713 10! IF NGDR <> 0 THEN !
1714 11! [DPAV] := TRANS ( [GSUBO(BC)] ) * [DPFV]; !
1715 11! IF NRSET <> 0 [DMUA] := TRANS ( [GSUBO(BC)] ) * [DMUF]; !
1716 11! ELSE !
1717 11! IF NOMIT <> 0 THEN !
1718 12! CALL FREDUCE ( , [DPFV], [PFOAS(BC)], 1, !
1719 12! [KOOL(BC,SUB)], [KOOU(BC,SUB)], !
1720 12! [KAO(BC,SUB)], [GASUBO(BC,SUB)], !
1721 12! [DPAV], [DPOV], ); !
1722 12! IF NRSET <> 0 !
1723 13! CALL FREDUCE ( , [DMUF], [PFOAS(BC)], 1, !
1724 13! [KOOL(BC,SUB)], [KOOU(BC,SUB)], !
1725 13! [KAO(BC,SUB)], [GASUBO(BC,SUB)], !
1726 13! [DMUA], [DMUO], ); !
1727 12! ELSE !
1728 12! [DPAV] := [DPFV]; !
1729 12! IF NRSET <> 0 [DMUA] := [DMUF]; !
1730 12! ENDIF; !
1731 11! ENDIF; !
1732 10!$ !
1733 10! IF NRSET <> 0 THEN !
1734 11! CALL ROWPART ( [DPAV], [DPRV], [DPLV], [PARLS(BC)] ); !
1735 11! CALL ROWPART ( [DMUA], [DMUR], [DMUL], [PARLS(BC)] ); !
1736 11! CALL GFBS ( [RL1(BC,SUB)], [RU1(BC,SUB)], !
1737 11! [DPLV], [R11DPL] ); !
1738 11! [DP1] := TRANS ( [D(BC)] ) * [DMUL] + [DMUR] - !
1739 11! [R21(BC,SUB)] * [R11DPL]; !
1740 11! [DRHS] := TRANS ( [D(BC)] ) * [DPLV] + [DPRV] - !
1741 11! [R31(BC,SUB)] * [R11DPL]; !
1742 11!$ !
1743 11!$ PROCESS ACTIVE CONSTRAINTS FOR SAERO DISCIPLINE $!
1744 11!$ !
1745 11! CALL GFBS ( [KL1(BC,SUB)], [KU1(BC,SUB)], !
1746 11! [DP1], [DK1V] ); !
1747 11! [DRHS] := [DRHS] - [K21(BC,SUB)] * [DK1V]; !
1748 11!$ !
1749 11! CALL DECOMP ( [LHSA(BC,SUB)], [LHSL], [LHSU] ); !
1750 11! CALL GFBS ( [LHSL], [LHSU], [DRHS], [DU2] ); !
1751 11!$ !
1752 11! [DU1R] := [DK1V] + [K1112(BC,SUB)] * [DU2]; !
1753 11! [DU1L] := [R11DPL] + [R1112(BC,SUB)] * [DU1R] + !
1754 11! [R1113(BC,SUB)] * [DU2]; !
1755 11! [EFFSENS] := - [R31(BC,SUB)] * [DU1L] - !
1756 11! [R32(BC,SUB)] * [DU1R]; !
1757 11!$ !
1758 11! CALL AEROEFFS ( NITER, BC, SUB, SYM, NDV, CONST, !
1759 11! PCAE, [EFFSENS], [AMAT] ); !
1760 11! ELSE !
1761 11!$ !
1762 11!$ NOTE THAT SAERO W/O SUPPORT IS NOT SUPPORTED $!
1763 11!$ !
1764 11! ENDIF; !
1765 10! ENDIF; $ END IF ON ACTAEFF $!

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1766 91$
1767 91
1768 101$
1769 101$
1770 101$
1771 101$
1772 101$
1773 101
1774 101
1775 101
1776 101$
1777 101$
1778 101$
1779 101$
1780 101
1781 101
1782 101
1783 101
1784 111
1785 111
1786 111
1787 111
1788 111
1789 111
1790 111
1791 111
1792 101$
1793 101$
1794 101$
1795 101
1796 101
1797 111
1798 111
1799 111
1800 121
1801 111
1802 111
1803 111
1804 111
1805 101$
1806 101
1807 101
1808 111
1809 111
1810 121
1811 111
1812 111
1813 111
1814 111
1815 101$
1816 101
1817 101
1818 111
1819 111
1820 111
1821 111
1822 121
1823 121
1824 121
1825 121
1826 121
1827 131
1828 131
1829 131
1830 131
1831 121
1832 121
1833 121
1834 121
1835 111
1836 101$
1837 101
1838 111
1839 111
1840 111
1841 111
1842 111
1843 111
1844 111
1845 111
1846 111$

IF ACTUAG THEN
SENSITIVITIES OF CONSTRAINTS WRT DISPLACEMENTS
FOR SAERO. THE ACTUAGG FLAG WILL BE RETURNED
FALSE IF ONLY TRIM PARAMETER CONSTRAINTS ARE ACTIVE
CALL NULLMAT ( [DFDU] );
CALL MAKDFU ( NITER, BC, GSIZEB, [SMAT], [GLBSIG],
CONST, [DFDU], ACTUAGG, SUB );
SOME RELATIVELY SIMPLE CALCULATIONS THAT PRECEDE
THE LOOP ON THE DESIGN VARIABLES
CALL MAKDVU ( NITER, NDV, GLBDES, [UGA], [DKUG],
GMKCT, DKVI );
CALL NULLMAT ( [DPGV] );
IF NRSET <> 0 THEN
CALL MAKDVU ( NITER, NDV, GLBDES, [AGA], [DMAG],
GMCT, DMVI );
[DPGV] := [DKUG] + [DMAG];
CALL MAKDVU ( NITER, NDV, GLBDES, [UGA], [DMUG],
GMCT, DMVI );
ELSE
[DPGV] := [DKUG];
ENDIF;
REDUCE THE RIGHT HAND SIDES TO THE L SET
CALL NULLMAT ( [DPNV], [DMUN] );
IF NMPC <> 0 THEN
CALL GREduce ( , [DPGV], [PGMNS(BC)], [TMN(BC)],,
[DPNV] );
IF NRSET <> 0 CALL GREduce ( , [DMUG],
[PGMNS(BC)], [TMN(BC)],, [DMUN] );
ELSE
[DPNV] := [DPGV];
IF NRSET <> 0 [DMUN] := [DMUG];
ENDIF;
CALL NULLMAT ( [DPFV], [DMUF] );
IF NSPC <> 0 THEN
CALL NREDUCE ( , [DPNV], [PNSFS(BC)],, [DPFV] );
IF NRSET <> 0
CALL NREDUCE ( , [DMUN], [PNSFS(BC)],, [DMUF] );
ELSE
[DPFV] := [DPGV];
IF NRSET <> 0 [DMUF] := [DMUN];
ENDIF;
CALL NULLMAT ( [DPAV], [DMUA] );
IF NGDR <> 0 THEN
[DPAV] := TRANS( [GSUBO(BC)] ) * [DPFV];
IF NRSET <> 0 [DMUA] := TRANS([GSUBO(BC)]) * [DMUF];
ELSE
IF NOMIT <> 0 THEN
CALL FREDUCE ( , [DPFV], [PFOAS(BC)], 1,
[KOOL(BC,SUB)], [KOOU(BC,SUB)],
[KAO(BC,SUB)], [GASUBO(BC,SUB)], ,
[DPAV], [DPOV], );
IF NRSET <> 0
CALL FREDUCE ( , [DMUF], [PFOAS(BC)], 1,
[KOOL(BC,SUB)], [KOOU(BC,SUB)],
[KAO(BC,SUB)], [GASUBO(BC,SUB)], ,
[DMUA], [DMUO], );
ELSE
[DPAV] := [DPFV];
IF NRSET <> 0 [DMUA] := [DMUF];
ENDIF;
ENDIF;
IF NRSET <> 0 THEN
CALL ROWPART ([DPAV], [DPRV], [DPLV], [PARLS(BC)] );
CALL ROWPART ([DMUA], [DMUR], [DMUL], [PARLS(BC)] );
CALL GFBS ( [RL11(BC,SUB)], [RU11(BC,SUB)],
[DPLV], [R11DPL] );
[DP1] := TRANS([D(BC)]) * [DMUL] + [DMUR] -
[R21(BC,SUB)] * [R11DPL];
[DRHS] := TRANS( [D(BC)] ) * [DPLV] + [DPRV] -
[R31(BC,SUB)] * [R11DPL];

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1847 11!$ PROCESS ACTIVE CONSTRAINTS FOR SAERO DISCIPLINE $!
1848 11!$ $!
1849 11! CALL GFBS ( [K111(BC,SUB)], [K111(BC,SUB)], $!
1850 11! [DP1], [DK1V] ); $!
1851 11! [DRHS] := [DRHS] - [K21(BC,SUB)] * [DK1V]; $!
1852 11!$ $!
1853 11! CALL AEROSENS ( NITER, BC, MINDEX, SUB, CONST, $!
1854 11! SYM, NDV, $!
1855 11! BGPDT(BC), STABCF, [PGAA], $!
1856 11! [LHSA(BC,SUB)], [RHSA(BC,SUB)], $!
1857 11! [DRHS], [AAR], [DDELVDV], [AMAT] ); $!
1858 11!$ $!
1859 11! [DURV] := [K1112(BC,SUB)] * [AAR] + $!
1860 11! [PAR(BC,SUB)] * [DDELVDV] + [DK1V]; $!
1861 11! [DULV] := [R1112(BC,SUB)] * [DURV] + $!
1862 11! [R1113(BC,SUB)] * [AAR] - $!
1863 11! [R11PAL(BC,SUB)] * [DDELVDV] + [R11DPL]; $!
1864 11! CALL ROWMERGE ([DUAV], [DURV], [DULV], [PARLS(BC)]); $!
1865 11! ELSE $!
1866 11!$ $!
1867 11!$ NOTE THAT SAERO W/O SUPPORT IS NOT SUPPORTED $!
1868 11!$ $!
1869 11!$ ENDIF; $!
1870 10!$ $!
1871 10!$ RECOVER SENSITIVITIES TO THE F SET $!
1872 10!$ $!
1873 10! CALL NULLMAT ( [UAFTMP] ); $!
1874 10! IF NGDR <> 0 THEN $!
1875 11! [UAFTMP] := [GASUBO(BC,SUB)] * [DUAV]; $!
1876 11! ELSE $!
1877 11! IF NOMIT <> 0 THEN $!
1878 12! IF NRSET <> 0 THEN $!
1879 13! [TMP1] := [DPOV] + [POARO(BC,SUB)] * [DDELVDV]; $!
1880 13! ELSE $!
1881 13! [TMP1] := [DPOV]; $!
1882 13! ENDIF; $!
1883 12! CALL GFBS ( [KOOL(BC,SUB)], [KOOO(BC,SUB)], $!
1884 12! [TMP1], [UOO] ); $!
1885 12! [UO] := [GASUBO(BC,SUB)] * [DUAV] + [UOO]; $!
1886 12! CALL ROWMERGE ( [UAFTMP], [UO], [DUAV], $!
1887 12! [PFOAS(BC)] ); $!
1888 12! ELSE $!
1889 12! [UAFTMP] := [DUAV]; $!
1890 12! ENDIF; $!
1891 11!$ ENDIF; $!
1892 10! CALL AROSNSMR ( BC, SUB, NDV, [PGAA], [PGAU], [DUFV], $!
1893 10! [UAFTMP] ); $!
1894 10!$ $!
1895 10!$ ENDIF; $ END IF ON ACTUAG $!
1896 9!$ ENDDO; $ END DO ON SUBSCRIPT LOOP $!
1897 8!$ $!
1898 8!$ IF ACTUAGG THEN $!
1899 9!$ $!
1900 9!$ REDUCE THE LEFT HAND SIDE MATRIX $!
1901 9!$ $!
1902 9! CALL NULLMAT ( [DFDUN] ); $!
1903 9! IF NMPC <> 0 THEN $!
1904 10! CALL GREduce ( , [DFDU], [PGMNS(BC)], [TMN(BC)], $!
1905 10! [DFDUN] ); $!
1906 10! ELSE $!
1907 10! [DFDUN] := [DFDU]; $!
1908 10! ENDIF; $!
1909 9!$ $!
1910 9! CALL NULLMAT ( [DFDUF] ); $!
1911 9! IF NSPC <> 0 THEN $!
1912 10! CALL ROWPART ( [DFDUN], , [DFDUF], [PNSFS(BC)] ); $!
1913 10! ELSE $!
1914 10! [DFDUF] := [DFDUN]; $!
1915 10! ENDIF; $!
1916 9!$ $!
1917 9!$ TAKE MERGED SENSITIVITIES OF DISPLACEMENTS AND $!
1918 9!$ COMPUTE THE AMAT MATRIX TERMS FOR THE SAERO $!
1919 9!$ CONSTRAINTS $!
1920 9!$ $!
1921 9! CALL MKAMAT ([AMAT], [DFDUF], [DUFV], PCAA, [PGAU] ); $!
1922 9!$ $!
1923 9!$ ENDIF; $ END IF ON ANY ACTIVE DISPLACEMENTS $!
1924 8!$ ENDIF; $ END IF ON ACTIVE AEROELASTIC CONSTRAINTS $!
1925 7!$ $!
1926 7!$ EVALUATE PANEL BUCKLING CONSTRAINT SENSITIVITIES $!
1927 7!$ $!

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1928 7!          IF ACTPNL THEN
1929 8!          CALL PBKLSSENS ( BC, NITER, NDV, GLBDES, LOCLVAR, {PTRANS},
1930 8!          PDLIST );
1931 8!          ENDF;
1932 7!          IF ACTBAR THEN
1933 8!          CALL EBKLSSENS ( BC, NITER, NDV, GLBDES, LOCLVAR, {PTRANS});
1934 8!          ENDF;
1935 7!          ENDF; $      END IF ON ACTIVE BOUNDARY CONDITION $!
1936 6!          ENDDO; $      END DO ON ACTIVE BOUNDARY CONDITIONS $!
1937 5!$
1938 5!          CALL OFFGRAD ( NITER, NUMOPTBC, [AMAT], GLBDES, CONST, GRADIENT );
1939 5!$
1940 5!          IF NITER >= OCS AND NITER <= OCE THEN
1941 6!          PRINT("LOG=('          VANGO MODULE')");
1942 6!          CALL VANGO ( NITER, NDV, APPCNVRG, MOVLIM, CNVRGLIM,
1943 6!          CTL, CTLMIN, NUMOPTBC, GLBDES, CONST, [AMAT],
1944 6!          DESHIST );
1945 6!          ELSE
1946 6!          IF NITER >= MPS AND NITER <= MPE THEN
1947 7!          PRINT("LOG=('          DESIGN MODULE')");
1948 7!          CALL DESIGN( NITER, NDV, APPCNVRG, MOVLIM, CNVRGLIM,
1949 7!          CTL, CTLMIN, NUMOPTBC, GLBDES, CONST, [AMAT],
1950 7!          DESHIST );
1951 7!          ENDF;
1952 6!          ENDF;
1953 5!$
1954 5!          ENDF; $      END IF ON FSD METHOD $!
1955 4!          ENDF; $      END IF TEST AFTER ACTCON $!
1956 3!          ENDDO; $      END WHILE LOOP FOR GLOBAL CONVERGENCE $!
1957 2!ENDF; $      END IF ON OPTIMIZATION $!
1958 1!$
1959 1!$*****$
1960 1!$      BEGIN FINAL ANALYSIS LOOP $!
1961 1!$*****$
1962 1!$
1963 1!IF NBNDCOND > NUMOPTBC THEN
1964 2!$
1965 2!$ ASSEMBLE THE GLOBAL MATRICES
1966 2!$
1967 2! PRINT("LOG=('*****')");
1968 2!$
1969 2!$ ASSEMBLE THE GLOBAL MATRICES
1970 2!$ BEGIN BOUNDARY CONDITION LOOP
1971 2!$
1972 2! PRINT("LOG=('BEGIN FINAL ANALYSIS')");
1973 2! CALL ANALINIT;
1974 2! CALL EMA2 ( , NDV, GSIZEB, GLBDES, GMKCT, DKVI, [K1GG],
1975 2!          GMMCT, DMVI, [M1GG] );
1976 2! FOR BC = NUMOPTBC + 1 TO NBNDCOND DO
1977 3! PRINT("LOG=('          BOUNDARY CONDITION ',I3)",BC);
1978 3!$
1979 3!$ ESTABLISH THE BASE USET AND PARTITIONING DATA FOR THE BC $!
1980 3!$
1981 3! CALL MKUSET( BC, GSIZEB, [YS(BC)], [TMN(BC)], [PGMN(BC)], [PNSF(BC)],
1982 3!          [PFOA(BC)], [PARL(BC)], USET(BC) );
1983 3!$
1984 3!$ MAKE B.C.-DEPENDENT BGPDT FROM BASE, ADDING THE EXTRA POINTS FOR $!
1985 3!$ THIS B.C. $!
1986 3!$
1987 3! CALL BCBGPD( BC , GSIZEB , BGPDT(BC) , ESIZE(BC) );
1988 3! GSIZE := GSIZEB;
1989 3! PSIZE(BC) := ESIZE(BC) + GSIZE;
1990 3!$
1991 3!$ PROCESS MATRICES, TRANSFER FUNCTIONS, AND INITIAL CONDITIONS FOR $!
1992 3!$ THIS B.C. $!
1993 3!$
1994 3! CALL BCBULK( BC , PSIZE(BC) , BGPDT(BC) , USET(BC) );
1995 3!$
1996 3! CALL BOUND ( BC, GSIZE, ESIZE(BC), USET(BC), BLOAD, BMASS, DMODES,
1997 3!          BMODES, BSAERO, BFLUTR, BDYN, BDRSP, BDTR, BMTR, BDFR,
1998 3!          BMFR, BGUST, BBLAST, NMPC, NSPC, NOMIT, NRSET, NGDR );
1999 3!$
2000 3!$ DETERMINE IF ANY M2GG/K2GG INPUT DATA ARE TO BE ADDED $!
2001 3!$
2002 3! CALL NULLMAT ( [KGG], [MGG] );
2003 3! CALL MK2GG ( BC, GSIZEB, [M2GG], M2GGFLAG, [K2GG], K2GGFLAG );
2004 3! IF M2GGFLAG THEN
2005 4! [MGG] := [M1GG] + [M2GG];
2006 4! ELSE
2007 4! [MGG] := [M1GG];
2008 4! ENDF;

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2009 3! IF K2GGFLAG THEN
2010 4! [KGG] := [K1GG] + [K2GG];
2011 4! ELSE
2012 4! [KGG] := [K1GG];
2013 4! ENDIF;
2014 3!$
2015 3!$ CALL THE GRID POINT WEIGHT GENERATOR FOR THIS BOUNDARY CONDITON
2016 3!$
2017 3! CALL GPWG ( , BC, GPWGGRID, [MGG], OGPWG );
2018 3!$
2019 3! IF BLOAD <> 0 CALL GTLOAD ( , BC, GSIZE, BGPDT(BC), GLBDES,
2020 4! SMPLOD, [DPHVI], [DPGRVI], [PG], OGRIDLOD);
2021 3!$
2022 3!$ PARTITION-REDUCTION OF GLOBAL MATRICES
2023 3!$
2024 3!$***** TAKEN OUT FOR ZAERO *****$! ←
2025 3!$ IF NBNDCOND > 1 CALL NULLMAT ( [KNN], [PN], [MNN], [GTKN], [GSTKN],
2026 4!$ [UGTKN] );
2027 3!$*****
2028 3! IF NBNDCOND > 1 CALL NULLMAT ( [KNN], [PN], [MNN], [UGTKN] ); ←
2029 3! IF NMPC <> 0 THEN
2030 4!$
2031 4!$ PERFORM MPC REDUCTION
2032 4!$
2033 4! PRINT("LOG=(' MPC REDUCTION')");
2034 4! CALL GREduce ( [KGG], [PG], [PGMN(BC)], [TMN(BC)], [KNN], [PN] );
2035 4! IF BMAS <> 0 CALL GREduce ([MGG], [PGMN(BC)], [TMN(BC)], [MNN]);
2036 4!$***** TAKEN OUT FOR ZAERO *****$! ←
2037 4!$ IF BSAERO < 0 THEN
2038 4!$ CALL GREduce ( , [GTKG], [PGMN(BC)], [TMN(BC)], , [GTKN]);
2039 4!$ CALL GREduce ( , [GSTKG], [PGMN(BC)], [TMN(BC)], , [GSTKN]);
2040 4!$ ENDIF;
2041 4!$*****
2042 4! IF BELUTR < 0 OR BGUST < 0 OR BELAST < 0 OR BSAERO < 0 ←
2043 5! CALL GREduce ( , [UGTKG], [PGMN(BC)], [TMN(BC)], , [UGTKN] );
2044 4! ELSE
2045 4!$
2046 4!$ NO MPC REDUCTION
2047 4!$
2048 4! [KNN] := [KGG];
2049 4! IF BLOAD <> 0 [PN] := [PG];
2050 4! IF BMAS <> 0 [MNN] := [MGG];
2051 4!$***** TAKEN OUT FOR ZAERO *****$! ←
2052 4!$ IF BSAERO < 0 THEN
2053 4!$ [GTKN] := [GTKG];
2054 4!$ [GSTKN] := [GSTKG];
2055 4!$ ENDIF;
2056 4!$*****
2057 4! IF BELUTR < 0 OR BGUST < 0 OR BELAST < 0 OR BSAERO < 0 ←
2058 5! [UGTKN] := [UGTKG];
2059 4! ENDIF;
2060 3!$
2061 3!$ PERFORM AUTOSPC CALCULATIONS ON THE KNN MATRIX
2062 3!$
2063 3! PRINT("LOG=(' AUTOSPC COMPUTATIONS')");
2064 3! CALL GPSP ( , BC, NGDR, [KNN], BGPDT(BC), [YS(BC)], USET(BC),
2065 3! GPST(BC) );
2066 3! CALL MKPVECT ( USET(BC), [PGMN(BC)], [PNSF(BC)], [PFOA(BC)], [PARL(BC)] );
2067 3! CALL BOUNDUPD ( BC, GSIZE, ESIZE(BC), USET(BC), NSPC, NOMIT, NRSET );
2068 3!$
2069 3!$***** TAKEN OUT FOR ZAERO *****$! ←
2070 3!$ IF NBNDCOND > 1 CALL NULLMAT ( [KFF], [PF], [MFF], [GTKF], [GSTKF],
2071 4!$ [UGTKF] );
2072 3!$*****
2073 3! IF NBNDCOND > 1 CALL NULLMAT ( [KFF], [PF], [MFF], [UGTKF] ); ←
2074 3! IF NSPC <> 0 THEN
2075 4!$
2076 4!$ PERFORM SPC REDUCTION
2077 4!$
2078 4! PRINT("LOG=(' SPC REDUCTION')");
2079 4! CALL NREDUCE ( [KNN], [PN], [PNSF(BC)], [YS(BC)], [KFF], [KFS],
2080 4! [KSS], [PF], [PS] );
2081 4! IF BMAS <> 0 CALL NREDUCE ( [MNN], , [PNSF(BC)], , [MFF] );
2082 4!$***** TAKEN OUT FOR ZAERO *****$! ←
2083 4!$ IF BSAERO < 0 THEN
2084 4!$ CALL NREDUCE ( , [GTKN], [PNSF(BC)], , , , [GTKF] );
2085 4!$ CALL NREDUCE ( , [GSTKN], [PNSF(BC)], , , , [GSTKF] );
2086 4!$ ENDIF;
2087 4!$*****
2088 4! IF BELUTR < 0 OR BGUST < 0 OR BELAST < 0 OR BSAERO < 0 ←
2089 5! CALL NREDUCE ( , [UGTKN], [PNSF(BC)], , , , [UGTKF] );

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2090 4!      ELSE
2091 4!$
2092 4!$      NO SPC REDUCTION
2093 4!$
2094 4!      [KFF] := [KNN];
2095 4!      IF BLOAD <> 0 [PF] := [PN];
2096 4!      IF BMAS <> 0 [MFF] := [MNN];
2097 4!$***** TAKEN OUT FOR LAERO *****$! ←
2098 4!$      IF BSAERO < 0 THEN
2099 4!$          [GTKF] := [GTKN];
2100 4!$          [GSTKF] := [GSTKN];
2101 4!$      ENDIF;
2102 4!$*****$!
2103 4!      IF BFLUTR < 0 OR BGUST < 0 OR BBLAST < 0 OR BSAERO < 0
2104 5!          [UGTKF] := [UGTKN];
2105 4!      ENDIF;
2106 3!$
2107 3!      IF NBNDCOND > 1 CALL NULLMAT ([KAA], [PA], [MAA], [KAAA], [PAA], [UGTKA]);
2108 3!$
2109 3!      IF NGDR <> 0 THEN
2110 4!$
2111 4!$          PERFORM THE GENERAL DYNAMIC REDUCTION WHICH IS DISCIPLINE
2112 4!$          INDEPENDENT. THE RESULTING [GSUBO] MATRIX WILL BE USED BY
2113 4!$          ALL DISCIPLINES
2114 4!$
2115 4!          PRINT("LOG=('          DYNAMIC REDUCTION')");
2116 4!$
2117 4!$          OBTAIN THE OMITTED DOF PARTITION OF KFF AND MFF
2118 4!$
2119 4!          CALL PARTN ( [KFF], [KOO], , [KOA], , [PFOA(BC)] );
2120 4!          CALL PARTN ( [MFF], [MOO], , , [PFOA(BC)] );
2121 4!          ASIZE := GSIZE - NMPC - NSPC - NOMIT;
2122 4!          LSIZE := ASIZE - NRSET;
2123 4!          CALL GDR1 ( [KOO], [MOO], [KSOO], [GGO], LKSET, LJSET, NEIV,
2124 4!                  FMAX, BC, BGPDT(BC), USET(BC), NOMIT, LSIZE );
2125 4!$
2126 4!$          LKSET      MEANING
2127 4!$          <> 0      APPROX. MODE SHAPES SELECTED
2128 4!$          = 0      NO APPROX. MODE SHAPES IN GDR
2129 4!$
2130 4!          IF LKSET <> 0 THEN
2131 5!              CALL SDCOMP ( [KSOO], [LSOO], USET(BC), SINGOSET );
2132 5!              CALL GDR2 ( [LSOO], [MOO], [PHIOK], LKSET, LJSET,
2133 5!                      NEIV, FMAX, BC );
2134 5!          ENDIF;
2135 4!          CALL GDR3 ( [KOO], [KOA], [MGG], [PHIOK], [TMN(BC)], [GGO],
2136 4!                  [PGMN(BC)], [PNSF(BC)], [PFOA(BC)], [GSUBO(BC)],
2137 4!                  BGPDT(BC), USET(BC),
2138 4!                  LKSET, LJSET, ASIZE, GNORM, BC );
2139 4!          CALL GDR4 ( BC, GSIZE, PSIZE(BC), LKSET, LJSET, NUMOPTBC, NBNDCOND,
2140 4!                  [PGMN(BC)], [TMN(BC)], [PNSF(BC)], [PFOA(BC)],
2141 4!                  [PARL(BC)], [PGDRG(BC)], [PAJK], [PFJK], BGPDT(BC),
2142 4!                  USET(BC) );
2143 4!      ENDIF;
2144 3!$
2145 3!      IF BLOAD <> 0 OR BMODES <> 0 OR BFLUTR <> 0 OR BDN <> 0 THEN
2146 4!$
2147 4!$          REDUCE THE MATRICES WITHOUT AEROELASTIC CORRECTIONS
2148 4!$
2149 4!          IF NGDR <> 0 THEN
2150 5!$
2151 5!$          PERFORM THE GENERAL DYNAMIC REDUCTION
2152 5!$
2153 5!          PRINT("LOG=('          SYMMETRIC DYNAMIC REDUCTION')");
2154 5!$
2155 5!          [MAA] := TRANS ( [GSUBO(BC)] ) * [ [MFF] * [GSUBO(BC)] ];
2156 5!          [KAA] := TRANS ( [GSUBO(BC)] ) * [ [KFF] * [GSUBO(BC)] ];
2157 5!          IF BLOAD <> 0 [PA] := TRANS ( [GSUBO(BC)] ) * [PF];
2158 5!          IF BFLUTR <> 0 OR BGUST <> 0 OR BBLAST <> 0 THEN
2159 6!              [TMP1] := TRANS ( [UGTKF] ) * [GSUBO(BC)];
2160 6!              CALL TRNPOSE ( [TMP1], [UGTKA] );
2161 6!          ENDIF;
2162 5!      ELSE
2163 5!          IF NOMIT <> 0 THEN
2164 6!$
2165 6!$          PERFORM THE STATIC REDUCTION
2166 6!$
2167 6!          PRINT("LOG=('          STATIC CONDENSATION')");
2168 6!$
2169 6!          CALL FREDUCE ( [KFF], [PF], [PFOA(BC)], , [KOOINV(BC)], , ,
2170 6!                  [GSUBO(BC)], [KAA], [PA], [PO], USET(BC) );

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```

2171 61$ IF BMASS <> 0 THEN $!
2172 61$ $!
2173 71$ $!
2174 71$ PERFORM GUYAN REDUCTION OF THE MASS MATRIX $!
2175 71$ $!
2176 71$ CALL PARTN ( [MFF], [MOO], , [MOA], [MAABAR], [PFOA(BC)] ); $!
2177 71$ [MAA] := [MAABAR] + TRANS([MOA]) * [GSUBO(BC)] + $!
2178 71$ TRANS([GSUBO(BC)]) * [MOA] + $!
2179 71$ TRANS([GSUBO(BC)]) * [ [MOO] * [GSUBO(BC)] ]; $!
2180 71$ IF NRSET <> 0 [IFM(BC)] := [MOO] * [GSUBO(BC)] + [MOA]; $!
2181 71$ ENDIF; $!
2182 61$ IF BFLUTR <> 0 OR BGUST <> 0 OR BBLAST <> 0 THEN $!
2183 71$ CALL ROWPART ( [UGTKF], [UGTKO], [UGTKAB], [PFOA(BC)] ); $!
2184 71$ [TMP1] := TRANS( [UGTKO] ) * [GSUBO(BC)]; $!
2185 71$ CALL TRNSPOSE ( [TMP1], [TMP2] ); $!
2186 71$ [UGTKA] := [UGTKAB] + [TMP2]; $!
2187 71$ ENDIF; $!
2188 61$ ELSE $!
2189 61$ $!
2190 61$ NO F-SET REDUCTION $!
2191 61$ $!
2192 61$ [KAA] := [KFF]; $!
2193 61$ IF BLOAD <> 0 [PA] := [PF]; $!
2194 61$ IF BFLUTR <> 0 OR BGUST <> 0 OR BBLAST <> 0 [UGTKA]:=[UGTKF]; $!
2195 61$ IF BMASS <> 0 [MAA] := [MFF]; $!
2196 61$ ENDIF; $!
2197 51$ ENDIF; $!
2198 41$ $!
2199 41$ IF NRSET <> 0 THEN $!
2200 51$ $!
2201 51$ PERFORM THE SUPPORT SET REDUCTION $!
2202 51$ $!
2203 51$ PRINT("LOG=(' SUPPORT REDUCTION')"); $!
2204 51$ CALL PARTN ( [KAA], [KRR], [KLR], , [KLL], [PARL(BC)] ); $!
2205 51$ CALL SDCOMP ( [KLL], [KLLINV(BC)], USET(BC), SINGLSET ); $!
2206 51$ CALL FBS ( [KLLINV(BC)], [KLR], [D(BC)], -1 ); $!
2207 51$ CALL RBCHECK ( BC, USET(BC), BGPDT(BC), [D(BC)], [KLL], $!
2208 51$ [KRR], [KLR] ); $!
2209 51$ $!
2210 51$ CALCULATE THE REDUCED MASS MATRIX $!
2211 51$ $!
2212 51$ CALL PARTN ([MAA], [MRRBAR], [MLR], , [MLL], [PARL(BC)]); $!
2213 51$ [IFR(BC)] := [MLL] * [D(BC)] + [MLR]; $!
2214 51$ [MRR(BC)] := [MRRBAR] + TRANS ( [MLR] ) * [D(BC)] + $!
2215 51$ TRANS ( [D(BC)] ) * [IFR(BC)]; $!
2216 51$ [R22] := TRANS ( [D(BC)] ) * [MLR] + [MRRBAR]; $!
2217 51$ $!
2218 51$ IF BLOAD <> 0 THEN $!
2219 61$ $!
2220 61$ PROCESS STATICS WITH INERTIA RELIEF $!
2221 61$ $!
2222 61$ PRINT("LOG=(' >>>DISCIPLINE: STATICS(INERTIA RELIEF)')"); $!
2223 61$ CALL ROWPART ( [PA], [PR], [PLBAR], [PARL(BC)] ); $!
2224 61$ [LHS(BC)] := [MRR(BC)]; $!
2225 61$ [RHS(BC)] := TRANS([D(BC)]) * [PLBAR] + [PR]; $!
2226 61$ CALL INERTIA ( [LHS(BC)], [RHS(BC)], [AR] ); $!
2227 61$ [AL] := [D(BC)] * [AR]; $!
2228 61$ CALL ROWMERGE ( [AA], [AR], [AL], [PARL(BC)] ); $!
2229 61$ [RHS(BC)] := [PLBAR] - [IFR(BC)] * [AR]; $!
2230 61$ CALL FBS ( [KLLINV(BC)], [RHS(BC)], [UL] ); $!
2231 61$ CALL YSMERGE ( [UA], , [UL], [PARL(BC)] ); $!
2232 61$ ENDIF; $!
2233 51$ IF BMODES <> 0 THEN $!
2234 61$ PRINT("LOG=(' >>>DISCIPLINE: NORMAL MODES')"); $!
2235 61$ CALL REIG ( , BC, USET(BC), [KAA], [MAA], [MRR(BC)], $!
2236 61$ [D(BC)], LAMBDA, [PHIA], [MII], HSIZE(BC) ); $!
2237 61$ CALL OFFPMROOT ( , BC, NUMOPTBC, LAMBDA ); $!
2238 61$ ENDIF; $!
2239 51$ ELSE $!
2240 51$ $!
2241 51$ NO SUPPORT SET REDUCTION $!
2242 51$ $!
2243 51$ IF BLOAD <> 0 THEN $!
2244 61$ PRINT("LOG=(' >>>DISCIPLINE: STATICS')"); $!
2245 61$ CALL SDCOMP ( [KAA], [KLLINV(BC)], USET(BC), SINGASET ); $!
2246 61$ CALL FBS ( [KLLINV(BC)], [PA], [UA] ); $!
2247 61$ ENDIF; $!
2248 51$ IF BMODES <> 0 THEN $!
2249 61$ PRINT("LOG=(' >>>DISCIPLINE: NORMAL MODES')"); $!
2250 61$ CALL REIG ( , BC, USET(BC), [KAA], [MAA], , , LAMBDA, $!
2251 61$ [PHIA], [MII], HSIZE(BC) ); $!

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2252 6!          CALL OFFPMROOT ( , BC, NUMOPTBC, LAMBDA );
2253 6!          ENDIF;
2254 5!          ENDIF;
2255 4!          ENDIF;
2256 3!$
2257 3!          IF BSAERO <> 0 THEN
2258 4!$
2259 4!$          PERFORM STATIC AEROELASTIC ANALYSES
2260 4!$
2261 4!          PRINT("LOG=('          SAERO INITIALIZATION')");
2262 4!$***** TAKEN OUT FOR ZAERO *****$! ←
2263 4!$          CALL TRNSPOSE ( [GSTKF], [GSKF] );
2264 4!$*****$!
2265 4!          CALL TRNSPOSE ( [UGTKF], [GSKF] );
2266 4!          LOOP := TRUE;
2267 4!          SUB := 0;
2268 4!          WHILE LOOP DO
2269 5!              SUB := SUB + 1;
2270 5!              CALL SAERODRV (BC, SUB, LOOP, MINDEX, SYM, MACH, QDP, 1 );
2271 5!$
2272 5!$          ADJUST THE KFF MATRIX AND DETERMINE THE RIGID AIR LOADS
2273 5!$
2274 5!$***** TAKEN OUT FOR ZAERO *****$! ←
2275 5!$          IF SYM = 1 [AICS] := [GSTKF]*[TRANS([AICMAT(MINDEX)])]*[GSKF];
2276 5!$          IF SYM = -1 [AICS] := [GSTKF]*[TRANS([AAICMAT(MINDEX)])]*[GSKF];
2277 5!$          [PAF] := (QDP) [ [GSTKF] * [AIRFRM(MINDEX)] ];
2278 5!$*****$!
2279 5!          IF SYM = 1 [AICS] := [UGTKF]*[TRANS([AICMAT(MINDEX)])]*[GSKF];
2280 5!          IF SYM = -1 [AICS] := [UGTKF]*[TRANS([AAICMAT(MINDEX)])]*[GSKF];
2281 5!          [PAF] := (QDP) [ [UGTKF] * [AIRFRM(MINDEX)] ];
2282 5!          [KAFF] := [KFF] - (QDP) [AICS];
2283 5!$
2284 5!$          REDUCE THE MATRICES WITH AEROELASTIC CORRECTIONS
2285 5!$          SAVE THE SUBCASE/BC DEPENDENT DATA FOR SENSITIVITY ANALYSIS
2286 5!$
2287 5!          IF NGDR <> 0 THEN
2288 6!$
2289 6!$          PERFORM THE GENERAL DYNAMIC REDUCTION
2290 6!$
2291 6!          PRINT("LOG=('          SAERO DYNAMIC REDUCTION')");
2292 6!          [MAAA] := TRANS ( [GSUBO(BC)] ) * [ [MFF] * [GSUBO(BC)] ];
2293 6!          [KAAA] := TRANS ( [GSUBO(BC)] ) * [ [KAFF] * [GSUBO(BC)] ];
2294 6!          [PAA] := TRANS ( [GSUBO(BC)] ) * [PAF];
2295 6!          ELSE
2296 6!          IF NOMIT <> 0 THEN
2297 7!$
2298 7!$          PERFORM THE STATIC REDUCTION
2299 7!$
2300 7!          PRINT("LOG=('          SAERO STATIC CONDENSATION')");
2301 7!$
2302 7!          IF NRSET <> 0 AND SUB = 1 AND BLOAD = 0 AND BMODES = 0 AND
2303 8!          BFLUTR = 0 AND BDOYN = 0 THEN
2304 8!$
2305 8!$          FORM [KAA] ON SO [D] CAN BE FORMED
2306 8!$
2307 8!          CALL FREDUCE ([KFF], , [PFOA(BC)], , [KOOINV(BC)], , ,
2308 8!          [GSUBO(BC)], [KAA], , , USET(BC) );
2309 8!          ENDIF;
2310 7!$
2311 7!          CALL FREDUCE ( [KAFF], [PAF], [PFOA(BC)], BSAERO,
2312 7!          [KOOL(BC,SUB)], [KOOU(BC,SUB)],
2313 7!          [KAO(BC,SUB)], [GASUBO(BC,SUB)], [KAAA],
2314 7!          [PAA], [POARO(BC,SUB)], USET(BC) );
2315 7!$
2316 7!          IF BMASS <> 0 THEN
2317 8!$
2318 8!$          PERFORM GUYAN REDUCTION OF THE MASS MATRIX
2319 8!$
2320 8!          CALL PARTN ( [MFF], [MOO], , [MOA], [MAABAR],
2321 8!          [PFOA(BC)] );
2322 8!          [MAAA] := [MAABAR] + TRANS([MOA]) * [GASUBO(BC,SUB)] +
2323 8!          TRANS([GASUBO(BC,SUB)]) * [MOA] +
2324 8!          TRANS([GASUBO(BC,SUB)]) * [[MOO] *
2325 8!          [GASUBO(BC,SUB)]];
2326 8!          IF NRSET <> 0
2327 9!          [IFMA(BC,SUB)] := [MOO]*[GASUBO(BC,SUB)]+[MOA];
2328 8!          ENDIF;
2329 7!          ELSE
2330 7!$
2331 7!$          NO F-SET REDUCTION
2332 7!$

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2333 7! IF NRSET <> 0 AND SUB = 1 AND BLOAD = 0 AND
2334 8! BMODES = 0 AND BFLUTR = 0 AND BLDYN = 0 THEN
2335 8!$
2336 8!$ FORM [KAA] ON FIRST PASS SO [D] CAN BE FORMED
2337 8!$
2338 8! [KAA] := [KFF];
2339 8! ENDIF;
2340 7! [KAAA] := [KAFF];
2341 7! [MAAA] := [MFF];
2342 7! [PAA] := [PAF];
2343 7! ENDIF;
2344 6! ENDIF;
2345 5!$
2346 5! IF NRSET <> 0 THEN
2347 6!$
2348 6!$ PERFORM THE SUPPORT SET REDUCTION
2349 6!$
2350 6!$ PRINT("LOG=(' SAERO SUPPORT REDUCTION')");
2351 6!$
2352 6! IF SUB = 1 AND BLOAD = 0 AND BMODES = 0 AND BFLUTR = 0
2353 7! AND BLDYN = 0 THEN
2354 7!$
2355 7!$ [D] WAS NOT COMPUTED FOR NON-SAERO DISCIPLINES SO
2356 7!$ NEED TO COMPUTE IT NOW
2357 7!$
2358 7! CALL PARTN ( [KAA], [KRR], [KLR], , [KLL], [PARL(BC)] );
2359 7! CALL SDCOMP ( [KLL], [KLLINV(BC)], USET(BC), SINGLSET );
2360 7! CALL FBS ( [KLLINV(BC)], [KLR], [D(BC)], -1 );
2361 7! CALL RBCHECK ( BC, USET(BC), BGPDT(BC), [D(BC)], [KLL],
2362 7! [KRR], [KLR] );
2363 7! ENDIF;
2364 6!$
2365 6!$ CALCULATE THE REDUCED MASS MATRIX
2366 6!$
2367 6! CALL PARTN ([MAAA], [MRRBAR], [MLR], , [MLL], [PARL(BC)]);
2368 6! [R13(BC,SUB)] := [MLL] * [D(BC)] + [MLR];
2369 6! [R33] := [MRRBAR] + TRANS ( [MLR] ) * [D(BC)] +
2370 6! TRANS ( [D(BC)] ) * [R13(BC,SUB)];
2371 6! [R22] := TRANS ( [D(BC)] ) * [MLR] + [MRRBAR];
2372 6! CALL TRNPOSE ( [R13(BC,SUB)], [R21(BC,SUB)] );
2373 6!$
2374 6!$ PROCESS STEADY AEROELASTIC DISCIPLINE
2375 6!$
2376 6! PRINT("LOG=(' >>>DISCIPLINE: STEADY AERO')");
2377 6! CALL PARTN ( [KAAA], [KARR], [R12(BC,SUB)], [KARL], [R11],
2378 6! [PARL(BC)] );
2379 6! [R32(BC,SUB)] := TRANS([D(BC)]) * [R12(BC,SUB)] + [KARR];
2380 6! [R31(BC,SUB)] := TRANS([D(BC)]) * [R11] + [KARL];
2381 6!$
2382 6! CALL DECOMP ( [R11], [RL11(BC,SUB)], [RU11(BC,SUB)] );
2383 6!$
2384 6! CALL ROWPART ( [PAA], [PARBAR], [PAL], [PARL(BC)] );
2385 6! CALL GFBS ( [RL11(BC,SUB)], [RU11(BC,SUB)], [PAL],
2386 6! [R11PAL(BC,SUB)], -1 );
2387 6! [PRIGID] := [PARBAR] + TRANS([D(BC)]) * [PAL];
2388 6! [P1] := [R21(BC,SUB)] * [R11PAL(BC,SUB)];
2389 6! [P2] := [PRIGID] + [R31(BC,SUB)] * [R11PAL(BC,SUB)];
2390 6!$
2391 6! CALL GFBS ( [RL11(BC,SUB)], [RU11(BC,SUB)], [R12(BC,SUB)],
2392 6! [R1112(BC,SUB)], -1 );
2393 6! CALL GFBS ( [RL11(BC,SUB)], [RU11(BC,SUB)], [R13(BC,SUB)],
2394 6! [R1113(BC,SUB)], -1 );
2395 6! [K11] := [R22] + [R21(BC,SUB)] * [R1112(BC,SUB)];
2396 6! [K12(BC,SUB)] := [R21(BC,SUB)] * [R1113(BC,SUB)];
2397 6! [K21(BC,SUB)] := [R32(BC,SUB)] + [R31(BC,SUB)] * [R1112(BC,SUB)];
2398 6! [K22] := [R33] + [R31(BC,SUB)] * [R1113(BC,SUB)];
2399 6!$
2400 6! CALL DECOMP ( [K11], [KL11(BC,SUB)], [KU11(BC,SUB)] );
2401 6! CALL GFBS ( [KL11(BC,SUB)], [KU11(BC,SUB)], [P1],
2402 6! [PAR(BC,SUB)] );
2403 6! CALL GFBS ( [KL11(BC,SUB)], [KU11(BC,SUB)], [K12(BC,SUB)],
2404 6! [K1112(BC,SUB)], -1 );
2405 6! [LHSA(BC,SUB)] := [K22] + [K21(BC,SUB)] * [K1112(BC,SUB)];
2406 6! [RHSA(BC,SUB)] := [P2] - [K21(BC,SUB)] * [PAR(BC,SUB)];
2407 6! CALL SAERO ( , BC, MINDEX, SUB, SYM, QDP, STABCF,
2408 6! BGPDT(BC), [LHSA(BC,SUB)], [RHSA(BC,SUB)], [AAR],
2409 6! [DELTA(SUB)], [PRIGID], [R33] );
2410 6! [AAL] := [D(BC)] * [AAR];
2411 6! CALL ROWMERGE ( [AAA(SUB)], [AAR], [AAL], [PARL(BC)] );
2412 6! [UAR] := [K1112(BC,SUB)] * [AAR] + [PAR(BC,SUB)] *
2413 6! [DELTA(SUB)];

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2414 6!          [UAL] := [R1112(BC,SUB)] * [UAR] + [R1113(BC,SUB)] * [AAR]      !
2415 6!          - [R11PAL(BC,SUB)] * [DELTA(SUB)];                          !
2416 6!          CALL ROWMERGE ( [UAA(SUB)], [UAR], [UAL], [PARL(BC)] );        !
2417 6!          IF NOMIT <> 0 [PAO(SUB)] := [POARO(BC,SUB)] * [DELTA(SUB)] ;    !
2418 6!          ELSE                                                                !
2419 6!$          NO SUPPORT SET REDUCTION                                         !$
2420 6!$          NO SUPPORT SET REDUCTION                                         !$
2421 6!$          NO SUPPORT SET REDUCTION                                         !$
2422 6!$          NO SUPPORT SET REDUCTION                                         !$
2423 6!$          NO SUPPORT SET REDUCTION                                         !$
2424 6!$          NO SUPPORT SET REDUCTION                                         !$
2425 6!          PRINT("LOG=('          >>>DISCIPLINE: STEADY AERO')");          !
2426 6!          ENDDO;                                                            !
2427 5!          ENDDO;                                                            !
2428 4!          ENDDO;                                                            !
2429 3!$          NO SUPPORT SET REDUCTION                                         !$
2430 3!$          NO SUPPORT SET REDUCTION                                         !$
2431 3!$          NO SUPPORT SET REDUCTION                                         !$
2432 3!$          NO SUPPORT SET REDUCTION                                         !$
2433 3!          IF BDRSP <> 0 THEN                                                !
2434 4!          IF BFLUTR <> 0 THEN                                                !
2435 5!          PRINT("LOG=('          >>>DISCIPLINE: FLUTTER')");              !
2436 5!          SUB := 0;                                                         !
2437 5!          LOOP := TRUE;                                                      !
2438 5!          WHILE LOOP DO                                                      !
2439 6!          SUB := SUB + 1;                                                      !
2440 6!          CALL FLUTDRV ( BC, SUB, LOOP );                                    !
2441 6!          CALL FLUTQHHZ ( , BC, SUB, ESIZE(BC), PSIZE(BC), [AJK],          ! ←
2442 6!          [SKJ], [UGTKA], [PHIA], USET(BC),                                  !
2443 6!          [TMN(BC)], [GSUBO(BC)], NGDR, AECOMPU, GEOMUA,                    !
2444 6!          [PHIKH], [QHHFL(BC,SUB)], OAGRDDSP );                              ! ←
2445 6!          CALL FLUTDMA ( , BC, SUB, ESIZE(BC), PSIZE(BC), BGPDT(BC),      !
2446 6!          USET(BC), [MAA], [KAA], [TMN(BC)], [GSUBO(BC)],                  !
2447 6!          NGDR, LAMBDA, [PHIA], [MHHFL(BC,SUB)],                          !
2448 6!          [BHHFL(BC,SUB)], [KHHFL(BC,SUB)] );                                !
2449 6!          CALL FLUTTRAZ ( , BC, SUB, [QHHFL(BC,SUB)], LAMBDA, HSIZE(BC),  ! ←
2450 6!          ESIZE(BC), [MHHFL(BC,SUB)], [BHHFL(BC,SUB)],                  !
2451 6!          [KHHFL(BC,SUB)], CLAMBDA, ,AEROZ );                                ! ←
2452 6!          ENDDO;                                                            !
2453 5!          ENDDO;                                                            !
2454 4!          IF BDRSP <> 0 THEN                                                !
2455 5!          IF BMTR <> 0 OR BDTR <> 0 THEN                                        !
2456 6!          PRINT("LOG=('          >>>DISCIPLINE: TRANSIENT RESPONSE')");      !
2457 6!          ENDDO;                                                            !
2458 5!          IF BMFR <> 0 OR BDFR <> 0 THEN                                        !
2459 6!          PRINT("LOG=('          >>>DISCIPLINE: FREQUENCY RESPONSE')");      !
2460 6!          ENDDO;                                                            !
2461 5!$          CALL QHHLGEN (BC, ESIZE(BC), [QKHL], [QKJL], [UGTKA], [PHIA],  ! ←
2462 5!$          [PHIKH], [QHHL], [QKJL]);                                         !$
2463 5!$          CALL QHHLGEN2 (BC, ESIZE(BC), [AJK], [SKJ], [QK], [UGTKA], [PHIA], !
2464 5!$          [PHIKH], [QHHL], [QKJL], AEROZ );                                ! ←
2465 5!          CALL DMA ( , BC, ESIZE(BC), PSIZE(BC), BGPDT(BC), USET(BC), [MAA], !
2466 5!          [KAA], [TMN(BC)], [GSUBO(BC)], NGDR,                             !
2467 5!          LAMBDA, [PHIA], [MDD], [BDD], [KDDT], [KDDF],                    !
2468 5!          [MHH], [BHH], [KHHT], [KHHF] );                                    !
2469 5!          CALL DYNLOAD ( , BC, GSIZE, ESIZE(BC), PSIZE(BC), SMPLOD, BGPDT(BC), !
2470 5!          USET(BC), [TMN(BC)], [GSUBO(BC)],                                !
2471 5!          NGDR, [PHIA], [QHHL], [PDT], [PDF],                               !
2472 5!          [PTGLOAD], [PTHLOAD], [PFGLOAD], [PFHLOAD] );                    !
2473 5!          CALL DYNRSP (BC, ESIZE(BC), [MDD], [BDD], [KDDT], [KDDF],        !
2474 5!          [MHH], [BHH], [KHHT], [KHHF], [PDT], [PDF],                     !
2475 5!          [QHHL], [UTRANA], [UFREQA], [UTRANI], [UFREQI],                  !
2476 5!          [UTRANE], [UFREQE] );                                              !
2477 5!          IF BMTR <> 0 [UTRANA] := [PHIA] * [UTRANI];                      !
2478 5!          IF BMFR <> 0 [UFREQA] := [PHIA] * [UFREQI];                      !
2479 5!          ENDDO;                                                            !
2480 4!          ENDDO;                                                            !
2481 3!          IF BBLAST <> 0 THEN                                                !
2482 4!          PRINT("LOG=('          >>>DISCIPLINE: BLAST')");                  !
2483 4!          CALL BLASTFIT ( BC, [QJL], [MATR], [MATSS], BQDP, [BFR],          !
2484 4!          [DWNWSH], HSIZE(BC), [ID2], [MPART], [UGTKA],                    !
2485 4!          [BLGTJA], [BLSTJA] );                                              !
2486 4!          CALL COLPART ( [PHIA], , [PHIE], [MPART] );                      !
2487 4!          CALL ROWMERGE ( [PHIR], [ID2], [D(BC)], [PARL(BC)] );            !
2488 4!          CALL COLMERGE ( [PHIB], [PHIR], [PHIE], [MPART] );                !
2489 4!          [GENM] := TRANS ( [PHIB] ) * [ [MAA] * [PHIB] ];                  !
2490 4!          [GENK] := TRANS ( [PHIB] ) * [ [KAA] * [PHIB] ];                  !
2491 4!          [DTSLP] := TRANS ( [BLSTJA] ) * [PHIB];                          !
2492 4!          [FTF] := TRANS ( [PHIB] ) * [BLGTJA];                             !
2493 4!          [FTF] := TRANS ( [PHIB] ) * [BLGTJA];                             !
2494 4!          [FTF] := TRANS ( [PHIB] ) * [BLGTJA];                             !

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2495 4! [GENF] := (BQDP) [FTF] * [BFRG];
2496 4! [GENFA] := (BQDP) [FTF] * [MATSS];
2497 4! [GENQ] := [GENFA] * [DTSLP];
2498 4! [GENQL] := (BQDP) [FTF] * [MATTR];
2499 4! CALL PARTN ( [GENQ],[QRR] , , [QRE], [QEE], [MPART] );
2500 4! CALL PARTN ( [GENK], , , [KEE], [MPART] );
2501 4! [KEQE] := [QEE] + [KEE];
2502 4! CALL DECOMP ( [KEQE], [LKQ], [UKQ] );
2503 4! CALL ROWPART ( [GENF], [GFR], [GFE], [MPART] );
2504 4! CALL GFBS ( [LKQ], [UKQ], [GFE], [BTEM] );
2505 4! [DELM] := -[QRE] * [BTEM] + [GFR];
2506 4! CALL BLASTRIM ( BC, [DELM], [MRR(BC)], [URDB], [DELB] );
2507 4! [ELAS] := [BTEM] * [DELB];
2508 4! [SLPMOD] := TRANS ( [BLSTJA] ) * [PHIE];
2509 4! CALL BLASTDRV ( BC, [GENM], [GENK], [GENFA], [GENQL], [DELB],
2510 4! [URDB], [DWNWSH], [SLPMOD], [ELAS], [UBLASTI] );
2511 4!
2512 3!$ ENDIF;
2513 3!$ BEGIN THE DATA RECOVERY OPERATIONS
2514 3!$
2515 3! IF NBNDCOND > 1 CALL NULLMAT ( [UF], [AF], [PHIF] );
2516 3! IF NGDR <> 0 THEN
2517 4!$ DATA RECOVERY WITH GDR
2518 4!$ APPEND THE GDR-GENERATED DOFS TO THE F-SET
2519 4!$
2520 4!$ PRINT("LOG=(' DYNAMIC REDUCTION RECOVERY')");
2521 4! IF BLOAD <> 0 THEN
2522 4! [UFGDR] := [GSUBO(BC)] * [UA];
2523 5! CALL ROWPART ( [UA], [UJK], , [PAJK] );
2524 5! CALL ROWMERGE ( [UF], [UJK], [UFGDR], [PFJK] );
2525 5! IF NRSET <> 0 THEN
2526 5! [AFGDR] := [GSUBO(BC)] * [AA];
2527 6! CALL ROWPART ( [AA], [UJK], , [PAJK] );
2528 6! CALL ROWMERGE ( [AF], [UJK], [AFGDR], [PFJK] );
2529 6!
2530 6! ENDF;
2531 5! ENDF;
2532 4! IF BSAERO <> 0 THEN
2533 5! FOR S = 1 TO SUB DO
2534 6! [UFGDR] := [GSUBO(BC)] * [UAA(S)];
2535 6! CALL ROWPART ( [UAA(S)], [UJK], , [PAJK] );
2536 6! CALL ROWMERGE ( [UAFTMP], [UJK], [UFGDR], [PFJK] );
2537 6!$
2538 6!$ MERGE THE CURRENT SUBCASE DEPENDENT RESULTS INTO A SINGLE
2539 6!$ MATRIX OF RESPONSE QUANTITIES FOR FURTHER RECOVERY
2540 6!$
2541 6! CALL SAEROMRG ( BC, S, [UAF], [UAFTMP] );
2542 6! IF NRSET <> 0 THEN
2543 7! [AFGDR] := [GSUBO(BC)] * [AAA(S)];
2544 7! CALL ROWPART ( [AAA(S)], [UJK], , [PAJK] );
2545 7! CALL ROWMERGE ( [AAFTMP], [UJK], [AFGDR], [PFJK] );
2546 7! CALL SAEROMRG ( BC, S, [AAF], [AAFTMP] );
2547 7! ENDF;
2548 6! ENDDO;
2549 5! ENDF;
2550 4! IF BMODES <> 0 THEN
2551 5! [UFGDR] := [GSUBO(BC)] * [PHIA];
2552 5! CALL ROWPART ( [PHIA], [UJK], , [PAJK] );
2553 5! CALL ROWMERGE ( [PHIF], [UJK], [UFGDR], [PFJK] );
2554 5! ENDF;
2555 4! IF BDTR <> 0 OR BMTR <> 0 THEN
2556 5! [UFGDR] := [GSUBO(BC)] * [UTRANA];
2557 5! CALL ROWPART ( [UTRANA], [UJK], , [PAJK] );
2558 5! CALL ROWMERGE ( [UTRANF], [UJK], [UFGDR], [PFJK] );
2559 5! ENDF;
2560 4! IF BDFR <> 0 OR BMFR <> 0 THEN
2561 5! [UFGDR] := [GSUBO(BC)] * [UFREQA];
2562 5! CALL ROWPART ( [UFREQA], [UJK], , [PAJK] );
2563 5! CALL ROWMERGE ( [UFREQF], [UJK], [UFGDR], [PFJK] );
2564 5! ENDF;
2565 4! ELSE
2566 4! IF NOMIT <> 0 THEN
2567 5!$ DATA RECOVERY WITH STATIC CONDENSATION
2568 5!$
2569 5!$ PRINT("LOG=(' STATIC CONDENSATION RECOVERY')");
2570 5! IF BLOAD <> 0 THEN
2571 5! CALL RECOVA ( [UA], [PO], [GSUBO(BC)], NRSET, [AA],
2572 6! [IFM(BC)], , [KOOINV(BC)], [PFOA(BC)], [UF] );
2573 6! IF NRSET <> 0 CALL RECOVA ( [AA], , [GSUBO(BC)], , ,
2574 6! [PFOA(BC)], [AF] );
2575 7!

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2576 6!      ENDIF;
2577 5!      IF BSAERO <> 0 THEN
2578 6!          FOR S = 1 TO SUB DO
2579 7!              CALL RECOVA ( [UAA(S)], [PAO(S)], [GASUBO(BC,S)],
2580 7!                  NRSET, [AAA(S)], [IFMA(BC,S)], BSAERO,
2581 7!                  [KOOL(BC,S)], [KOOU(BC,S)],
2582 7!                  [PFOA(BC)], [UAFTMP] );
2583 7!$
2584 7!$      MERGE THE CURRENT SUBCASE DEPENDENT RESULTS INTO A SINGLE
2585 7!$      MATRIX OF RESPONSE QUANTITIES FOR FURTHER RECOVERY
2586 7!$
2587 7!      CALL SAEROMRG ( BC, S, [UAF], [UAFTMP] );
2588 7!      IF NRSET <> 0 THEN
2589 8!          CALL RECOVA ( [AAA(S)], [GASUBO(BC,S)], [PFOA(BC)], [UAFTMP] );
2590 8!          CALL SAEROMRG ( BC, S, [AAF], [UAFTMP] );
2591 8!      ENDIF;
2592 8!      ENDDO;
2593 7!
2594 6!      ENDIF;
2595 5!      IF BMODES <> 0 THEN
2596 6!          [PHIO] := [GASUBO(BC)] * [PHIA];
2597 6!          CALL ROWMERGE ( [PHIF], [PHIO], [PHIA], [PFOA(BC)] );
2598 6!      ENDIF;
2599 5!      IF BDTR <> 0 OR BMTR <> 0 THEN
2600 6!          CALL RECOVA ( [UTRANA], [GASUBO(BC)], [PFOA(BC)], [UTRANF] );
2601 6!      ENDIF;
2602 6!      IF BDFR <> 0 OR BMFR <> 0 THEN
2603 5!          CALL RECOVA ( [UFREQA], [GASUBO(BC)], [PFOA(BC)], [UFREQF] );
2604 6!      ENDIF;
2605 6!      ELSE
2606 5!$      DATA RECOVERY WITHOUT F-SET REDUCTION
2607 5!$
2608 5!$      IF BLOAD <> 0 THEN
2609 6!          [UF] := [UA];
2610 6!          IF NRSET <> 0 [AF] := [AA];
2611 6!      ENDIF;
2612 5!      IF BSAERO <> 0 THEN
2613 6!          FOR S = 1 TO SUB DO
2614 7!$
2615 7!$      MERGE THE CURRENT SUBCASE DEPENDENT RESULTS INTO A SINGLE
2616 7!$      MATRIX OF RESPONSE QUANTITIES FOR FURTHER RECOVERY
2617 7!$
2618 7!      CALL SAEROMRG ( BC, S, [UAF], [UAA(S)] );
2619 7!      IF NRSET <> 0 CALL SAEROMRG ( BC, S, [AAF], [AAA(S)] );
2620 7!      ENDDO;
2621 6!      ENDIF;
2622 5!      IF BMODES <> 0 [PHIF] := [PHIA];
2623 5!      IF BDTR <> 0 OR BMTR <> 0 [UTRANF] := [UTRANA];
2624 5!      IF BDFR <> 0 OR BMFR <> 0 [UFREQF] := [UFREQA];
2625 5!      ENDIF;
2626 4!      ENDIF;
2627 3!$      IF NBNDCOND > 1 CALL NULLMAT ( [UN], [AN], [PHIN] );
2628 3!      IF NSPC <> 0 THEN
2629 4!$      DATA RECOVERY WITH SPC-REDUCTION
2630 4!$
2631 4!$      PRINT("LOG=('          SPC RECOVERY')");
2632 4!      IF BLOAD <> 0 THEN
2633 5!          CALL YSMERGE ( [UN], [YS(BC)], [UF], [PNSF(BC)] );
2634 5!          CALL OFFSPCF ( 0, BC, 1, 1, GSIZE, ESIZE(BC), NGDR,
2635 5!              [KFS], [KSS], [UF], [YS(BC)], [PS],
2636 5!              [PNSF(BC)], [PGMN(BC)], [PFJK], , , ,
2637 5!              BGPDT(BC), OGRIDLOD );
2638 5!          IF NRSET <> 0 CALL YSMERGE ( [AN], [AF], [PNSF(BC)] );
2639 5!      ENDIF;
2640 4!      IF BSAERO <> 0 THEN
2641 5!          CALL YSMERGE ( [UAN], [YS(BC)], [UAF], [PNSF(BC)] );
2642 5!          IF NRSET <> 0 CALL YSMERGE ( [AAN], [AAF], [PNSF(BC)] );
2643 5!      ENDIF;
2644 4!      IF BMODES <> 0 THEN
2645 5!          CALL YSMERGE ( [PHIN], [YS(BC)], [PHIF],
2646 5!              [PNSF(BC)] );
2647 5!          IF DMODES <> 0 CALL OFFSPCF ( 0, BC, 2, 1, GSIZE,
2648 5!              ESIZE(BC), NGDR,
2649 5!              [KFS], , [PHIF], , ,
2650 5!              [PNSF(BC)], [PGMN(BC)], [PFJK],
2651 5!              , , , BGPDT(BC), OGRIDLOD );
2652 6!
2653 6!
2654 6!
2655 6!
2656 6!

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2657 5!      ENDIF;
2658 4!      IF BDTR <> 0 OR BMTR <> 0
2659 5!          CALL YSMERGE ( [UTRANN], [YS(BC)], [UTRANF],
2660 5!                      [PNSF(BC)], BDTR );
2661 4!      IF BDFR <> 0 OR BMFR <> 0
2662 5!          CALL YSMERGE ( [UFREQN], [YS(BC)], [UFREQF],
2663 5!                      [PNSF(BC)], BDFR );
2664 4!      IF BFLUTR <> 0
2665 5!          CALL OFFSPCF ( 0, BC, 4, 2, GSIZE, ESIZE(BC), NGDR, [KFS], ,
2666 5!                      [PHIF], , , [PNSF(BC)], [PGMN(BC)], [PFJK],
2667 5!                      , , BGPDT(BC), OGRIDLOD );
2668 4!      IF BBLAST <> 0 THEN
2669 5!          [UBLASTF] := [PHIF]*[UBLASTI];
2670 5!          CALL OFFSPCF ( 0, BC, 8, 1, GSIZE, ESIZE(BC), NGDR,
2671 5!                      [KFS], , [UBLASTF], , , [PNSF(BC)], [PGMN(BC)],
2672 5!                      [PFJK], , , BGPDT(BC), OGRIDLOD );
2673 5!      ENDIF;
2674 4!      ELSE
2675 4!$
2676 4!$      DATA RECOVERY WITHOUT SPC-REDUCTION
2677 4!$
2678 4!      IF BLOAD <> 0 THEN
2679 5!          [UN] := [UF];
2680 5!          IF NRSET <> 0 [AN] := [AF];
2681 5!      ENDIF;
2682 4!      IF BSAERO <> 0 THEN
2683 5!          [UAN] := [UAF];
2684 5!          IF NRSET <> 0 [AAN] := [AAF];
2685 5!      ENDIF;
2686 4!      IF BMODES <> 0 [PHIN] := [PHIF];
2687 4!      IF BDTR <> 0 OR BMTR <> 0 [UTRANN] := [UTRANA];
2688 4!      IF BDFR <> 0 OR BMFR <> 0 [UFREQN] := [UFREQA];
2689 4!      ENDIF;
2690 3!$
2691 3!      IF NBNDCOND > 1 CALL NULLMAT ( [UG(BC)], [AG(BC)], [UAG(BC)], [AAG(BC)],
2692 4!                      [PHIG(BC)] );
2693 3!
2694 4!$      IF NMPC <> 0 THEN
2695 4!$
2696 4!$      DATA RECOVERY WITH MPC-REDUCTION
2697 4!$
2698 4!      PRINT("LOG=('      MPC RECOVERY')");
2699 5!      IF BLOAD <> 0 THEN
2700 5!          [UM] := [TMN(BC)] * [UN];
2701 5!          CALL ROWMERGE ( [UG(BC)], [UM], [UN], [PGMN(BC)] );
2702 6!          IF NRSET <> 0 THEN
2703 6!              [UM] := [TMN(BC)] * [AN];
2704 6!              CALL ROWMERGE ( [AG(BC)], [UM], [AN], [PGMN(BC)] );
2705 6!          ENDIF;
2706 5!      ENDIF;
2707 4!      IF BSAERO <> 0 THEN
2708 5!          [UM] := [TMN(BC)] * [UAN];
2709 5!          CALL ROWMERGE ( [UAG(BC)], [UM], [UAN], [PGMN(BC)] );
2710 6!          IF NRSET <> 0 THEN
2711 6!              [UM] := [TMN(BC)] * [AAN];
2712 6!              CALL ROWMERGE ( [AAG(BC)], [UM], [AAN], [PGMN(BC)] );
2713 6!          ENDIF;
2714 5!      ENDIF;
2715 4!      IF BMODES <> 0 THEN
2716 5!          [UM] := [TMN(BC)] * [PHIN];
2717 5!          CALL ROWMERGE ( [PHIG(BC)], [UM], [PHIN], [PGMN(BC)] );
2718 5!      ENDIF;
2719 4!      IF BDTR <> 0 OR BMTR <> 0 THEN
2720 5!          [UM] := [TMN(BC)] * [UTRANN];
2721 5!          CALL ROWMERGE ( [UTRANG], [UM], [UTRANN], [PGMN(BC)] );
2722 5!      ENDIF;
2723 4!      IF BDFR <> 0 OR BMFR <> 0 THEN
2724 5!          [UM] := [TMN(BC)] * [UFREQN];
2725 5!          CALL ROWMERGE ( [UFREQG], [UM], [UFREQN], [PGMN(BC)] );
2726 5!      ENDIF;
2727 4!      ELSE
2728 4!$
2729 4!$      DATA RECOVERY WITHOUT MPC-REDUCTION
2730 4!$
2731 4!      IF BLOAD <> 0 THEN
2732 5!          [UG(BC)] := [UN];
2733 5!          IF NRSET <> 0 [AG(BC)] := [AN];
2734 5!      ENDIF;
2735 4!      IF BSAERO <> 0 THEN
2736 5!          [UAG(BC)] := [UAN];
2737 5!          IF NRSET <> 0 [AAG(BC)] := [AAN];
2738 5!      ENDIF;

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2738 4!      IF BMODES <> 0 [PHIG(BC)] := [PHIN];
2739 4!      IF BDTR <> 0 OR BMTR <> 0 [UTRANG] := [UTRANN];
2740 4!      IF BDFR <> 0 OR BMFR <> 0 [UFREQG] := [UFREQN];
2741 4!      ENDIF;
2742 3!$
2743 3!$ RECOVER PHYSICAL BLAST DISCIPLINE DISPLACEMENTS
2744 3!$
2745 3!      IF BBLAST <> 0 [UBLASTG] := [PHIG(BC)] * [UBLASTI];
2746 3!$
2747 3!$ HANDLE OUTPUT REQUESTS
2748 3!$
2749 3!      PRINT("LOG=('      OUTPUT PROCESSING')");
2750 3!      IF BSAERO <> 0 THEN
2751 4!$
2752 4!$ RECOVER STATIC AEROELASTIC LOADS DATA
2753 4!$
2754 4!      LOOP := TRUE;
2755 4!      SUB := 0;
2756 4!      WHILE LOOP DO
2757 5!          SUB := SUB + 1;
2758 5!          CALL SAERODRV (BC, SUB, LOOP, MINDEX, SYM, MACH, QDP);
2759 5!$
2760 5!$ CALL THE TRIMMED LOADS COMPUTATION WITH PROPER MATRICES
2761 5!$
2762 5!      IF SYM = 1 THEN
2763 6!$***** TAKEN OUT FOR ZAERO *****$!
2764 6!$      CALL OFFPALOAD ( , BC, MINDEX, SUB, GSIZE, BGPDT(BC),
2765 6!$          [GTKG], [GSTKG], QDP, [AIRFRM(MINDEX)],
2766 6!$          [DELTA(SUB)], [AICMAT(MINDEX)],
2767 6!$          [UAG(BC)], [MGG], [AAG(BC)], [KFS],
2768 6!$          [KSS], [UAF], [YS(BC)], [PNSF(BC)],
2769 6!$          [PGMN(BC)], [PFJK], NGDR, USET(BC),
2770 6!$          OGRIDLOD);
2771 6!$*****$!
2772 6!      CALL OFFPALOAD ( , BC, MINDEX, SUB, GSIZE, BGPDT(BC),
2773 6!$          [UGTKG], [UGSTKG], QDP, [AIRFRM(MINDEX)],
2774 6!$          [DELTA(SUB)], [AICMAT(MINDEX)],
2775 6!$          [UAG(BC)], [MGG], [AAG(BC)], [KFS],
2776 6!$          [KSS], [UAF], [YS(BC)], [PNSF(BC)],
2777 6!$          [PGMN(BC)], [PFJK], NGDR, USET(BC),
2778 6!$          OGRIDLOD);
2779 6!      ELSE
2780 6!      IF SYM = -1 THEN
2781 7!$***** TAKEN OUT FOR ZAERO *****$!
2782 7!$      CALL OFFPALOAD ( , BC, MINDEX, SUB, GSIZE, BGPDT(BC),
2783 7!$          [GTKG], [GSTKG], QDP, [AIRFRM(MINDEX)],
2784 7!$          [DELTA(SUB)], [AICMAT(MINDEX)],
2785 7!$          [UAG(BC)], [MGG], [AAG(BC)], [KFS],
2786 7!$          [KSS], [UAF], [YS(BC)], [PNSF(BC)],
2787 7!$          [PGMN(BC)], [PFJK], NGDR, USET(BC),
2788 7!$          OGRIDLOD);
2789 7!$*****$!
2790 7!      CALL OFFPALOAD ( , BC, MINDEX, SUB, GSIZE, BGPDT(BC),
2791 7!$          [UGTKG], [UGSTKG], QDP, [AIRFRM(MINDEX)],
2792 7!$          [DELTA(SUB)], [AICMAT(MINDEX)],
2793 7!$          [UAG(BC)], [MGG], [AAG(BC)], [KFS],
2794 7!$          [KSS], [UAF], [YS(BC)], [PNSF(BC)],
2795 7!$          [PGMN(BC)], [PFJK], NGDR, USET(BC),
2796 7!$          OGRIDLOD);
2797 7!      ENDIF;
2798 6!      ENDIF;
2799 5!$
2800 5!$ CALL TO COMPUTE THE TRIMMED LOADS/DISPLACEMENTS ON THE
2801 5!$ AERODYNAMIC MODEL
2802 5!$
2803 5!      IF SYM = 1 THEN
2804 6!$***** TAKEN OUT FOR ZAERO *****$!
2805 6!$      CALL OFFPAEROM ( NITER, BC, MINDEX, SUB, GSIZE, GEOMSA,
2806 6!$          [GTKG], [GSTKG], QDP, [AIRFRM(MINDEX)],
2807 6!$          [DELTA(SUB)], [AICMAT(MINDEX)],
2808 6!$          [UAG(BC)], [OAGRDLOD], [OAGRDDSP]);
2809 6!$*****$!
2810 6!      CALL OFFPAEROM ( NITER, BC, MINDEX, SUB, GSIZE, GEOMSA,
2811 6!$          [UGTKG], [UGSTKG], QDP, [AIRFRM(MINDEX)],
2812 6!$          [DELTA(SUB)], [AICMAT(MINDEX)],
2813 6!$          [UAG(BC)], [OAGRDLOD], [OAGRDDSP]);
2814 6!      ELSE
2815 6!      IF SYM = -1 THEN
2816 7!$***** TAKEN OUT FOR ZAERO *****$!
2817 7!$      CALL OFFPAEROM ( NITER, BC, MINDEX, SUB, GSIZE, GEOMSA,
2818 7!$          [GTKG], [GSTKG], QDP, [AIRFRM(MINDEX)],

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2819 7!$ [DELTA(SUB)], [AAICMAT(MINDEX)], $!
2820 7!$ [UAG(BC)], OAGRDLOD, OAGRDDSP ); $!
2821 7!$*****$!
2822 7! CALL OFFPAEROM ( NITER, BC, MINDEX, SUB, GSIZE, GEOMSA, !
2823 7! [UGTKG], [UGTKG], QDP, [AIRFRM(MINDEX)], !
2824 7! [DELTA(SUB)], [AAICMAT(MINDEX)], !
2825 7! [UAG(BC)], OAGRDLOD, OAGRDDSP ); ! ←
2826 7! ENDIF; !
2827 6! ENDIF; !
2828 5! ENDDO; !
2829 4! ENDIF; !
2830 3! IF BDRSP <> 0 THEN !
2831 4! CALL OFFPDLOAD ( , BC, BGPDT(BC), PSIZE(BC), ESIZE(BC), [PHIG(BC)], !
2832 4! [PTGLOAD], [PTHLOAD], [PFGLOAD], [PFHLOAD], OGRIDLOD ); !
2833 4! IF BDTR <> 0 OR BMTR <> 0 !
2834 5! CALL OFFSPCF ( 0, BC, 5, 1, GSIZE, ESIZE(BC), !
2835 5! NGDR, [KFS], , [UTRANF], , , !
2836 5! [PNSF(BC)], [PGMN(BC)], [PFJK], !
2837 5! [PHIG(BC)], [PTGLOAD], [PTHLOAD], !
2838 5! BGPDT(BC), OGRIDLOD ); !
2839 4! IF BDFR <> 0 OR BMFR <> 0 !
2840 5! CALL OFFSPCF ( 0, BC, 6, 2, GSIZE, ESIZE(BC), !
2841 5! NGDR, [KFS], , [UFREQF], , , !
2842 5! [PNSF(BC)], [PGMN(BC)], [PFJK], !
2843 5! [PHIG(BC)], [PFGLOAD], [PFHLOAD], !
2844 5! BGPDT(BC), OGRIDLOD ); !
2845 4! ENDIF; !
2846 3! CALL OFFLOAD ( NUMOPTBC, BC, , GSIZE, BGPDT(BC), PSIZE(BC), !
2847 3! [PG] ); !
2848 3! CALL OFFDISP( NUMOPTBC, BC, , GSIZE, BGPDT(BC), ESIZE(BC), PSIZE(BC), !
2849 3! OGRIDDSP, [UG(BC)], [AG(BC)], [UAG(BC)], [AAG(BC)], !
2850 3! [UBLASTG], , [UTRANG], [UTRANE], [UFREQG], [UFREQE], !
2851 3! LAMBDA, [PHIG(BC)] ); !
2852 3! CALL EDR ( NUMOPTBC, BC, , NDV, GSIZE, EOSUMMARY, EODISC, !
2853 3! GLBDES, LOCLVAR, [PTRANS], !
2854 3! [UG(BC)], [UAG(BC)], , [UTRANG], [UFREQG], [PHIG(BC)] ); !
2855 3! CALL OFFPEDR ( BC, HSIZE(BC) ); !
2856 3! ENDDO; !
2857 2! ENDIF; !
2858 1! END; !

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APPENDIX C

ZAERO BULK DATA TEMPLATE DEFINITIONS (TEMPLATE.DAT)

The following lists the twenty three (23) new bulk data templates in file (TEMPLATE.DAT) used to define the ZAERO bulk data cards:

ACCOORD	ID	XORIGN	YORIGN	ZORIGN	DELTA	THETA	XMCNT	YMCNT	CONT	
CHAR	INT	REAL	REAL	REAL	REAL	REAL	REAL	REAL	CHAR	
DEFAULT		0.0	0.0	0.0	0.0	0.0	0.0	0.0		
CHECKS	GT 0									
	1	2	3	4	5	6	7	8		
ACCOORD	ID	XORIGN	YORIGN	ZORIGN	DELTA	THETA	XMCNT	YMCNT		
+COORD	ZMCNT	XBEND	YBEND	ZBEND	XTORQ	YTORQ	ZTORQ			
CHAR	REAL	REAL	REAL	REAL	REAL	REAL	REAL			
DEFAULT	0.0	0.0	0.0	0.0	0.0	0.0	0.0			
CHECKS										
	9	10	11	12	13	14	-15			
	ZMCNT	XBEND	YBEND	ZBEND	XTORQ	YTORQ	ZTORQ			\$

AEROZ	ACSID	XZSYM	RHOREF	REFC	REFB	REFS	GREF			
CHAR	INT	CHAR	REAL	REAL	REAL	REAL	INT			
DEFAULT	0	YES	1.0	1.0	1.0	1.0	0			
CHECKS			GE 0.	GE 0.	GE 0.	GE 0.	GE 0			
	1	2	3	4	5	6	-7			
AEROZ	ACSID	XZSYM	RHOREF	REFC	REFB	REFS	GREF			\$

AESURFZ	LABEL	TYPE	CID	SETK	SETG					
CHAR	CHAR	CHAR	INT	INT	INT					
DEFAULT										
CHECKS			GE 0	GT 0	GE 0					
	1	3	5	6	-7					
AESURFZ	LABEL	TYPE	CID	SETK	SETG					\$

ATTACH	EID	MODEL	SETK	REFGRID	FEEDBK					
CHAR	INT	CHAR	INT	INT	CHAR					
DEFAULT					FLEX					
CHECKS	GT 0		GT 0	GT 0	FRCHK					
	1	2	4	5	-6					
ATTACH	EID	MODEL	BOXSETIDREFGRD	FEEDBK						\$

BODY7	IDBODY	LABELB	IPBODY	ACCOORD	NSEG	ID(1)	ID(2)	ID(3)	CONT	
CHAR	INT	CHAR	INT	INT	INT	INT	INT	INT	CHAR	
DEFAULT			0	0		NULL	NULL	NULL		
CHECKS	GT 0		GE 0	GE 0	GE 1	GT 0	GTZOB	GTZOB		
	1	2	4	5	6	7	8	9		
BODY7	IDBODY	LABELB	IPBODY	ACCOORD	NSEG	IDMESH A	IDMESH B	IDMESH C		
+BODY7	ID(5)	ID(6)	ID(7)	ID(8)	ID(9)	ID(10)	ID(11)	ID(12)		
CHAR	INT	INT	INT	INT	INT	INT	INT	INT		
DEFAULT	NULL	NULL	NULL	NULL	NULL	NULL	NULL	NULL		
CHECKS	GTZOB	GTZOB	GTZOB	GTZOB	GTZOB	GTZOB	GTZOB	GTZOB		
	10	11	12	13	14	15	16	-17		
	IDMESH D	IDMESH E	IDMESH F	IDMESH G	IDMESH H	IDMESH I	IDMESH J	IDMESH K		\$

CAERO7	EID	LABELC	ACOORD	NSPAN	NCHORD	LSPAN	ZTAIC	PAFOIL	CONT	
CHAR	INT	CHAR	INT	INT	INT	INT	INT	INT	CHAR	
DEFAULT										
CHECKS	GT 0		GE 0	GE 2	GE 2	GE 0	GE 0	GE 0		
1	2	4	5	6	7	8	9			
CAERO7	EID	LABELC	ACOORD	NSPAN	NCHORD	LSPAN	ZTAIC	PAFOIL		
+CAERO7	XRL	YRL	ZRL	RCH	LRCHD	ATTR			CONT	
CHAR	REAL	REAL	REAL	REAL	INT	INT			CHAR	
DEFAULT					0	0				
CHECKS				GE 0.	GE 0	GE 0				
10	11	12	13	14	15					
XRL	YRL	ZRL	RCH	LRCHD	ATTR					
+CAERO7	XTL	YTL	ZTL	TCH	LTCHD	ATTT				
CHAR	REAL	REAL	REAL	REAL	INT	INT				
DEFAULT					0	0				
CHECKS				GE 0.	GE 0	GE 0				
16	17	18	19	20	-21					
XTL	YTL	ZTL	TCH	LTCHD	ATTT					\$

CHORDCP	ID	X	CPU	CPL	X	CPU	CPL		CONT	
CHAR	INT	REAL	REAL	REAL	REAL	REAL	REAL		CHAR	
DEFAULT										
CHECKS	GT 0	GE 0.			GE 0.					
1	2	3	-4	2	3	-4				
CHORDCP	ID	X	CPU	CPL						
+CHORDCP		X	CPU	CPL	X	CPU	CPL		ETC	
CHAR		REAL	REAL	REAL	REAL	REAL	REAL		CHAR	
DEFAULT										
CHECKS		GE 0.			GE 0.					
2	3	-4	2	3	-4					\$

FLUTTER	SID	METHOD	DENS	IDMK	VEL	MLIST	KLIST	EFFID	CONT	
CHAR	INT	CHAR	INT	INT	INT	INT	INT	INT		
DEFAULT		PK								
CHECKS	GT 0		GT 0	GT 0	GT 0	GE 0	GE 0	GE 0		
1	2	3	4	5	6	7	8			
FLUTTER	SETID	METHOD	DENS	IDMK	VEL	MLIST	KLIST	EFFID		
+FLUTTER	SYMXX	SYMXY	EPS	CURVFIT	PRINT					
CHAR	INT	INT	REAL	CHAR	INT					
DEFAULT			1.E-5	LINEAR	0					
CHECKS	IB -1		GT 0.	FLTFIT						
9 1	10	11	-14							
SYMXX	SYMXY	EPS	CURVFIT	PRINT						\$

GUST	SID	GLOAD	WG	X0	V	QDP	IDMK		CONT	
CHAR	INT	INT	REAL	REAL	REAL	REAL	INT		CHAR	
DEFAULT										
CHECKS	GT 0	GT 0	NE 0.		GT 0.	GT 0.	GT 0			
1	2	3	4	5	6	7				
GUST	SID	GLOAD	WG	X0	V	QDP	IDMK			
+GUST	SYMXX	SYMXY								
CHAR	INT	INT								
DEFAULT										
CHECKS	IB -1									
8 1	-9 0									
SYMXX	SYMXY									\$

LOADMOD	LID	LABEL	CP	SETK	SETG					
CHAR	INT	CHAR	INT	INT	INT					
DEFAULT										
CHECKS	GT 0		GE 0	GT 0	GT 0					
1	2	4	5	-6						
LOADMOD	LID	LABEL	CP	SETK	SETG					\$

MACHCP	ID	MACH	IGRID	INDICIA	SPNID	CHDCP	SPNID	CHDCP	CONT	
CHAR	INT	REAL	INT	INT	INT	INT	INT	INT	CHAR	
DEFAULT		0.9	0	0						
CHECKS	GT 0	GE 0.		GE 0	GT 0	GT 0				
	1	2	3	4	5	-6	5	-6		
MACHCP	ID	MACH	IGRID	INDICIA	SPANID	CHORDCP				
+MACHCP	SPNID	CHDCP	SPNID	CHDCP	SPNID	CHDCP	SPNID	CHDCP	ETC	
CHAR	INT	INT	INT	INT	INT	INT	INT	INT	CHAR	
DEFAULT										
CHECKS										
	5	-6	5	-6	5	-6	5	-6		\$

MKAEROZ	IDMK	MACH	METHOD	IDFLT	SAVE	FILE1	FILE2	PRINT	CONT	
CHAR	INT	REAL	INT	INT	CHAR	CHAR	CHAR	INT	CHAR	
DEFAULT			0	0						
CHECKS	GT 0	GE 0.0		GE 0						
	1	2	3	4	5	7	9	11		
MKAEROZ	IDMK	MACH	METHOD	IDFLT	SAVE	FILE1	FILE2	PRINT		
+MKAROZ	FREQ(1)	FREQ(2)	FREQ(3)	FREQ(4)	FREQ(5)	FREQ(6)	FREQ(7)	FREQ(9)	ETC	
CHAR	REAL	REAL	REAL	REAL	REAL	REAL	REAL	REAL	CHAR	
DEFAULT	0.									
CHECKS	GE 0.	GE 0.	GE 0.	GE 0.	GE 0.	GE 0.	GE 0.	GE 0.		
	-12	-12	-12	-12	-12	-12	-12	-12		\$
	RFREQ									

PAFOIL7	ID	IAFX	ITHR	ICAMR	RADR	ITHT	ICAMT	RADT		
CHAR	INT	INT	INT	INT	REAL	INT	INT	REAL		
DEFAULT		0	0	0	0.0	0	0	0.0		
CHECKS	GT 0		GE 0	GE 0	GE 0.0	GE 0	GE 0	GE 0.0		
	1	2	3	4	5	6	7	-8		
PAFOIL7	ID	IAFX	ITHR	ICAMR	RADR	ITHT	ICAMT	RADT		\$

PANLST1	SETID	MACROID	BOX1	BOX2						
CHAR	INT	INT	INT	INT						
DEFAULT										
CHECKS	GT 0	GT 0	GT 0	GEP						
	1	2	3	-4						
PANLST1	SETID	MACROID	BOX1	BOX2						\$

PANLST2	SETID	MACROID	B(1)	B(2)	B(3)	B(4)	B(5)	B(6)	CONT	
CHAR	INT	INT	INT	INT/CHAR	INT	INT	INT	INT	CHAR	
DEFAULT										
CHECKS	GT 0	GT 0	GE 0	GE 0	GE 0	GE 0	GE 0	GE 0		
	1	2	-3	-3	-3	-3	-3	-3		
PANLST2	SETID	MACROID	BOX1							
+PNLST2	B(N)	B(N+1)	B(N+2)	B(N+3)	B(N+4)	B(N+5)	B(N+6)	B(N+7)	ETC	
CHAR	INT	INT	INT	INT	INT	INT	INT	INT	CHAR	
DEFAULT										
CHECKS	GE 0	GE 0	GE 0	GE 0	GE 0	GE 0	GE 0	GE 0		
	-3	-3	-3	-3	-3	-3	-3	-3		\$

PBODY7	IPBODY7	WAKE	CPBASE	XSWAKE	XDWAKE	YWAKE	ZWAKE	INLET	CONT	
CHAR	INT	INT	REAL	REAL	REAL	REAL	REAL	INT	CHAR	
DEFAULT		0	-0.2	1.3	1.1	0.0	0.0	0		
CHECKS	GT 0	GE 0		GE 1.0	GE 1.0			GE 0		
	1	2	3	4	5	6	7	8		
PBODY7	IPBODY7	WAKE	CPBASE	XSWAKE	XDWAKE	YWAKE	ZWAKE	INLET		
+PBODY7	IDP(1)	FLW(1)	IDP(2)	FLW(2)	IDP(3)	FLW(3)	IDP(4)	FLW(4)	ETC	
CHAR	INT	REAL	INT	REAL	INT	REAL	INT	REAL	CHAR	
DEFAULT	0	0.0	0	0.0	0	0.0	0	0.0		
CHECKS										
	9	-10	9	-10	9	-10	9	-10		\$
	IDP	FLOWRT								

SEGMESH	IDMESH	NAXIS	NRAD						CONT	
CHAR	INT	INT	INT						CHAR	
DEFAULT										
CHECKS	GT 0	GE 2	GE 2							
	1	2	3							
SEGMESH	IDMESH	NAXIS	NRAD							
+SEG1	IT(N)	X(N)	CM(N)	YR(N)	ZR(N)	IY(N)	IZ(N)		ETCT	
CHAR	INT	REAL	REAL	REAL	REAL	INT	INT		CHAR	
DEFAULT						0	0			
CHECKS	GT 0									
	4	5	6	7	8	9	-10			\$
	ITYPE	X	CAM	YR	ZR	IDY	IDZ			

SPLINE1	EID	MODEL	CP	SETK	SETG	DZ	EPS			
CHAR	INT	CHAR	INT	INT	INT	REAL	REAL			
DEFAULT							0.01			
CHECKS	GT 0		GE 0	GT 0	GT 0	GE 0.	GE 0.			
	1	2	4	5	6	7	-8			
SPLINE1	EID	MODEL	CP	BOXSETIDGRDSETIDFLEX			EPS			\$

SPLINE2	EID	MODEL	SETK	SETG	DZ	DTOR	CID	DTHX	CONT	
CHAR	INT	CHAR	INT	INT	REAL	REAL	INT	REAL	CHAR	
DEFAULT										
CHECKS	GT 0		GT 0	GT 0	GE 0.	GE 0.	GE 0			
	1	2	4	5	6	7	8	9		
SPLINE2	EID	MODEL	BOXSETIDGRDSETIDFLEX			DTOR	CID	DTHX		
+SPLNE2	DTHY									
CHAR	REAL									
DEFAULT										
CHECKS										
	-10									\$
	DTHY									

SPLINE3	EID	MODEL	CP	SETK	SETG	DZ	EPS			
CHAR	INT	CHAR	INT	INT	INT	REAL	REAL			
DEFAULT							0.01			
CHECKS	GT 0		GE 0	GT 0	GT 0	GE 0.	GE 0.			
	1	2	4	5	6	7	-8			
SPLINE3	EID	MODEL	CP	BOXSETIDGRDSETIDFLEX			EPS			\$
SPOINT	ID	ID	ID	ID	ID	ID	ID	ID		
CHAR	INT	INT/CHAR	INT	INT	INT	INT	INT	INT		
DEFAULT										
CHECKS	GT 0	GE 0	GE 0	GE 0	GE 0	GE 0	GE 0	GE 0		
	-1	-1	-1	-1	-1	-1	-1	-1		\$
SPOINT	EXTID									

TRIM	SETID	IDMK	QDP	TRMTYP	EFFID	VO	PRINT		CONT
CHAR	INT	INT	REAL	CHAR	INT	REAL	INT		CHAR
DEFAULT									
CHECKS	GT 0	GT 0	GT 0.	TRIM	GE 0	GE 0.			
	1	2	3	4	6	7	8		
TRIM	SETID	IDMK	QDP	TRMTYP	EFFID	VO	PRINT		
+TRIM	LABEL1	VALUE1	LABEL2	VALUE2	LABEL3	VALUE3	LABEL4	VALUE4	ETC
CHAR	CHAR	REL/CHAR	CHAR	REL/CHAR	CHAR	REL/CHAR	CHAR	REL/CHAR	CHAR
DEFAULT									
CHECKS	9	-11	9	-11	9	-11	9	-11	
	LABEL1	FIXI	FREEI						\$

TRIMFLT	IDFLT	TILTA	ALPHA	BETA	PRATE	QRATE	RRATE		CONT
CHAR	INT	INT	REAL	REAL	REAL	REAL	REAL		CHAR
DEFAULT		0	0.0	0.0	0.0	0.0	0.0		
CHECKS	GT 0								
	1	2	3	4	5	6	7		
TRIMFLT	IDFLT	TILTA	ALPHA	BETA	PRATE	QRATE	RRATE		
+TRIMF	LABEL1	VALUE1	LABEL2	VALUE2	LABEL3	VALUE3	LABEL4	VALUE4	ETC
CHAR	CHAR	REAL	CHAR	REAL	CHAR	REAL	CHAR	REAL	CHAR
DEFAULT		0.0							
CHECKS	8	-10	8	-10	8	-10	8	-10	
	LABEL1	VALUE							\$

ZTAIC	ID	NFLAP	MACHCP1	MACHCP2	MACHCP3	MACHCP4	MACHCP5	MACHCP6	CONT
CHAR	INT	INT	INT	INT	INT	INT	INT	INT	CHAR
DEFAULT		0	0	0	0	0	0	0	
CHECKS	GT 0	GE 0	GT 0	GE 0	GE 0	GE 0	GE 0	GE 0	
	1	2	3	4	5	6	7	8	
ZTAIC	ID	NFLAP	MACHCP1	MACHCP2	MACHCP3	MACHCP4	MACHCP5	MACHCP6	
+ZTAIC	LABEL	HINGE	INBDY	OUTBDY	LABEL	HINGE	INBDY	OUTBDY	ETC
CHAR	CHAR	INT	INT	INT	CHAR	INT	INT	INT	CHAR
DEFAULT		2	1	2					
CHECKS	9	GE 1	GE 1	GE 2	9	10	11	-12	
	LABEL	HINGE	INBDY	OUTBDY					\$

APPENDIX D

ZAERO RELATIONAL SCHEMA DEFINITION

(RELATION.DAT)

The following are the relational SCHEMA definitions (from file RELATION.DAT) for all database relational entities used by the ZAERO module:

<p>RELATION ACOORD</p> <p>ID INT</p> <p>XORIGN RSP</p> <p>YORIGN RSP</p> <p>ZORIGN RSP</p> <p>DELTA RSP</p> <p>THETA RSP</p> <p>XMCNT RSP</p> <p>YMCNT RSP</p> <p>ZMCNT RSP</p> <p>XBEND RSP</p> <p>YBEND RSP</p> <p>ZBEND RSP</p> <p>XTORQ RSP</p> <p>YTORQ RSP</p> <p>ZTORQ RSP</p> <p>END</p> <hr/> <p>RELATION AGRIDZ</p> <p>EXTID INT</p> <p>INTID INT</p> <p>CORD INT</p> <p>X RSP</p> <p>Y RSP</p> <p>Z RSP</p> <p>END</p> <hr/> <p>RELATION AEROZ</p> <p>ACSID INT</p> <p>XZSYM STR 4</p> <p>RHOREF RSP</p> <p>REFC RSP</p> <p>REFB RSP</p> <p>REFS RSP</p> <p>REFG INT</p> <p>END</p> <hr/> <p>RELATION AESURFZ</p> <p>LABEL STR 8</p> <p>TYPE STR 8</p> <p>CID INT</p> <p>SETK INT</p> <p>SETG INT</p> <p>END</p> <hr/> <p>RELATION AQUADZ</p> <p>MACROID INT</p> <p>ACMPNT INT</p> <p>NDOF INT</p> <p>EXTID INT</p> <p>INTID INT</p> <p>AREA RSP</p> <p>X RSP</p> <p>Y RSP</p> <p>Z RSP</p> <p>N1 RSP</p> <p>N2 RSP</p> <p>N3 RSP</p> <p>R1 RSP</p> <p>R2 RSP</p> <p>R3 RSP</p> <p>RTHETA RSP</p> <p>RDELTA RSP</p> <p>CHORD RSP</p> <p>ID1 RSP</p> <p>ID2 RSP</p> <p>ID3 RSP</p> <p>ID4 RSP</p> <p>CAM85 RSP</p> <p>CAM95 RSP</p> <p>DZX85 RSP</p> <p>DZX95 RSP</p> <p>DZXLE RSP</p> <p>DZXTE RSP</p> <p>END</p>	<p>RELATION BODY7</p> <p>IDBODY INT</p> <p>LABELB STR 8</p> <p>IPBODY INT</p> <p>ACCOORD INT</p> <p>NSEG INT</p> <p>IDMESH A INT</p> <p>IDMESH B INT</p> <p>IDMESH C INT</p> <p>IDMESH D INT</p> <p>IDMESH E INT</p> <p>IDMESH F INT</p> <p>IDMESH G INT</p> <p>IDMESH H INT</p> <p>IDMESH I INT</p> <p>IDMESH J INT</p> <p>IDMESH K INT</p> <p>END</p> <hr/> <p>RELATION CAERO7</p> <p>EID INT</p> <p>LABELC STR 8</p> <p>ACCOORD INT</p> <p>NSPAN INT</p> <p>NCHORD INT</p> <p>LSPAN INT</p> <p>ZTAIC INT</p> <p>PAFOIL INT</p> <p>XRL RSP</p> <p>YRL RSP</p> <p>ZRL RSP</p> <p>RCH RSP</p> <p>LRCHD INT</p> <p>ATTR INT</p> <p>XTL RSP</p> <p>YTL RSP</p> <p>ZTL RSP</p> <p>TCH RSP</p> <p>LTCHD INT</p> <p>ATTT INT</p> <p>END</p> <hr/> <p>RELATION CHORDCP</p> <p>ID INT</p> <p>X RSP</p> <p>CPU RSP</p> <p>CPL RSP</p> <p>END</p> <hr/> <p>RELATION FLUTTER</p> <p>SETID INT</p> <p>METHOD STR 4</p> <p>DENS INT</p> <p>IDMK INT</p> <p>VEL INT</p> <p>MLIST INT</p> <p>KLIST INT</p> <p>EFFID INT</p> <p>SYMXX INT</p> <p>SYMXY INT</p> <p>EPS RSP</p> <p>CURVFIT STR 8</p> <p>MACHVAL RSP</p> <p>PRINT INT</p> <p>END</p> <hr/>	<p>RELATION GEOMZA</p> <p>MACROID INT</p> <p>ACMPNT STR 8</p> <p>NDOF INT</p> <p>EXTID INT</p> <p>INTID INT</p> <p>AREA RSP</p> <p>X RSP</p> <p>Y RSP</p> <p>Z RSP</p> <p>N1 RSP</p> <p>N2 RSP</p> <p>N3 RSP</p> <p>R1 RSP</p> <p>R2 RSP</p> <p>R3 RSP</p> <p>RTHETA RSP</p> <p>RDELTA RSP</p> <p>CHORD RSP</p> <p>ID1 RSP</p> <p>ID2 RSP</p> <p>ID3 RSP</p> <p>ID4 RSP</p> <p>CAM85 RSP</p> <p>CAM95 RSP</p> <p>DZX85 RSP</p> <p>DZX95 RSP</p> <p>DZXLE RSP</p> <p>DZXTE RSP</p> <p>INLET INT</p> <p>IWAKE INT</p> <p>END</p> <hr/> <p>RELATION LOADMOD</p> <p>LID INT</p> <p>LABEL STR 8</p> <p>CP INT</p> <p>SETK INT</p> <p>SETG INT</p> <p>END</p> <hr/> <p>RELATION MACHCP</p> <p>ID INT</p> <p>MACH RSP</p> <p>IGRID INT</p> <p>INDICIA INT</p> <p>SPANID INT</p> <p>CHORDCP INT</p> <p>END</p> <hr/> <p>RELATION MKAEROZ</p> <p>IDMK INT</p> <p>MACH RSP</p> <p>METHOD INT</p> <p>IDFLT INT</p> <p>SAVE STR 8</p> <p>FILE1 STR 8</p> <p>FILE2 STR 8</p> <p>PRINT INT</p> <p>RFREQ RSP</p> <p>END</p> <hr/> <p>RELATION PAFOIL7</p> <p>ID INT</p> <p>IAFX INT</p> <p>ITHR INT</p> <p>ICAMR INT</p> <p>RADR RSP</p> <p>ITHT INT</p> <p>ICAMT INT</p> <p>RADT RSP</p> <p>END</p>	<p>RELATION PANLST1</p> <p>SETID INT</p> <p>MACROID INT</p> <p>BOX1 INT</p> <p>BOX2 INT</p> <p>END</p> <hr/> <p>RELATION PANLST2</p> <p>SETID INT</p> <p>MACROID INT</p> <p>BOX1 INT</p> <p>END</p> <hr/> <p>RELATION PBODY7</p> <p>IPBODY7 INT</p> <p>WAKE INT</p> <p>CPBASE RSP</p> <p>XSWAKE RSP</p> <p>XDWAKE RSP</p> <p>YWAKE RSP</p> <p>ZWAKE RSP</p> <p>INLET INT</p> <p>IDP INT</p> <p>FLOWRT RSP</p> <p>END</p> <hr/> <p>RELATION REUNMK</p> <p>IDMK INT</p> <p>MACH RSP</p> <p>METHOD INT</p> <p>SYMXX INT</p> <p>ALPHA RSP</p> <p>BETA RSP</p> <p>PRATE RSP</p> <p>QRATE RSP</p> <p>RRATE RSP</p> <p>MINDEX INT</p> <p>KINDEX INT</p> <p>RFREQ RSP</p> <p>END</p> <hr/> <p>RELATION SEGMESH</p> <p>IDMESH INT</p> <p>NAXIS INT</p> <p>NRAD INT</p> <p>ITYPE INT</p> <p>X RSP</p> <p>CAM RSP</p> <p>YR RSP</p> <p>ZR RSP</p> <p>IDY INT</p> <p>IDZ INT</p> <p>END</p> <hr/> <p>RELATION SPLINE3</p> <p>EID INT</p> <p>MODEL STR 8</p> <p>CP INT</p> <p>BOXSETID INT</p> <p>GRDSETID INT</p> <p>FLEX RSP</p> <p>EPS RSP</p> <p>END</p> <hr/> <p>RELATION TRIMFLT</p> <p>IDFLT INT</p> <p>TILTA INT</p> <p>ALPHA RSP</p> <p>BETA RSP</p> <p>PRATE RSP</p> <p>QRATE RSP</p> <p>RRATE RSP</p> <p>LABELI STR 8</p> <p>VALUE RSP</p> <p>END</p>
--	--	---	---

```
RELATION ZTAIC
ID      INT
NFLAP   INT
MACHCP1 INT
MACHCP2 INT
MACHCP3 INT
MACHCP4 INT
MACHCP5 INT
MACHCP6 INT
LABEL   STR      4
HINGE   INT
INBDY   INT
OUTBDY  INT
END
```

APPENDIX E

ZAERO ERROR MESSAGE DEFINITION

(SERRMSG.DAT)

In following the ASTROS format for error message definitions, three new error message modules (numbers 35 through 37) have been generated for the ZAERO software and added to the SERRMSG.DAT file. These ZAERO error message modules are listed as follows:

```
*MODULE 35      ZONA'S AEROGM MODULE MESSAGES
'NO $ BULK DATA ENTRIES ARE DEFINED, BUT BODY7 BULK DATA EXISTS IN THE INPUT.'
'$ BULK DATA ENTRY WITH BID: $ HAS $ NUMBER OF SEGMENTS, BUT THERE ARE ONLY $ NUMBER OF SEGMENT $
'BULK DATA ENTRIES DEFINED.'
'BULK DATA ENTRY $ IS REFERRED BY A ID: $ BUT NO $ EXISTS IN THE INPUT.'
'ID NUMBER: $ OF BULK DATA CARD $ IS NOT DEFINED.'
'BULK DATA ENTRY $ WITH ID: $ , REFERS TO BULK DATA ENTRY $ WITH ID: $ WHICH DOES NOT EXIST.'
'$ BULK DATA CARD WITH ID: $ SPECIFIES $ NUMBER OF AXIAL STATIONS, BUT ONLY $ ARE DEFINED.'
'THE X-LOCATIONS OF A $ BULK DATA ENTRY WITH ID: $ ARE NOT IN ASCENDING ORDER AT AXIAL STATIONS $ AND $.'
'$ WITH WID: $ HAS $ NUMBER OF SPANWISE DIVISIONS DEFINED, BUT THERE ARE $ NUMBER OF VALUES'
'LISTED IN THE CORRESPONDING $ BULK DATA ENTRY WITH ID: $ .'
'$ WITH ID: $ REFERENCED BY $ WITH WID: $ DOES NOT BEGIN WITH 0.0 OR END AT 100.0.'
'THE SPANWISE DIVISIONS OF A $ BULK DATA CARD, ID: $ REFERENCED BY A $ CARD WITH WID: $, ARE NOT'
'IN ASCENDING ORDER.'
'THE TOTAL NUMBER OF MACH NUMBERS LISTED IN ALL MACHCP BULK DATA ENTRIES EXCEEDS 6.'
'CAERO7 ENTRY WITH WID: $, HAS NO STEADY PRESSURE INPUT ON SPANWISE STRIP INDEX = $ AND MACH NUMBER = $.'
'THEREFORE LINEAR UNSTEADY PRESSURE WILL BE COMPUTED FOR THIS STRIP.'
'CAERO7 ENTRY WITH WID: $, HAS MORE THAN ONE SPANWISE STRIP INDEX DEFINED FOR A MACHCP BULK DATA ENTRY'
'FOR SPANWISE STRIP INDEX = $ AND MACH NUMBER = $.'
'AERODYNAMIC $ ID: $ IS TOO LARGE BASED ON AVAILABLE MEMORY.'
'A DUPLICATE AERODYNAMIC $ EXISTS WITH ID: $ .'
'A SEGMENT BULK DATA CARD WITH ID: $ HAS $ NUMBER OF $-VALUE CIRCUMFERENTIAL POINTS (NRAD) DEFINED,'
'BUT THERE ARE ONLY $ NUMBER OF VALUES LISTED IN AFFECT WITH ID: $ .'
'A $ WITH ID: $ HAS A BOX OF ZERO AREA WITH ID: $ .'
'ERROR IN $ WITH ID: $ . INCOMPLETE LIST OF LABEL-HINGE-INBDY-OUTBDY PAIRS FOR NFLAP = $ .'
'ERROR IN $ WITH ID: $ . ENTRY LABEL = $ IS NOT $ OR $ .'
'ERROR IN $ WITH ID: $ . ENTRY HINGE = $ IS NOT GREATER THAN 1 AND LESS THAN $ (NCHORD) .'
'ERROR IN $ WITH ID: $ . ENTRY INBDY = $ IS NOT GREATER OR EQUAL TO 1 AND LESS THAN $ (NSPAN) .'
'ERROR IN $ WITH ID: $ . ENTRY OUTBDY = $ IS NOT GREATER THAN 1 AND LESS THAN OR EQUAL TO $ (NSPAN) .'
'ERROR IN $ WITH ID: $ . ENTRY INBDY = $ IS GREATER THAN OR EQUAL TO ENTRY OUTBDY = $ .'
'A $ BULK DATA CARD WITH ID: $ HAS A SPANWISE INDEX (SPANID) = $ WHICH IS LESS THAN 1 OR GREATER THAN THE'
'NUMBER OF SPANWISE BOXES (NSPAN) = $ .'
'A $ BULK DATA CARD WITH ID: $ DOES NOT HAVE COMPLETED X-CPU-CPL PAIRS (I.E. IN THREES) .'
'A $ BULK DATA CARD WITH ID: $ HAS A X-LOCATION VALUE GREATER THAN 100 PERCENT CHORD.'
'A $ BULK DATA CARD WITH ID: $ HAS X-LOCATION VALUES THAT ARE NOT IN ASCENDING ORDER.'
'A $ BULK DATA CARD WITH ID: $ HAS CHORDWISE X-VALUES THAT ARE NOT IN ASCENDING ORDER,'
'SPECIFIED IN $ BULK DATA CARD WITH ID: $ .'
'A $ BULK DATA CARD WITH ID: $ HAS CHORDWISE X-VALUES THAT DO NOT START WITH 0.0 OR END WITH 100.0'
'IN $ BULK DATA CARD WITH ID: $ .'
'A $ BULK DATA CARD WITH ID: $ SPECIFIES $ (ITAX) NUMBER OF CHORDWISE HALF THICKNESS VALUES ($), '
'BUT ONLY $ ARE LISTED IN THE CORRESPONDING $ BULK DATA CARD WITH ID: $ .'
'A $ BULK DATA CARD WITH ID: $ SPECIFIES $ (ITAX) NUMBER OF CHORDWISE CAMBER VALUES ($), '
'BUT ONLY $ ARE LISTED IN THE CORRESPONDING $ BULK DATA CARD WITH ID: $ .'
'A $ BULK DATA CARD WITH WID: $ HAS $ NUMBER OF CHORDWISE DIVISIONS (NCHORD) SPECIFIED,'
'BUT ONLY $ VALUES ARE LISTED IN THE CORRESPONDING $ BULK DATA CARD WITH ID: $ .'
'A $ BULK DATA CARD WITH ID: $ REFERENCED BY A $ BULK DATA CARD WITH ID: $ '
'IS NOT DEFINED AS THE CENTERLINE OF THE BODY.'
'A $ WING MACROELEMENT WITH WID: $ HAS ZERO AREA.'
'DUPLICATED ID IN BULK DATA CARD $ WITH ID: $ .'
'ERROR IN BULK DATA ENTRY $ WITH ID: $ . NUMBER OF INLET PANELS EQUALS $ (INLET) .'
'BUT THERE ARE $ NUMBER OF BOX ID SPECIFIED.'
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*MODULE 36      ZONA'S SPLINZ MODULE MESSAGES
'$ ENTRY $ REFERENCES AN AERODYNAMIC BODY COMPONENT. ONLY WING-LIKE COMPONENTS ALLOWED.'
'COORDINATE SYSTEM $, REFERENCED ON $ ENTRY $, CANNOT BE FOUND.'
'GRID POINT $, REFERENCED ON $ ENTRY $, CANNOT BE FOUND.'
'$ ENTRY $ REFERENCES STRUCTURAL SET DEFINITION $ THAT DOES NOT EXIST.'
'THE STRUCTURAL SET DEFINED BY SET2 ENTRY $, REFERENCED ON $ ENTRY $, IS EMPTY.'
'THE STRUCTURAL POINT DEFINITION PRISM DEFINED BY SET2 ENTRY $ ON $ ENTRY $ HAS ILLEGAL GEOMETRY.'
'$ ENTRY $ RESULTS IN A SINGULAR TRANSFORMATION MATRIX.'
'AERODYNAMIC BOX WITH INTERNAL IDENTIFICATION NUMBER $ HAS BEEN SPLINED MORE THAN ONCE.'
'$ ANALYSES ARE REQUESTED IN SOLUTION CONTROL BUT NO SPLINE OR ATTACH ENTRIES EXIST.'
'NO COORDINATE SYSTEM FOR THE SPLINE Y-AXIS IS DEFINED ON $ ENTRY $ .'
'WHEN USED ON A LIFTING SURFACE A CID MUST BE SUPPLIED.'
'$ SETID $ SPECIFIES NON-EXISTENT MACRO-ELEMENT $ .'
'$ SETID $ SPECIFIES NON-EXISTENT AERODYNAMIC BOXES FOR MACRO-ELEMENT $ .'
'THE RECTANGULAR REGION SPECIFIED BY BOX1 AND BOX2 ON $ SETID $ CONTAINS NO AERODYNAMIC BOXES.'
'$ SETID $ SPECIFIES MORE BOXES THAN EXIST IN THE AERODYNAMIC MODEL.'
'$ SETID $ SPECIFIES DUPLICATE AERODYNAMIC BOXES MACROID $, EXTID $ .'

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'\$ SETID \$ SPECIFIES NON-EXISTENT AERODYNAMIC BOX MACROID \$, EXTID \$.'

'COORD SYS \$, REFERENCED ON \$ ENTRY, CANNOT BE FOUND.'

'\$ \$ SPECIFIES A SPLINE PLANE WHICH IS NEARLY PERPENDICULAR TO THE FREE STREAM VELOCITY.'

'\$ SETID \$ SPECIFIES AERODYNAMIC BOXES BELONGING TO MORE THAN ONE MACRO-ELEMENT.'

'\$ SETID \$ FAILS WHEN USING DEFAULT SPLINE PLANE (CP=BLANK) BECAUSE THE BOUNDARY FOR'
' MACRO-ELEMENT \$ DOES NOT DEFINE A PLANE. USE CP OPTION TO SPECIFY A REFERENCE PLANE.'

'SPLINE2 WITH ID: \$ CAN ONLY BE USED WITH CAERO7.'

'AERODYNAMIC GRID WITH INTERNAL ID: \$ CANNOT BE FOUND IN ATTACH BULK DATA ENTRY.'

'STRUCTURAL GRID WITH EXTERNAL ID: \$ CANNOT BE FOUND IN ATTACH BULK DATA ENTRY.'

'SPLINE2 WITH ID: \$ HAS LESS THAN TWO STRUCTURAL GRIDS.'

'\$ WITH ID: \$ ERROR. STRUCTURAL GRID WITH INTERNAL ID: \$ CANNOT BE FOUND.'

'SPLINE2 WITH ID: \$ HAS TWO STRUCTURAL GRIDS WITH ID: \$ AND \$ THAT SHARE THE SAME '
' LOCATION ALONG THE LINE OF THE SPLINE.'

'THE \$ \$ AERODYNAMIC BOX IS NOT ATTACHED TO THE STRUCTURE, THEREFORE, NO DISPLACEMENT'
' IS ASSUMED FOR THIS BOX.'

'AERODYNAMIC GRID WITH INTERNAL ID: \$ CANNOT BE FOUND.'

'SPLINE1 WITH ID: \$ SPECIFIES A SPLINE PLANE WHICH IS NEARLY PERPENDICULAR TO THE FREE'
' STREAM VELOCITY.'

'\$ WITH ID: \$ REFERS TO A SETi THAT HAS LESS THAN \$ GRIDS.'

'\$ WITH ID: \$ REFERS TO A SETi THAT HAS ALL GRIDS ALIGNED ALONG A LINE.'

'\$ WITH ID: \$ REFERS TO A SETi THAT HAS TWO GRIDS AT THE SAME LOCATION.'

'\$ WITH ID: \$ GIVES A SINGULAR MATRIX.'

'A REFERENCED LOCAL COORDINATE SYSTEM WITH ID: \$ CANNOT BE FOUND.'

'SPLINE3 WITH ID: \$ REFERS TO A SETi THAT HAS ALL GRIDS LOCATED ON THE SAME PLANE.'

' THE NORMAL VECTOR OF THE PLANE IS XN = \$, YN = \$, ZN = \$.'

*MODULE 37 ZONA'S ZAEROM MODULE MESSAGES

'\$ WITH ID: \$ HAS DUPLICATED REDUCED FREQUENCIES.'

'THERE IS NO CAERO7 OR BODY7 INPUT FOR THE ZAERO MODULE.'

'THERE IS NO OR MORE THAN ONE \$ INPUT FOR THE ZAERO MODULE STEADY/UNSTEADY AERODYNAMIC ANALYSIS.'

'REFERENCE GRID ID FOR MOMENT CENTER (GREF = \$) REFERENCED IN \$ DOES NOT EXIST.'

'THE CONTROL POINT OF AN AERODYNAMIC BOX WITH ID: \$ LOCATED ON A CAERO7 WING MACROELEMENT'
' WITH WID: \$ ALIGNS WITH THE EDGE OF ANOTHER AERODYNAMIC BOX WITH ID: \$ LOCATED ON A'
' CAERO7 WITH WID: \$.'

'THE CONTROL POINT OF AN AERODYNAMIC BOX WITH INTERNAL ID: \$ LOCATED ON A CAERO7 WITH INTERNAL'
' ID: \$ ALIGNS WITH THE EDGE OF ANOTHER AERODYNAMIC BOX WITH INTERNAL ID: \$ LOCATED ON A'
' CAERO7 WITH INTERNAL ID: \$.'